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## TND6318/D

## On Board Charger (OBC) LLC Converter

## Background

Nowadays, so called plug in hybrid as well as fully electric vehicles are catching more and more attraction triggered by the reduction of pollution as it is normally happening with pure combustion engine. Nevertheless, there is at least one feature that is common to all of them electric energy is accumulated in dedicated battery pack and it is used in electric motors afterwards. Although this technology still undergoes heavy development nowadays, so do also relevant technical standards, it is clear that charging energy is provided utilizing existing mains infrastructure.

Hand in hand, it implies certain requirements put on chargers, those installed On Board as well as on those installed Off Board.

## LLC Converter in OBC Applications

As can be seen also in Figure 1, a typical battery charger application consists of two different stages, AC-DC converter and DC-DC converter. PFC goal is to rectify the input voltage normally provided by a mains, keeping power factor as close as possible to unity. DC-DC converter provides galvanic isolation and the output voltage / current levels as requested by the battery management system. Therefore DC-DC converter is a key block of any OBC system. Number of topologies can be used, however LLC converter is favorite one, among others well known for good efficiency figures and mild EMI fingerprint.

On the other hand, wide output voltage range generally seen in OBC applications may present serious design complications. Board presented in this document has been designed for evaluation of not only, but most of all, new ON Semiconductor Silicon Carbide MOSFET NVHL080N120SC1 (N-Channel, $1200 \mathrm{~V}, 80 \mathrm{~m} \Omega$, TO247-3L, suggested to be used with dedicated ON Semiconductor SiC MOSFET driver NCP51705), in OBC like application.

## Key Features

- Input Voltage $700 \pm 35 \mathrm{~V}$
- Output Voltage 200 / 450 V
- Output Current 0 / 40 A
- Maximum Output Power 10 kW
- Maximum Switching Frequency 400 kHz
- Microcontroller Control with USB and CAN Bus Interface
- Liquid Cooling
- Board Size without Resonant Tank Board $360 \times 187 \times 92 \mathrm{~mm}$

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OBC LLC Board Setup Picture


Figure 1. Typical Structure of OBC System


Figure 2. OBC LLC Block Diagram

## Concept Overview

Overall concept is shown in block diagram above (Figure 2). Since higher priorities have been put on testability, flexibility, modularity and reusability than to overall test setup dimensions, presented concept is definitely not aiming for highest power densities and compactness.

One can even notice that whole OBC LLC converter evaluation set up has been split into two separate boards. One board, called OBC LLC switch board, containing all active components and next board, called resonant tank board, containing LLC converter resonant members resonant inductor, resonant capacitor, transformer(s). Although it could be found as a suboptimal solution from various perspectives at first glance, there is one major advantage of this approach - virtually any resonant tank solution can be tested and compared to another one, without a need to change anything on switch board. This can be very helpful, especially for OBC like applications, where wide range of output voltages makes resonant tank design more complex. Furthermore, with certain small modifications also other converter topologies, full bridge phase shifted converter for example, could be tested as well.

## Power Stage

Target output power level at around 10 kW and LLC topology indicates that full bridge power stage is the preferred option for power stage. As already mentioned before, original intention was to support SiC MOSFETs application evaluation. Naturally, it implies certain requirements for MOSFETs driving circuitry, in this board addressed by NCP51705 driver.

From concept point of view, modularity approach has been followed again - every transistor has its driver installed on own small so called driver mini-board. Consequently, also different driver solutions can be eventually tested. Although NCP51705 driver contains also charge pump circuitry to generate negative supply voltage for SiC gate driver part, it is turned off on this board in its default state.

Driver power supply ( +20 V and -4.4 V ) is provided by external small, low coupling capacitance DC-DC converter, which may be advantageous in case also different power stage configurations are about to be tested. It means that application compare among regular, super junction MOSFET and even IGBT devices is feasible, while still using the same setup.

It is important to mention that insulation barrier between primary and secondary side at MOSFET drivers level is provided by a digital insulator, located on driver mini board.

Although targeted input voltage is $700 \pm 35 \mathrm{~V}$, in principle, also different voltage levels can be tested. Maximum applicable input voltage is basically limited by two 450 V rated electrolytic capacitors connected in series at the power stage input, by 900 V Ceralinks capacitors installed across both half bridges and of course transistors installed in power stage and housekeeping converter. Minimum input voltage level housekeeping converter still operates is around 390 V .

## Secondary Side Rectification

Full bridge has been selected for output voltage rectification, even if synchronous rectification is one of the main measures for efficiency improvements. Relatively high output voltage makes synchronous rectification more complicated and costly. Real OBC applications typically obey rule of simplicity therefore appropriate, sometimes also SiC diodes are utilized. Presented board uses four FFSH3065A diodes, but selected mechanical concept provides very convenient access to them, as well as to all power transistors, so they can be changed quite easily and quickly to any other type.

## Thermal Management

Selected liquid cooling not only simplifies power components thermal management, but also provides an option to have power components temperature under tighter control. Consequent results compare of different configurations is sometimes more objective and more appropriate. On the other hand, classic air cooling, seen almost exclusively in all Off Board charging solutions may work under slightly different conditions in reality. Cold plate actual temperature can be measured via I2C temperature sensor mounted on it, however no special measurement accuracy has been considered. Intended usage covers debugging purposes and eventual additional safety measures implemented in controller firmware, if needed.
As can be observed in block diagram, there is also fan control interface, providing thus a possibility to use standard transformer and inductor solutions on resonant tank board. These components very often require forced airflow to operate safely.

## Input \& Output Voltage, Output Current Sensing

Naturally, information about actual output voltage and output current is crucial for regulation purposes. Keeping simplicity in mind, output voltage sensing is provided by simple resistive divider which output is buffered by NCS333 amplifier and input to control board. Similarly, output current is sensed at negative DC output line as a voltage drop over $300 \mu \Omega$ shunt, amplified by special current sensing amplifier NCS210.
Since controller board sits on secondary side, primary side input voltage information has to be insulated in reasonable way. Simple voltage to current converter at primary side is driving optocoupler, which output current is converted back to voltage, which can be measured directly by controller board. Of course, price paid for this simple approach is certain non-linearity and limited input voltage measurable range, but it has been considered as a sufficient solution. Note, that input voltage information is not necessarily needed for output voltage and current regulation, in case simple algorithms are being considered. Actual board firmware uses input voltage information for protection purposes only.

## Housekeeping DC-DC Converter

Implemented two switch fly-back converter controlled by NCP1252 controller provides insulated 15 V at its output, up to 30 W maximum. This voltage is used as a main power source for all low voltage circuitry at the secondary side MOSFET drivers, controller board as well as eventual fan installed on resonant tank board. Housekeeping DC-DC converter can be easily disconnected from input voltage. In that case external 15 V power supply can be connected over dedicated connector to operate the board.

Brown out protection gets activated below 390 V (can be lowered if needed), maximum input voltage tested is about 830 V . For higher input voltages selected MOSFETs as well as capacitors at input LC filter have to be checked.

## Communication Interfaces

Two interfaces are present on board - USB and CAN bus interface. CAN bus interface is typically preferred in OBC applications, but because of potential software complexity related to it and standard variations no control over CAN interface has been implemented in current firmware version, since this board is not targeted to verify CAN bus protocols related to OBC. A python based application is currently available to interact with the switch board/micro-controller board. It communicates over USB. Also firmware flashing takes place over the same interface.

## Resonant Tank Design

Generally speaking, selection of resonant tank members is the key factor to achieve the specified operating conditions for the LLC converter. To determine passive components values, so called First Harmonic

Approximation (FHA) method has been applied. In fact, real experience shows that it is very valuable while still quite simple and straightforward method to evaluate regular LLC designs. Accuracy of estimations based on this method is more than fair for typical fixed output voltage LLC converters with relatively narrow input voltage ranges. Important point is that resonant tank is designed to operate ideally at its main resonance frequency (or very close to it) while exhibiting all its advantages, like efficient operation and quite mild EMI fingerprint by nature.
Unfortunately, such operating conditions are rarely present in OBC applications, since battery pack voltage varies quite substantially over battery state of charge space. Common situation example is depicted in Figure 3. It can be seen that fully depleted battery pack voltage can be as low as 220 V . On the other side, fully charged battery pack voltage of 410 V or higher can be expected. Of course, voltage range 220 / 410 V may not be taken as something generally valid, while these numbers are changing among others with battery pack temperature slightly. They are also affected by selected battery technology.
Nevertheless, it is apparent, that OBC output voltage can vary easily by factor 2 or more, which is huge difference compared to 10 / $15 \%$ variation typical LLC converter has to usually face to. Number of publications dedicated to this problem and its impact to proper LLC resonant tank design are available in literature, various approaches can be selected, unfortunately, every approach comes hand in hand with certain compromise and probably no universally applicable cook book can be given.


