INTRODUCTION

When it comes to communicating over a serial bus, there are three main methods, SPI (Serial Peripheral Interface), Microwire and I²C. The choice is not always easy to make, and often the designer must use whichever hardware is available on his micro-controllers or peripherals. Art Eck claims that that of the three common interfaces, SPI is easiest to write code for, and is the fastest protocol.

The SPI-bus was invented in the 1980s as a simple inexpensive way to communicate with peripherals, with a minimum of code and absolute simplicity of the receive function. The SPI-bus is synchronous, with the “master” device responsible for sending out its own clock signal. The bus in its most expansive form consists of 4 wires, SCK (Serial Clock), MISO (Master In Slave Out), MOSI (Master Out Slave In), and SS (Slave Select). The MC74HC589A is a MISO (slave) device only. It will not interfere with the SPI bus use of other master devices in the system, however if there are no other masters, the system reduces to the MISO line, the SCK line and number of SS lines. The SS lines can be either a single line controlling a single device or multiple lines for multiple devices. The Latch Clock pin of the NLSF589 is the SS pin for SPI operation. In addition, the MCU needs to provide a logic pin to control the action of the register, either Parallel Load or Serial Shift, this action is not an explicit requirement of SPI, however the part will not function properly, without setting this up. It requires a low to high transition to move the data that has been stored in the shift register, into the output latch. Although the device has an active low Enable pin, it is not necessary to use this pin, and it may be hard wired low.

APPLICATION

The diagram below shows the use of an MC74HC589 used to detect key closures in a remote location. We only use the MISO port of the MCU. The Key closures are applied to pins A-H. There is no way to determine that a key has either been opened or closed, so the designer must use a “polling” technique. The designer initialises the data, then goes out to the shift register, and reads the data, and looks for a change from the prior state. The designer must return to the SPI port, and update the information on a regular basis e.g. every 30ms. The “HC589” has 8 parallel inputs, along with the various pins for SPI. The diagram shows the switches with pull up resistors on the parallel port (A-H), so the designer just needs to supply a logic level to the port. De-bounce is not explicitly required in hardware. The software engineer might want to return to the port and poll it again, perhaps 10ms later, to see if the closure records the same data. The actual software algorithm will be left to the designer. One further aspect of the design requires the rise and fall times of the clock signals are observed. At a supply voltage of 5 V, the rise time must be = 400 ns to assure the clock are recognized and change state properly. Some designers try to eliminate rf noise by using RC filtering ion the data and clock lines. The recommendation is to use a hysteresis gate(s) on the lines so that the rise and fall time can be met. The circuit is shown operating at 3.3 V, the only requirement is that both the MCU and the shift register function at the same voltage, unless the designer explicitly handles the differences with logic level translators. The diagram shows the EN (Pin 10) asserted with a logic level low, and the latch clock (Pin 12) being asserted with a rising edge applied to this pin. If the designer is trying to save wires, he can use a single gate inverter e.g MC74HC1G14 to create a rising edge from the output enable logic level. Two or more“589s” may be cascaded to get 16, 24 or more bits of data. If this is done, the reader should approach this carefully by reading ON Semiconductor Application Note: AND8144/D and observing the timing issues.

Figure 1. Application Diagram