Figure 3. Charging Profile Example for 410 V Li-Ion Based Battery Pack

The problem with FHA analysis can be identified in its name already - first harmonic analysis. As already mentioned above, typical LLC converter with narrow input to output voltage ratio range operates in close vicinity of so called main resonance point, where current waveforms are not very distorted from their ideal sinusoidal shape. Even if frequency excursion range in OBC LLC converters could be reduced up to a certain degree with adequate resonant components, it is almost sure that converter's operating frequency will be shifted relatively far from main resonance point. This happens especially for maximum input voltage with minimum output voltage and minimum load current, or vice versa, for minimum input voltage with maximum output voltage and maximum load current. It results in by far non-sinusoidal current waveforms that FHA is not considering. Unfortunately, no other, comparably simple method exists, so one has to be aware of operating point calculation errors while applying this method for distant operating points.

A practical approach used for the LLC passive calculation is summarized in [1] and it has been used as a reference for this application:

## - Select Transformer Primary to Secondary Turns' Ratio

Number of different approaches can be taken when considering optimal transformer turns ratio. Efficiency aspect may dictate to select turns ratio in a way that LLC converter operates at its optimum operating point (e.g. typically main resonant point) as long as possible. Especially in OBC applications, this is where the information about intended battery pack charging profile is very useful. Looking back in example profile above, it can be found, that maximum constant power or maximum constant current delivery can be expected in output voltage range from about 290 V up to 410 V . Selecting middle point of this range gives out 350 V . Considering nominal input voltage of 700 V implies a transformer turns ratio of 2 .

$$
\mathrm{N}=\frac{\mathrm{U}_{\mathrm{IN}, \text { nominal }}}{\mathrm{U}_{\mathrm{OUT}, \text { middle }}}
$$

## - Calculating Minimum Converter Gain

The minimum converter gain is typically given by the ratio between the minimum output voltage and the maximum input voltage, however in an OBC application it would result in a very high switching frequency (several times the main resonant frequency). This is very often not practically possible if considering light load conditions. Therefore the usage of some kind of skip mode functionality is unavoidable. Thus, instead of minimum output voltage, a reasonable skip mode entry output voltage has to be selected for minimum converter gain calculation. Such selection can be driven by the minimum output voltage achieved under full load conditions are applied. This narrows output voltage range, however, entering skip mode operation below this output voltage is automatically connected with increased
charging current ripple. It is usually acceptable, but it has to be checked in particular cases.

$$
\mathrm{M}_{\min }=\frac{\mathrm{N} \times \mathrm{U}_{\mathrm{OUT}, \text { skip entry }}}{\mathrm{U}_{\mathrm{IN}, \max }}
$$

Just for illustration, with minimum output voltage of 220 V , maximum input voltage of 735 V , transformer turns ratio 2 and skip mode entry voltage of 292.5 V required minimum converter gain is 0.796 .

## - $L_{R}$ to $L_{M}$ Ratio Selection

$L_{R}$ to $L_{M}$ ratio is one of the critical parameters of every LLC converter. Among others its selection has direct impact on converter frequency characteristics, e.g. also on frequency excursion needed to cover required converter gain range. In theory, reducing $\mathrm{L}_{\mathrm{M}}$ can eventually lead to smaller transformer footprint, but hand in hand it increases circulating current in the resonant tank, implying higher stress to the windings and magnetic circuit of magnetic components. Typical $L_{R}$ to $L_{M}$ ratio seen in LLC converters is somewhere from 1:3 to $1: 7$. It is also not very different in OBC LLC converters, although lower ratios are more likely to be selected.

Here, such value is calculated considering the ratio between maximum switching frequency (minimum converter gain) and nominal resonant frequency (converter gain 1). Following equation can be used:

$$
\mathrm{I}=\frac{\mathrm{L}_{\mathrm{R}}}{\mathrm{~L}_{\mathrm{M}}}=\left(\frac{1}{\mathrm{M}_{\min }}-1\right) \times \frac{8 \times \mathrm{f}_{n, \max }^{2}}{8 \times \mathrm{f}_{n, \max }^{2}-\pi^{2}}
$$

where $f_{n, \max }$ is the normalized maximum switching frequency - ratio of maximum switching frequency, applied just at skip mode entry output voltage and maximum input voltage, to nominal resonant frequency:

$$
f_{n, \max }=\frac{f_{\max }}{f_{r}}
$$

Both, $f_{r}$ and $f_{\text {max }}$ have to be selected as a design requirements. Typical LLC converters normally go with $\mathrm{f}_{\mathrm{n}, \max }$ within the range $1.5 / 2.5$. Because of Silicon Carbide MOSFET, maximum switching frequency of 400 kHz has been selected, even if the SiC MOSFET gate driver NCP51705 is capable of maximum switching frequency of 500 kHz . In order to mitigate switching losses resonant frequency of 108 kHz has been considered. With given frequency parameters and already calculated minimum converter gain $\left(\mathrm{M}_{\text {min }}\right)$, the resulting $\mathrm{L}_{\mathrm{R}}$ to $\mathrm{L}_{\mathrm{M}}$ ratio is 0.282 (1:3.549).

## - Calculate Critical Operating Point

LLC converter should always operates at zero voltage switching (ZVS) mode. Such condition is guaranteed when the actual switching frequency is located in the inductive impedance nature of the resonant tank. The critical operating point is defined as a crossover point between the capacitive and the inductive impedance of the tank. The
critical operating point can be analytically determined with the following two equations. The first represents the critical converter gain, $\mathrm{M}_{\text {crit }}$, and the later represents the critical impedance, $\mathrm{Z}_{\text {crit }}$ :

$$
\begin{gathered}
M_{\text {crit }}=\sqrt{1+\sqrt{\frac{I}{1+I}}} \\
Z_{\text {crit }}=\frac{8}{\pi^{2}} \frac{\mathrm{U}_{\mathrm{IN}, \min }^{2}}{\mathrm{P}_{\mathrm{OUT}, \max }}(\sqrt{I \times(1+I)+1)}
\end{gathered}
$$

According design parameters mentioned in previous paragraphs, it leads to a $\mathrm{M}_{\text {crit }}$ of 1.212 and a $\mathrm{Z}_{\text {crit }}$ of $31.6 \Omega$. Additionally, output voltage, output current and input current can be calculated for this critical condition:

$$
\begin{aligned}
\mathrm{U}_{\mathrm{OUT}, \text { crit }} & =\frac{\mathrm{U}_{\mathrm{IN}, \text { min }} \times \mathrm{M}_{\text {crit }}}{\mathrm{N}} \\
\mathrm{I}_{\mathrm{OUT}, \text { crit }} & =\frac{\mathrm{P}_{\mathrm{OUT}, \text { max }}}{\mathrm{U}_{\mathrm{OUT}, \text { crit }}} \\
\mathrm{I}_{\mathrm{IN}, \text { crit }} & =\frac{\mathrm{P}_{\mathrm{OUT}, \text { max }}}{\eta \times \mathrm{U}_{\mathrm{IN}, \text { min }}}
\end{aligned}
$$

where $\eta$ is estimated converter efficiency at critical operating point. Even though exact efficiency value is not known at this point yet, rough estimated value is usually fair enough to use. Just for completeness for considered design example, calculated $U_{\text {OUT,crit }}$ is 403 V , IOUT,crit is 24.8 A and $\mathrm{I}_{\text {IN, crit }}$ is 15.7 A , when considering 10 kW output power, 665 V minimum input voltage and $96 \%$ efficiency.

## - Calculate Required Minimum $L_{M}$ for ZVS Operation at Critical Operating Point

Once all parameters for critical operating point are known, following equation can be used to calculate minimum magnetizing inductance Lm value needed so that converter still operates in ZVS mode at this critical point.

$$
\mathrm{L}_{\mathrm{M}}=\frac{\mathrm{N}^{2}}{\mathrm{f}_{\mathrm{r}}} \frac{\mathrm{U}_{\mathrm{OUT} / \text { crit }}}{4 \mathrm{NI}_{\mathrm{IN}_{\mathrm{crit}}}+\left(\mathrm{pi}^{2} \times \mathrm{I} \times \mathrm{M}_{\text {crit }}-4\right) \mathrm{I}_{\mathrm{OUT}, \text { crit }}}
$$

## - Calculate Maximum $L_{M}$ for ZVS Operation at

 MaximumThere is one additional condition which needs certain attention - as selected previously, switching frequency during very light load or no load condition is clamped at given maximum $f_{\text {max }}$. The problem is that at no load condition only circulating resonant tank current takes care about zero voltage switching. It is only current charging and discharging switch nodes parasitic capacitances. Once this current gets naturally reduced by high frequency operation compared to operation at resonant frequency (there is not enough time available for relevant current increase in
magnetizing inductance) selected commutation time (e.g. dead time) may become too short and MOSFET switches are turned on before their body diode starts to conduct. Following equation can be used to calculated maximum magnetizing inductance $\mathrm{L}_{\mathrm{M}}$ providing ZVS operation:

$$
\mathrm{L}_{\mathrm{M}, \max }=\frac{\text { dead time }}{8 \pi f_{r} \mathrm{C}_{o s s}} \sqrt{\left(1+\frac{1}{l}\right) \mathrm{M}_{\min }^{2}-\frac{1}{1(1+l)}}
$$

where $\mathrm{C}_{\text {oss }}$ is one MOSFET junction capacitance. Using 80 pF and 100 ns dead time for design example above maximum acceptable magnetizing inductance is $154.7 \mu \mathrm{H}$. In case value calculated in this point is lower than value calculated in previous point some of design inputs needs to be changed and whole calculation reiterated. Usually, manipulating $f_{n, \text { max }}\left(f_{r}\right.$ or $\left.f_{\text {max }}\right)$ or increasing dead time does the trick. In case control circuitry allows it, dead time can also be manipulated across operating space, using reasonable short dead time during normal operation and increasing it once approaching light load or no load condition.

## - Calculate $L_{R}$ and $C_{R}$, Verify $Z_{o}$

Last, but not least step is to calculate own resonant inductor and resonant capacitor values. Since 1 value has been already calculated $\mathrm{L}_{\mathrm{R}}$ is very easy to calculate as well

$$
L_{R}=I \times L_{M}
$$

Similarly, main resonant frequency $\mathrm{fr}_{\mathrm{r}}$ has been given as a design input parameter, calculation of $\mathrm{C}_{\mathrm{R}}$ is straightforward

$$
C_{R}=\frac{1}{L_{R} \times\left(2 \pi f_{r}\right)^{2}}
$$

Finally, characteristic resonant tank impedance has to be calculated

$$
Z_{0}=\sqrt{\frac{L_{R}}{C_{R}}}
$$

The resulting characteristic impedance values has to be lower than $\mathrm{Z}_{\text {crit }}$ value calculated previously. If not, reducing $\mathrm{f}_{\mathrm{n} \text {, max }}$ (increasing main resonant frequency or reducing maximum switching frequency) usually solves situation. Calculation for considered design example leads to $\mathrm{Lr}_{\mathrm{r}}$ inductance $38.3 \mu \mathrm{H}$, Cr capacitance 56.6 nF and $\mathrm{Z}_{0}$ impedance $26 \Omega$, which is less than $\mathrm{Z}_{\text {crit }} 31.6 \Omega$, therefore proposed resonant tank will operate safely in ZVS also during constant maximum power operation.
Although the previous paragraph introduces a numeric approach to calculate the tank parameters, a SPICE simulation analysis is added in Figure 4 for completeness.
Just for illustration, SIMetrix simple FHA model used for design example in this document and its outputs are presented briefly in next Figures (5 to 9).

***************************************************************************************

* transformer parameters
*turn ratio - primary to secondary
.PARAM N 2
* primary magnetizing inductance
.PARAM Lm 136.1 u
* prinary winding resistance
.PARAM R_pri 33 m
* primary stray inductance
.PARAM Ls_pri 1 p
* secondary inductance
.PARAM Lsec $\left\{L \mathrm{~m} /\left(\mathrm{N}^{\wedge} 2\right)\right\}$
* coupling to primary $=1 \rightarrow$ ideal transformer, stray inductance are modeled
as a separate elements

K1 Lpri Lsec 1

* secondary winding resistance
.PARAM R_sec 13 m
* secondary stray inductance
.PARAM Ls_sec 1p
* resonance inductor
.PARAM Lr 38.3u
.PARAM R_Lr 11m
* resonance capacitor

PARAM Cr 56.6n
PARAM R_Cr $2 m$

Figure 4. Simple SPICE Simulation Model Example for AC Analysis

Output voltage (Lm $136.1 \mu \mathrm{H}, \operatorname{Lr} 38.3 \mu \mathrm{H}, \mathrm{Cr} 56.6 \mathrm{nF}, \mathrm{N} 2)$


Frequency / Hertz

Figure 5. FHA Results - Output Voltage

Primary current amplitude and phase (Lm 136.1uH, Lr 38.3uH, Cr 56.6nF, N 2:1)



Figure 6. FHA Results - Primary Current

Transformer primary voltage (Lm 136.1uH, Lr 38.3uH, Cr 56.6nF, N 2:1)


Figure 7. FHA Results - Transformer Primary Voltage


Figure 8. FHA Results - Resonant Capacitor Voltage


LLC working area search
Processing sweep for $665 \mathrm{~V} / 450 \mathrm{~V} / 10 \mathrm{~kW}=>548 \mathrm{~V}$ peak found at 56.62 kHz Nominal switching frequency: 73.04 kHz , current phase: -20.06 ${ }^{\circ}$

Processing sweep for $700 \mathrm{~V} / 220 \mathrm{~V} / 1 \mathrm{~W}=>139.1 \mathrm{kV}$ peak found at 50.7 kHz ERROR: Target voltage not reachable - max Fsw 400 kHz reached !!! Lowest reachable voltage is 277.6 V

Processing sweep for $700 \mathrm{~V} / 250 \mathrm{~V} / 10 \mathrm{~kW}=>358.3 \mathrm{~V}$ peak found at 98.17 kHz Nominal switching frequency: 147.9 kHz , current phase: $-43.85^{\circ}$

Processing sweep for $700 \mathrm{~V} / 350 \mathrm{~V} / 1 \mathrm{~W}=>144 \mathrm{kV}$ peak found at 50.7 kHz Nominal switching frequency: 108.1 kHz , current phase: $-89.96^{\circ}$

Processing sweep for $700 \mathrm{~V} / 350 \mathrm{~V} / 10 \mathrm{~kW}=>412.3 \mathrm{~V}$ peak found at 70.63 kHz Nominal switching frequency: 107.6 kHz , current phase: - $21.62^{\circ}$

Processing sweep for $700 \mathrm{~V} / 450 \mathrm{~V} / 1 \mathrm{~W}=>145.2 \mathrm{kV}$ peak found at 50.7 kHz Nominal switching frequency: 80.8 kHz , current phase: $-89.94^{\circ}$ *****************************************************************************************
Processing sweep for $700 \mathrm{~V} / 450 \mathrm{~V} / 1 \mathrm{~kW}=>5.225 \mathrm{kV}$ peak found at 50.7 kHz Nominal switching frequency: 80.76 kHz , current phase: $-82.2^{\circ}$

*Processing sweep for $700 \mathrm{~V} / 450 \mathrm{~V} / 6.6 \mathrm{~kW}=>831.2 \mathrm{~V}$ peak found at 53.09 kHz Nominal switching frequency: 79.35 kHz , current phase: $-43.23^{\circ}$

Processing sweep for $700 \mathrm{~V} / 450 \mathrm{~V} / 10 \mathrm{~kW}=>576.8 \mathrm{~V}$ peak found at 56.62 kHz Nominal switching frequency: 76.96 kHz , current phase: - $23.66^{\circ}$ *************************************************************************************
Processing sweep for $735 \mathrm{~V} / 220 \mathrm{~V} / 1 \mathrm{~W}=>146.1 \mathrm{kV}$ peak found at 50.7 kHz ERROR: Target voltage not reachable - max Fsw 400 kHz reached !!! Lowest reachable voltage is 291.5 V
$\qquad$ 5 errors found ...
$\qquad$

Processing sweep for $700 \mathrm{~V} / 220 \mathrm{~V} / 1 \mathrm{~kW}=>1.28 \mathrm{kV}$ peak found at 51.64 kHz ERROR: Target voltage not reachable - max Fsw 400 kHz reached !!! Lowest reachable voltage is 252.9 V

Processing sweep for $700 \mathrm{~V} / 220 \mathrm{~V} / 6.6 \mathrm{~kW}=>363.3 \mathrm{~V}$ peak found at 93.97 kHz Nominal switching frequency: 173.3 kHz , current phase: $-50.53^{\circ}$

Processing sweep for $700 \mathrm{~V} / 220 \mathrm{~V} / 10 \mathrm{~kW}=>353.4 \mathrm{~V}$ peak found at 102.3 kHz
Nominal switching frequency: 150.1 kHz
Maximum current phase: -50.15 deg
Processing sweep for $700 \mathrm{~V} / 250 \mathrm{~V} / 1 \mathrm{~W}=>141 \mathrm{kV}$ peak found at 50.7 kHz ERROR: Target voltage not reachable - max Fsw 400 kHz reached !!! Lowest reachable voltage is 277.6 V

Processing sweep for $700 \mathrm{~V} / 250 \mathrm{~V} / 1 \mathrm{~kW}=>1.643 \mathrm{kV}$ peak found at 51.17 kHz ERROR: Target voltage not reachable - max Fsw 400 kHz reached !!! Lowest reachable voltage is 262 V
***

Figure 9. FHA Results - Resonant Inductor Voltage

With the FHA results, it is possible to define basic electrical parameters of resonant tank components. As further comment to the primary current chart shown earlier, a peak value greater than 22 A is expected when working with an input voltage of 700 V . However this peak current does not necessary represent the switching current, which is going to be different and useful to determine the switching losses of the switching devices. In case of lower input voltage operation, a higher peak current is expected as depicted in the next table.

Note, that transformer has been split into two smaller components: their primary windings are connected in series and secondary windings in parallel.

On top of it, usage of transformer leakage inductance as resonant inductor, often used in few hundreds watts solutions, is usually not feasible in $\sim 10 \mathrm{~kW}$ converters. Most of all, from efficiency point of view, but also from EMI perspective, it is good to minimize stray fluxes around
transformer. Furthermore, regular magnetic component manufacturer specifies only maximum value of leakage inductance, because from production line point of view precise control of leakage inductance may be quite tremendous task requiring extra effort. It naturally results in usage of an external inductor, as a separate component acting as the resonant inductor. Sometimes also this one can be split into two components, providing certain benefits.
Nevertheless, it is definitely worthwhile to build also simulation model for transient simulations, ideally with real simulation models of transistors, rectifier diodes and all resonant tank members. It allows designer to investigate real operating conditions and verify design margins, especially when operating points distant from main resonant point are subject of interest. As an example, expected operating points have been summarized in below Figure 10 for discussed example design.

|  | OBC LLC 10kW simulations, load 10 kW , tank proposal: Lm $136.1 \mu \mathrm{H}, \mathrm{Lr} 38.3 \mu \mathrm{H}, \mathrm{Cr} 56.6 \mathrm{nF}, \mathrm{N} 2$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Input voltage [V] <br> 665 |  |  |  |  | Input voltage $\mathrm{VV]}$ <br> 700 |  |  |  |  | Input voltage [V] <br> 735 |  |  |  |  |
|  | Output voltage [V] |  |  |  |  | Output voltage [V] |  |  |  |  | Output voltage [V] |  |  |  |  |
|  | 250 | 300 | 350 | 400 | 450 | 250 | 300 | 350 | 400 | 450 | 250 | 300 | 350 | 400 | 450 |
| Switching frequency [ kHz$]$ | 134.832 | 120.517 | 98.476 | 85.453 | 78.067 | 140.000 | 127.080 | 105.528 | 90.032 | 81.159 | 144.828 | 133.333 | 113.976 | 95.022 | 84.507 |
| Primary current [ $\left.A_{\text {peaxa }}\right]$ | 31.5 | 26.3 | 26.7 | 27.7 | 28.1 | 31.9 | 26.5 | 25.6 | 26.3 | 25.1 | 32.3 | 26.6 | 23.9 | 25.6 | 25.4 |
| Primary current [ $A_{\text {enss }}$ ] | 22.9 | 19.1 | 18.4 | 18.4 | 18.9 | 22.8 | 19.3 | 18.1 | 17.9 | 17.7 | 23.0 | 19.4 | 17.2 | 17.7 | 17.6 |
| Transformer primary voltage [V $\mathrm{peaxk}^{\text {c }}$ ] | 513.1 | 611.2 | 712.0 | 813.0 | 912.9 | 512.4 | 611.1 | 711.3 | 811.6 | 911.1 | 512.7 | 611.3 | 710.9 | 812.1 | 912.0 |
| Transformer primary current [A peakl | 31.5 | 26.3 | 26.7 | 27.7 | 28.1 | 31.9 | 26.5 | 25.6 | 26.3 | 25.1 | 32.3 | 26.6 | 23.9 | 25.6 | 25.4 |
| Transformer magnetizing current [A peax] | 9.9 | 9.2 | 11.9 | 13.7 | 16.3 | 6.7 | 8.7 | 12.2 | 14.0 | 16.2 | 6.4 | 8.3 | 11.4 | 14.2 | 16.2 |
| Transformer primary winding resistance [m $\Omega$ [ | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 | 33.0 |
| Transformer primary winding power loss [W ] | 17.3 | 12.1 | 11.2 | 11.2 | 11.8 | 17.2 | 12.3 | 10.8 | 10.5 | 10.4 | 17.4 | 12.4 | 9.8 | 10.3 | 10.2 |
| Transformer secondary voltage [V peax] | 255.5 | 304.7 | 355.1 | 405.5 | 455.6 | 255.1 | 304.7 | 354.8 | 404.9 | 454.7 | 255.2 | 304.8 | 354.7 | 405.2 | 455.2 |
| Transformer secondary current [A peax] | 66.0 | 48.6 | 49.8 | 49.8 | 49.9 | 59.4 | 48.3 | 46.7 | 47.7 | 45.2 | 60.0 | 48.2 | 43.3 | 45.5 | 45.1 |
| Transformer secondary current [ $\mathrm{A}_{\text {Rens }}$ ] | 44.1 | 35.8 | 33.4 | 31.3 | 29.6 | 43.9 | 36.0 | 32.2 | 30.5 | 27.2 | 44.2 | 36.2 | 31.2 | 29.8 | 27.9 |
| Transformer secondary winding resistance [m $\mathrm{m}^{\text {[ }}$ | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 |
| Transformer secondary winding power loss [W ] | 19.4 | 12.8 | 11.2 | 9.8 | 8.8 | 19.3 | 13.0 | 10.4 | 9.3 | 7.4 | 19.5 | 13.1 | 9.7 | 8.9 | 7.8 |
| Resonant capacitor voltage [V peax] | 669.1 | 631.9 | 744.4 | 868.5 | 994.6 | 646.9 | 602.3 | 684.2 | 798.6 | 884.3 | 624.5 | 573.3 | 600.6 | 748.4 | 852.1 |
| Resonant capacitor ESR [m $\mathrm{\Omega}$ ] | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 |
| Resonant capacitor power loss [W] | 5.3 | 3.7 | 3.4 | 3.4 | 3.6 | 5.2 | 3.7 | 3.3 | 3.2 | 3.1 | 5.3 | 3.7 | 3.0 | 3.1 | 3.1 |
| Resonant inductor voltage [V peax] | 1812.7 | 1862.2 | 1723.1 | 1853.1 | 998.7 | 1823.4 | 1844.5 | 842.0 | 1845.0 | 1555.5 | 1838.8 | 1877.5 | 1986.8 | 964.6 | 1573.3 |
| Resonant inductor ESR ]m@[ | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 | 10.0 |
| Resonant inductor power loss [W] | 5.3 | 3.7 | 3.4 | 3.4 | 3.6 | 5.2 | 3.7 | 3.3 | 3.2 | 3.1 | 5.3 | 3.7 | 3.0 | 3.1 | 3.1 |
| Single transistor average power loss [ $W$ ] | 25.5 | 15.8 | 14.0 | 14.1 | 14.9 | 26.6 | 16.9 | 13.5 | 13.4 | 12.7 | 27.9 | 17.7 | 12.4 | 13.1 | 13.0 |
| All transistors losses [ W ] | 102.2 | 63.4 | 56.2 | 56.2 | 59.5 | 106.6 | 67.7 | 54.2 | 53.4 | 50.8 | 111.4 | 70.9 | 49.5 | 52.4 | 51.9 |
| Output current [ A ] | 40.0 | 33.3 | 28.6 | 25.0 | 22.2 | 40.0 | 33.3 | 28.6 | 25.0 | 22.2 | 40.0 | 33.3 | 28.6 | 25.0 | 22.2 |
| Single rectifier diode average power loss [W] | 34.5 | 26.1 | 23.1 | 19.8 | 17.7 | 34.5 | 26.4 | 22.3 | 19.4 | 15.8 | 34.7 | 26.5 | 21.6 | 19.4 | 16.9 |
| Rectifier overall power loss [W] | 138.0 | 104.3 | 92.2 | 79.4 | 70.6 | 138.1 | 105.8 | 89.1 | 77.7 | 63.3 | 138.6 | 106.0 | 86.3 | 77.7 | 67.8 |
| Input capacitor ripple current [A mns] | 7.1 | 3.3 | 2.1 | 2.5 | 3.3 | 7.9 | 4.3 | 2.8 | 2.8 | 3.5 | 8.7 | 5.1 | 2.5 | 3.4 | 3.6 |
| Input capacitor ESR ]m@[ | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 | 93.0 |
| Input capacitor power loss [W] | 4.7 | 1.0 | 0.4 | 0.6 | 1.0 | 5.8 | 1.7 | 0.7 | 0.8 | 1.1 | 7.1 | 2.4 | 0.6 | 1.0 | 1.2 |
| Output capacitor ripple current [ $\mathrm{A}_{\text {Ress }}$ ] | 17.4 | 13.6 | 17.1 | 18.8 | 19.1 | 17.7 | 13.6 | 14.9 | 17.4 | 16.9 | 18.1 | 13.8 | 12.4 | 16.1 | 16.8 |
| Output capacitor ESR ]m@[ | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 | 80.0 |
| Output capacitor power loss [W] | 24.3 | 14.8 | 23.3 | 28.2 | 29.2 | 25.2 | 14.8 | 17.9 | 24.1 | 22.8 | 26.3 | 15.2 | 12.3 | 20.6 | 22.5 |
| Input power - simulated [ $W$ ] | 10317.2 | 10238.3 | 10193.7 | 10192.4 | 10186.9 | 10324.3 | 10223.9 | 10187.7 | 10163.4 | 10153.5 | 10331.3 | 10240.4 | 10185.3 | 10186.1 | 10168.9 |
| Output power - simulated [W] | 9998.5 | 10016.2 | 9993.8 | 9990.5 | 9995.3 | 9998.2 | 9998.5 | 9997.0 | 9980.1 | 9974.6 | 9998.4 | 10009.5 | 10009.6 | 10007.3 | 9995.5 |
| Power losses - simulated [W] | 318.7 | 222.1 | 199.9 | 201.9 | 191.6 | 326.1 | 225.4 | 190.7 | 183.3 | 178.9 | 332.9 | 230.9 | 175.7 | 178.8 | 173.4 |
| Power losses - summed by components above [W] | 316.3 | 214.6 | 200.8 | 191.6 | 187.1 | 316.8 | 220.9 | 188.8 | 181.5 | 161.0 | 323.9 | 225.0 | 173.5 | 176.1 | 166.4 |
| Transformer primary winding power loss ratio [\%] | 5.5 | 5.6 | 5.6 | 5.8 | 6.3 | 5.4 | 5.6 | 5.7 | 5.8 | 6.5 | 5.4 | 5.5 | 5.6 | 5.9 | 6.1 |
| Transformer secondary winding power loss ratio [\%] | 6.1 | 6.0 | 5.6 | 5.1 | 4.7 | 6.1 | 5.9 | 5.5 | 5.1 | 4.6 | 6.0 | 5.8 | 5.6 | 5.0 | 4.7 |
| Transformer overall power loss ratio [\%] | 11.6 | 11.6 | 11.1 | 11.0 | 11.0 | 11.5 | 11.4 | 11.2 | 10.9 | 11.1 | 11.4 | 11.3 | 11.2 | 10.9 | 10.8 |
| Resonant capacitor power loss ratio [\%] | 1.7 | 1.7 | 1.7 | 1.8 | 1.9 | 1.6 | 1.7 | 1.7 | 1.8 | 2.0 | 1.6 | 1.7 | 1.7 | 1.8 | 1.9 |
| Resonant inductor power loss ratio [\%] | 1.7 | 1.7 | 1.7 | 1.8 | 1.9 | 1.6 | 1.7 | 1.7 | 1.8 | 2.0 | 1.6 | 1.7 | 1.7 | 1.8 | 1.9 |
| Transistors power loss ratio [\%] | 32.3 | 29.5 | 28.0 | 29.4 | 31.8 | 33.6 | 30.6 | 28.7 | 29.4 | 31.5 | 34.4 | 31.5 | 28.5 | 29.7 | 31.2 |
| Rectifier power loss ratio [\%] | 43.6 | 48.6 | 45.9 | 41.4 | 37.7 | 43.6 | 47.9 | 47.2 | 42.8 | 39.3 | 42.8 | 47.1 | 49.8 | 44.1 | 40.7 |
| Output capacitor power loss ratio [\%] | 7.7 | 6.9 | 11.6 | 14.7 | 15.6 | 7.9 | 6.7 | 9.5 | 13.3 | 14.1 | 8.1 | 6.7 | 7.1 | 11.7 | 13.5 |
| Efficiency - simulated [\%] | 96.91 | 97.83 | 98.04 | 98.02 | 98.12 | 96.84 | 97.80 | 98.13 | 98.20 | 98.24 | 96.78 | 97.74 | 98.28 | 98.25 | 98.29 |

Figure 10. Summary Example of Transient Simulations with Real Device Models

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Figure 11. Transformer Selected for Resonant Tank in Design Example


Figure 12. Resonant Inductor Selected in Design Example

## Design Simulations

As already mentioned in previous chapters, reasonable simulation became very valuable and valid step within design of almost any power converter recently. Its relevance probably does not need any special dispute anymore. Despite of its general acceptance, level of simulation model abstraction is always in question. The more detailed, closer to the reality the model is, the lower error between simulation results and reality will be, however, too detailed model can result in heavy simulations, which could result in impractical usage. Moreover, usage of digital control (DSP, microcontroller. FPGA) in converters is becoming more and more standard approach, thus it is suggested to include the digital behavior in the model in order to guarantee simulation results closer to the reality. However the introduction of digital behavior brings a further computational complication to the modeling because of the timing discretization, here two different approaches have
been considered, a simplified (lighter) one and a full (heavier) one.

## Simplified SIMPLIS model

SIMPLIS modelling offers very convenient way to reduce simulation time needed for full SPICE models. The main idea is to build simplified model, which is still replicating reality at high level, but which is simplifying certain very complex events substantially as it happens in MOSFET switching transitions.

## Full SIMetrix model

Once particular operating point has been found using simplified SIMPLIS model, detailed simulation with real components models can be run around the identified operating point with the "known" initial conditions.

As can be seen in Figure 13 below, also digital control can be modelled very close to intended design approach.


Figure 13. SIMPLIS Simplified Mode Example for Fast Operating Conditions Search


Figure 14. Simplified Full Bridge Power Stage Model for SIMPLIS Simulations


Figure 15. Mixed (SPICE \& Digital) Simulation Model Example for SIMetrix - Top Level


Figure 16. Power Stage SIMetrix Model using Real SiC MOSFET Model


Proposal: $L_{M} 136.1 \mu H, L_{R} 38.3 \mu H, C_{R} 56.6 n F, N 2$
Figure 17. Transient Simulation Results Summary - Switching Frequency

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Figure 18. Transient Simulation Results Summary - Primary Side Current


Figure 19. Transient Simulation Results Summary - Secondary Side Current


Figure 20. Transient Simulation Results Summary - Transformer Magnetizing Peak Current


Figure 21. Transient Simulation Results Summary - Resonant Capacitor Peak Voltage


Figure 22. Transient Simulation Results Summary - Resonant Inductor Peak Voltage


Figure 23. Transient Simulation Results Summary - Input Capacitor Ripple Current


Figure 24. Transient Simulation Results Summary - Output Capacitor Ripple Current


Figure 25. Transient Simulation Results Summary - Overall Transistor Power Losses


Figure 26. Transient Simulation Results Summary - Overall Power Losses in Rectifier


Figure 27. Transient Simulation Results Summary - Estimated Efficiency (Core Losses not Considered)


Figure 28. Transient Simulation Waveforms


Figure 29. Transient Simulation Waveforms


Figure 30. Transient Simulation Waveforms

## SPICE Model for PCB Parasitic Evaluation

Even though number of design rules exist for good PCB layout, sometimes it is not possible to obey all of them. In the end, one of the important questions after PCB layout has been closed, usually is whether parasitic impedances introduced by PCB will or will not have substantial impact on voltage / current stress of components in circuitry. Analysis can also uncover some critical parts from EMI perspective. Various specialized software tools exist for these tasks, however even SPICE simulator can be used to get a behavioral feeling. The key point is to take a look at PCB layout and try to model all basic relations on it, building thus approximate representation of the circuit, segment by segment. Many equations and even online tools exist for flat wire inductance calculations. As an example, relatively simple one:
$\mathrm{L}_{\text {flat wire }}=0.0002 \times 1 \times\left[0.5+\ln \left(\frac{2 \mathrm{l}}{\mathrm{w}+\mathrm{t}}\right)+0.2235\left(\frac{\mathrm{w}+\mathrm{t}}{\mathrm{l}}\right)\right][\mu \mathrm{H}]$
Where is wire length, is wire width and is wire thickness, all in mm.

Example of power stage PBC part modeled can be seen also in Figure 31. Various operating conditions can be tested quite easily, example waveforms can be found below as well. Although this kind of analysis is not a must, it can be used very well for design validation. Among others, it can be also used for evaluation of snubber components effectiveness. For example so called Ceralinks very low ESL and $\mathrm{E}_{\text {SR }}$ capacitors are gaining more and more attraction. Their impact on switching waveforms can be seen very clearly in waveforms below.
Similar analysis has been done also for described evaluation board. As already mentioned previously, this board has been designed so that also external diodes can be connected in parallel to transistors. Since higher priority has been assigned to accessibility of these components than lowest PCB parasitic impedances, definite impact of these parasitic elements exist. On the other hand, although not perfect solution, it can be closer to real applications where perfect power stage layout cannot be always achieved.


Figure 31. SPICE Model for Power Stage PCB Parasitic Evaluation
QBH voltage and current: 700V/250V 10 kW without external diodes
_— Id(QBH) - no parasitics, no Ceralinks $\qquad$ Uds(QBH) - real parasitics, no Ceralinks Id(QBH) - real parasitics, no Ceralinks $\qquad$ (QBH) - real parasitics, with Ceralinks Jds(QBH) - real parasitics, with Ceralinks



Figure 32. QBH Transistor $V_{D S}$ and $I_{D}$ without External Diodes - Overview

QBH voltage and current: $700 \mathrm{~V} / 250 \mathrm{~V} 10 \mathrm{~kW}$ without external diodes
_Id(QBH) - no parasitics, no Ceralinks _U_ Uds(QBH) - real parasitics, no Ceralinks _Id(QBH) - real parasitics, with Ceralinks



Figure 33. QBH Transistor $V_{D S}$ and $I_{D}$ without External Diodes - Turn Off Detail

QBH voltage and current: 700V/250V 10kW with external diodes FFSH15120A


Figure 34. QBH Transistor $\mathrm{V}_{\mathrm{DS}}$ and $\mathrm{I}_{\mathrm{D}}$ with External Diodes Installed - Overview


Figure 35. QBH Transistor $\mathrm{V}_{\mathrm{DS}}$ and $\mathrm{I}_{\mathrm{D}}$ with External Diodes Installed - Turn Off Detail

## Simulink System Level Model

Nowadays, digital control is getting involved almost in every application. Also presented evaluation board is not an exception. Generally, the more complex the system is, the more complicated the algorithm and its implementation could be. Luckily, various methods and tools exist today to simplify these tasks. One of the options, meanwhile quite well established, is to utilize Simulink suite. It offers very good toolset for building virtually any mathematical model without any particular attention to the devices used at hardware level. It simplifies the way to build an electric model and to give higher priority to the algorithm development and testing.

Although basic control task in LLC converter is not so complicated, compared for example to 3 phase motor control or PFC applications, in principle - "only" switching
frequency has to be swept within pre-specified range, there is usually always at least one $\mathrm{PI}(\mathrm{D})$ regulator needed within the system. Different methods exist to calculate particular regulator constants, but Simulink modeling can make selection of these much more convenient.
Related control loops, constant voltage and constant current for example are very typical, can be tailored for required responses. Additionally, also their practical limits can be demonstrated, if needed. Even if optimal regulator constants have to be verified on real prototypes, simulation model can provide very good start points, shifting first prototyping tests more to the safe side.
Figure 36 depicts Simulink simulation model used during software development for presented evaluation board. As can be seen, main converter blocks visible in real hardware are replicated in model as well.


Figure 36. System Model in Simulink

## HW Schematic and Board Realization



Figure 37. OBC LLC Switch Board, Top Level Diagram


Figure 38. OBC LLC Switch Board, Power Stage


Figure 39. OBC LLC Switch Board, Rectifier


Figure 40. OBC LLC Switch Board, Drivers Interconnection, Fault Protection Logic






Figure 41. OBC LLC Switch Board, Controller Interface


Figure 42. OBC LLC Switch Board, Temperature Sensing and CAN Bus Interface


Figure 43. OBC LLC Switch Board, Insulated DC-DC Converters for MOSFET Drivers


Figure 44. OBC LLC Switch Board, DC-DC converter 700 V - 15 V 30 W


Figure 45. SiC Driver Board Circuit Diagram


Figure 46. OBC LLC Resonant Tank WE Board, Resonant Tank Board

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OBC LLC SWITCH BOARD - BILL OF MATERIALS

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OBC LLC SWITCH BOARD - BILL OF MATERIALS (continued)

| \# | Designator | Comment | Description | Manufacturer | Manufacturer Part Number | Quantity |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 39. | D9 | BAS16H | Switching diode 100 V 200 mA SOD323 ON Semiconductor | ON Semiconductor | BAS16HT1G | 1 |
| 40. | D10 | MMSZ12 | Zener diode 12 V 500 mW SOD123 ON Semiconductor | ON <br> Semiconductor | MMSZ12T1G | 1 |
| 41. | D11, D13 | MURA120 | Ultra Fast diode 200 V 1 A SMA ON Semiconductor | ON <br> Semiconductor | MURA120T3G | 2 |
| 42. | $\begin{gathered} \text { D12, D16, D17, } \\ \text { D18 } \end{gathered}$ | GREEN | SMD LED diode 30 mA GREEN 0603 Würth Elektronik | Würth Elektronik | 150060GS75000 | 4 |
| 43. | D14, D15 | BLUE | SMD LED diode 30 mA BLUE 0603 Würth Elektronik | Würth Elektronik | 150060 BS 75000 | 2 |
| 44. | $\begin{aligned} & \text { D19, D20, D21, } \\ & \text { D22 } \end{aligned}$ | NSR0340H | Schottky diode 40 V 250 mA low Vf SOD323 ON Semiconductor | ON <br> Semiconductor | NSR0340HT1G | 4 |
| 45. | $\begin{aligned} & \text { D_SEC1, } \\ & \text { D_SEC2, } \\ & \text { D_SEC3, } \\ & \text { D_SEC4 } \end{aligned}$ | FFSH3065A | SiC Schottky diode 650 V 30 A ON Semiconductor | ON Semiconductor | FFSH3065A | 4 |
| 46. | DRV_AH, <br> DRV_AL, <br> DRV_BH, <br> DRV_BL | SiC MOSFET driver board with NCP51705 | SiC MOSFET driver board with NCP51075 ON Semiconductor |  |  | 4 |
| 47. | L1, L2, L3, L4 | $22 \mu \mathrm{H}$ | WE TPC power inductor SMD $22 \mu \mathrm{H} 0.925 \mathrm{~A}$ Würth Elektronik | Würth Elektronik | 744043220 | 4 |
| 48. | L5 | $100 \mu \mathrm{H}$ | WE PD power inductor SMD $100 \mu \mathrm{H}$ 1.5 A Würth Elektronik | Würth Elektronik | 7447714101 | 1 |
| 49. | L6, L7 | 2 m 2 | Bobbin core RF choke 2.2 mH 80 mA TDK | TDK | B78108S1225J000 | 2 |
| 50. | L8 | 1 mH | Bobbin core RF choke 1 mH 130 mA TDK | TDK | B78108S1105J000 | 1 |
| 51. | NQ1, NQ4 | hex nut M3 DIN934 | Hex nut M3 DIN934 ISO4032 |  |  | 2 |
| 52. | O1, O2, О3 | SFH615A-3 | Optocoupler, high realibility, 5300 Vrms Vishay | Vishay | SFH615A-3X007T | 3 |
| 53. | $\begin{gathered} \text { PAH, PAL, PBH, } \\ \text { PBL } \end{gathered}$ | QA01C | Insulated DC-DC converter for IGBT drivers 15 V -> +20 V/-4 V low capacity Mornsun |  |  | 4 |
| 54. | Q1, Q2, Q5 | FQPF5N90 | NMOS 900 V 3 A 2.3R ON Semiconductor | ON <br> Semiconductor | FQPF5N90 | 3 |
| 55. | Q3 | BSS138L | NMOS $50 \mathrm{~V} 0.2 \mathrm{~A} 200 \mathrm{~mA} 3.5 \Omega$ ON Semiconductor | ON Semiconductor | BSS138LT1G | 1 |
| 56. | Q4 | FDPF2710T | NMOS $250 \mathrm{~V} 25 \mathrm{~A} 42.5 \mathrm{~m} \Omega$ ON Semiconductor | ON Semiconductor | FDPF2710T | 1 |
| 57. | Q6 | MMBT589LT1G | High Current surface mount PNP silicon switching transistor | ON Semiconductor | MMBT589LT1G | 1 |
| 58. | Q7, Q10 | TL431ACDG | Voltage reference 2.5 V 1 mA ON Semiconductor | ON <br> Semiconductor | TL431ACDG | 2 |
| 59. | Q8, Q9 | NCS333 | Single low noise zero drift OPAMP ON Semiconductor | ON Semiconductor | NCS333SN2T1G | 2 |
| 60. | $\begin{gathered} \text { QAH, QAL, QBH, } \\ \text { QBL } \end{gathered}$ | NTW080N12SC1 | SiC NMOS 1200 V 36 A $80 \mathrm{~m} \Omega$ ON Semiconductor | ON <br> Semiconductor | NTW080N12SC1 | 4 |
| 61. | R1, R2, R3, R4, RCOHA, RCOHB, RCOLA, RCOLB | 82k | SMD thick film resistor 82k 1206 1\% 660 mW Panasonic | Panasonic | ERJP08F8202V | 8 |
| 62. | $\begin{gathered} \text { R5, R11, R12, } \\ \text { R19, R20, R27, } \\ \text { R28, } \\ \text { R34, R35, R93, } \\ \text { R94 } \end{gathered}$ | 100k | SMD thick film resistor 100k 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF1003V | 11 |
| 63. | R6, R14, R22, R29, R91, R92, R118, R120 | 10k | SMD thick film resistor 10k 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF1002V | 8 |
| 64. | R7, R15, R23, R30, R98, R99, R123, R125, R128, R130 | 82R | SMD thick film resistor 82R $06031 \% 100 \mathrm{~mW}$ Panasonic | Panasonic | ERJ3EKF82R0V | 10 |
| 65. | R8, R16, R24, R31, R73, R95, R96 | 2k2 | SMD thick film resistor 2k2 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF2201V | 7 |
| 66. | R9, R17, R25, R32, R97 | 820R | SMD thick film resistor 820R $06031 \% 100 \mathrm{~mW}$ Panasonic | Panasonic | ERJ3EKF8200V | 5 |
| 67. | R10, R18, R21, R26, R33, R101, R102 | 10R | SMD thick film resistor 10R 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF10R0V | 7 |
| 68. | R13, R55, R83 | 2k2 | SMD thick film resistor 2k2 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF2201V | 3 |

OBC LLC SWITCH BOARD - BILL OF MATERIALS (continued)

| \# | Designator | Comment | Description | Manufacturer | Manufacturer Part Number | Quantity |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 69. | R36, R38, R39, R41, R44, R53, R71, R72, R74, R78, R79, R80, R81 | 820k | SMD thick film resistor 820k 1206 1\% 660 mW Panasonic | Panasonic | ERJP08F8203V | 13 |
| 70. | R37 | OR | SMD thick film resistor OR 0805 2A Panasonic | Panasonic | ERJ6GEYOR00V | 1 |
| 71. | R40, R42 | 47R | SMD thick film resistor 47R 1206 1\% 660 mW Panasonic | Panasonic | ERJP08F47R0V | 2 |
| 72. | R43, R46 | 220R | SMD thick film resistor 220R 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF2200V | 2 |
| 73. | R45, R54, R77 | 10k | SMD thick film resistor 10k 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1002V | 3 |
| 74. | R47, R52, R56, R57, R106, R107 | 3 k 3 | SMD thick film resistor 3k3 1206 1\% 660 mW Panasonic | Panasonic | ERJP08F3301V | 6 |
| 75. | R48 | 100R | SMD thick film resistor 100R 1206 1\% 660 mW Panasonic | Panasonic | ERJP08F1000V | 1 |
| 76. | R49, R62 | 22R | SMD thick film resistor 22R $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF22R0V | 2 |
| 77. | R50 | 10R | SMD thick film resistor 10R 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF10R0V | 1 |
| 78. | R51 | 56k | SMD thick film resistor 56k $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF5602V | 1 |
| 79. | R59 | 8R2 | SMD thick film resistor 8R2 0805 5\% 125 mW 150 V Vishay | Vishay Draloric | CRCW08058R20JNEAIF | 1 |
| 80. | R60, R82 | 330R | SMD thick film resistor 330R 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF3300V | 2 |
| 81. | R61 | 12k7 | SMD thick film resistor 12k7 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1272V | 1 |
| 82. | R63 | 78k7 | SMD thick film resistor 78k7 $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF7872V | 1 |
| 83. | R64, R89, R90 | 1k | SMD thick film resistor 1k $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF1001V | 3 |
| 84. | R65, R85 | 15k | SMD thick film resistor 15k 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1502V | 2 |
| 85. | R66, R108 | 6k8 | SMD thick film resistor 6k8 $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF6801V | 2 |
| 86. | R67 | 47k | SMD thick film resistor 47k 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF4702V | 1 |
| 87. | R68 | 1R3 | SMD current sense resistor 1R3 1206 1\% 330 mW Panasonic | Panasonic | ERJ8BQF1R3V | 1 |
| 88. | R69 | 2k49 | SMD thick film resistor 2k49 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF2491V | 1 |
| 89. | R70 | 56R | SMD thick film resistor 56R 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF56R0V | 1 |
| 90. | R75 | 16k2 | SMD thick film resistor 16k2 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1622V | 1 |
| 91. | R76 | 300 $\mu$ | SMD Current Sense Resistor with Kelvin connection, $300 \mu \Omega$, 7 W, $\pm 1 \%$, Power Metal Strip, Vishay | Vishay | WSL4026L3000FEB | 1 |
| 92. | R84, R88 | 680R | SMD thick film resistor 680R $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF6800V | 2 |
| 93. | R86 | 18k | SMD thick film resistor 18k 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1802V | 1 |
| 94. | R87 | 12R | SMD thick film resistor 12R 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF12R0V | 1 |
| 95. | R100, R115, R116, R117, R119 | 33R | SMD thick film resistor 33R 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF33ROV | 5 |
| 96. | R103, R104 | 60R4 | SMD thick film resistor 60R4 $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF60R4V | 2 |
| 97. | R105 | 1k2 | SMD thick film resistor 1k2 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF1201V | 1 |
| 98. | R109 | 68k | SMD thick film resistor 68k 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF6802V | 1 |
| 99. | R110 | 120k | SMD thick film resistor 120k $08051 \% 125 \mathrm{~mW}$ Panasonic | Panasonic | ERJ6ENF1203V | 1 |
| 100. | R111, R113 | 7k5 | SMD thick film resistor 7k5 0805 1\% 125 mW Panasonic | Panasonic | ERJ6ENF7501V | 2 |
| 101. | R112 | 91k | SMD thick film resistor 91k 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF9102V | 1 |
| 102. | R114 | 20k | SMD thick film resistor 20k 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF2002V | 1 |
| 103. | R121 | 220R | SMD thick film resistor 220R 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF2200V | 1 |
| 104. | R122, R124, R129, R131 | 22R | SMD thick film resistor 22R 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF22R0V | 4 |
| 105. | R126, R127 | 11R | SMD thick film resistor 11R 0603 1\% 100 mW Panasonic | Panasonic | ERJ3EKF11R0V | 2 |
| 106. | TR1 | 760301302 | Transformer for gate drive one output | Würth Elektronik | 760301302 | 1 |
| 107. | TR2 | 750315046 | Transformer for DC-DC converter 750315046 Würth Elektronik | Würth Elektronik | 750315046 | 1 |
| 108. | U1, U3, U9 | MC74ACT74 | Dual D-Type Positive Edge-Triggered Flip-Flop with asynchronous set/reset ON Semiconductor | ON Semiconductor | MC74ACT74DR2G | 3 |
| 109. | U2 | MC74HC30A | 8-input NAND gate, high speed ON Semiconductor | ON <br> Semiconductor | MC74HC30ADG | 1 |
| 110. | U4 | NCP4304A | Secondary side synchronous rectification driver | ON Semiconductor | NCP4304ADR2G | 1 |

OBC LLC SWITCH BOARD - BILL OF MATERIALS (continued)

| $\#$ | Designator | Comment | Description | Manufacturer | Manufacturer Part Number | Quantity |
| :---: | :---: | :---: | :--- | :---: | :---: | :---: |
| 111. | U5 | NCP1252D | Flyback/ Forward controller ON Semiconductor | ON <br> Semiconductor | NCP1252DDR2G | 1 |
| 112. | U6 | NCS210RSQ | Current Sense Amplifier, 26 V, Low-/High-Side Voltage Out, <br> Bidirectional Current Shunt Monitor, fixed gain 200 | ON <br> Semiconductor | NCS210RSQT2G | 1 |
| 113. | U7 | LM321 | Single channel operational amplifier, 3-32 V, bipolar, <br> ON Semiconductor | ON <br> Semiconductor | LM321SN3T1G | 1 |
| 114. | U8 | TC74A5-3.3VAT | Digital temperature sensor with serial interface -40 - 125º, I2C <br> addres 0xA5, optimized for 3.3 V, Microchip | Microchip | TC74A5-3.3VAT | 1 |
| 115. | U10, U11 | MC74VHC1G32 | 2-Input OR Gate/CMOS Logic Level Shifter ON Semiconductor | ON <br> Semiconductor | MC74VHC1G32DTT1G | 2 |
| 116. | U12 | NCV7342D13R2G | High speed low power CAN transceiver with dual supply <br> ON Semiconductor | ON <br> Semiconductor | NCV7342D13R2G | 1 |



Figure 47. OBC LLC Switch Board PCB - Top Layer


Figure 48. OBC LLC Switch Board PCB - Internal Groung Plane Layer


Figure 49. OBC LLC Switch Board PCB - Internal Power Plane Layer


Figure 50. OBC LLC Switch Board PCB - Bottom Layer


Figure 51. OBC LLC Switch Board - Top View


Figure 52. OBC LLC Switch Board - Bottom View


Figure 53. OBC LLC Switch Board with External Resonant Tank Board

## Test Setup Usage

Following prerequisites are needed to operate presented OBC LLC evaluation setup:

- OBC LLC switch board
- Resonant tank board

OBC LLC evaluation setup has been designed so that passive components of resonant tank are located on another board connected to OBC LLC switch board. This provides high degree of flexibility, various tank solutions can be tested without complete redesign of the converter board.

## - Interconnection between OBC LLC Switch Board and External Resonant Tank Board

4 short interconnection links are needed to connect external resonant tank to OBC LLC switch board. Good idea is to keep them short if possible. User has also to consider appropriate cross section of interconnection wires to handle flowing currents without substantial overheating. Maximum current foreseen in design phase is 40 ARMS at DC output. Switch board is equipped with so called red cube terminals for M5 screws.
OBC LLC switch board provides also an option to connect and control an external fan, which can be installed on external resonant tank board. Molex 43025-0400 connector and four 46235-0001 female crimp terminals are recommended.

## - High Voltage DC Power Supply

Nominal input voltage of the board is 700 V , there are two 450 V capacitors in series at the board input side, so maximum input voltage is about 850 V . Note, that power supply has to provide enough power for intended test purposes, including also power losses within tested application.
Molex 44441-2002 connector with two female crimp terminals 1718125-0100 are needed for DC input connection.

## - High Voltage DC Load

Maximal output voltage considered during design phase is 450 V , however, similarly to converter input, two branches of two 450 V capacitors in series are installed at the converter DC output, so even higher voltage could be tested, if required. Note that 650 V diodes are used in secondary side rectifier, so they need to be eventually changed for higher output voltages.
Electronic, so called recuperation loads are used very often to reduce electric energy amount used for tests. Unfortunately, sometimes their regulators are not so perfect under certain operating conditions, which may be exhibited as a various instabilities present at tested converter output.

Consequently, false implications can be derived judging converter guilty even if it is not necessary true.
Similarly to resonant tank board connection, M5 red cube terminals are used for DC output connection.

## - External 15 V Power Supply

Housekeeping 15 V output DC-DC converter on OBC LLC switch board starts to operate at about 390 V at board DC input. For test purposes, 15 V power line can be supplied also by external DC power supply. One 691351500002 connector from Würth Elektronik is needed to make this connection. Keep in mind that external DC power supply with appropriate insulation level has to be used eventually, once high voltage is present at OBC LLC switch board input and converter is running.

## - Recirculating Liquid Cooler

All power semiconductor components on OBC LLC switch board are mounted on liquid cold plate, so appropriate external liquid cooler, like Julabo F500 for example, has to be used. Liquid connection to cold plate consists of two bare $3 / 8$ " (outer diameter) copper tubes. Cold plate rated recommended maximum flowrate is 1 gallon per minute. Effective thermal resistance is not reduced meaningfully above this flowrate.

## - PC with Installed GUI Application

OBC LLC switch board does not start automatically once powered or reset. Firmware in controller requires active communication over USB interface with special GUI application on PC. As can be seen also in snapshot below, GUI provides basic diagnostic and control functions.

## Basic GUI Usage

1. Connection to OBC LLC switch board is initialized by clicking "CONNECT" button located in right bottom corner of application window
2. As a next step, virtual oscilloscope can be activated using "RUN" button on right side
3. Voltage and / or current reference (e.g. output regulation target value) has to be entered
4. Control type (voltage or current control) has to be selected using combo box in left bottom corner of application window. Bear in mind that only one control loop is active at the same time - constant voltage OR constant current
5. Now, converter can be started by clicking "SEND $R E F V A L U E "$ button. This button has to be used also if new target voltage or current value is needed while converter is already running
6. Finally, "STOP LLC SWITCHING" button can be used to stop converter operation

TND6318/D


Figure 54. OBC LLC Switch Board PC GUI Application

Test results


Figure 55. Converter Operating Waveforms - 700 V to 220 V, Load Current 30 A ( 6.6 kW)


Figure 56. Converter Operating Waveforms - 700 V to 250 V, Load Current 30 A ( 7.5 kW)


Figure 57. Converter Operating Waveforms - 700 V to 300 V, Load Current 30 A (9 kW)

## TND6318/D



Figure 58. Converter Operating Waveforms - 700 V to 350 V, Load Current 28.6 A (10 kW)


Figure 59. Converter Operating Waveforms - 700 V to 400 V, Load Current 25 A (10 kW)

## TND6318/D



Figure 60. Converter Operating Waveforms - 700 V to 450 V, Load Current 22.35 A (10 kW)


Figure 61. SWAHalf Bridge High Side Turn Off

## TND6318/D



Figure 62. SWA Half Bridge Low Side Turn Off


Figure 63. Skip Mode Operation - Input Voltage 700 V, Output Voltage 210 V, Load $136 \Omega$

## TND6318/D



Figure 64. Skip Mode Operation - Input Voltage 700 V, Output Voltage 250 V, Load $136 \Omega$


Figure 65. Skip Mode Operation - Input Voltage 700 V, Output Voltage 300 V, Load $136 \Omega$


Figure 66. Measured Efficiency vs. Load Current - Overview


Figure 67. Measured Efficiency vs. Load Current - Detail

OBC LLC 10 kW efficiency (input voltage 700 V )


Figure 68. Measured Efficiency vs. Output Power - Overview


Figure 69. Measured Efficiency vs. Output Power - Detail

## References

[1]. Junjun Deng, Siqi Li, Sideng Hu, Chunting Chris Mi, Ruiqing Ma"Design Methodology of LLC
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Chargers" published in IEEE Transactions on Vehicular Technology, Volume 63, Issue 4, May 2014.

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