

Intelligent Power Module (IPM)

600 V, 15 A

NFAQ1560R43TB

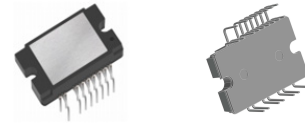
The NFAQ1560R43TB is a fully-integrated inverter power stage consisting of a high-voltage driver, six IGBTs (FS4 RC IGBT technology) and a thermistor, suitable for driving permanent magnet synchronous motors (PMSM), brushless-DC (BLDC) motors and AC asynchronous motors. The IGBTs are configured in a 3-phase bridge with separate emitter connections for the lower legs for maximum flexibility in the choice of control algorithm. The power stage has a full range of protection functions including cross-conduction protection, external shutdown and under-voltage lockout functions. An internal comparator and reference connected to the over-current protection circuit allows the designer to set the over-current protection level.

Features

- Three-phase 15 A/600 V IGBT Module with Integrated Drivers
- Compact 29.6 mm x 18.2 mm Dual In-Line Package
- Built-in Under Voltage Protection
- Cross-conduction Protection
- ITRIP Input to Shut Down All IGBTs
- Integrated Bootstrap Diodes and Resistors
- Thermistor for Substrate Temperature Measurement
- Shut Down Pin
- UL1557 Certification (File Number: E339285)
- This is a Pb-Free Device

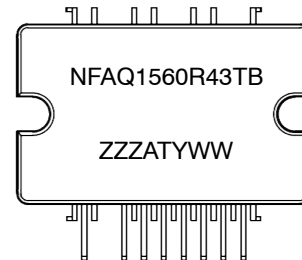
Typical Applications

- Industrial Pumps
- Industrial Fans
- Industrial Automation
- Home Appliances



DIP38 29.6x18.2
CASE 125BS

MARKING DIAGRAM



NFAQ1560R43TB = Specific Device Code
 ZZZ = Assembly Lot Code
 A = Assembly Location
 T = Test Location
 Y = Year
 WW = Work Week

Device marking is on package top side

ORDERING INFORMATION

Device	Package	Shipping (Qty / Packing)
NFAQ1560R43TB	DIP38 (Pb-Free)	400 / Box

NFAQ1560R43TB

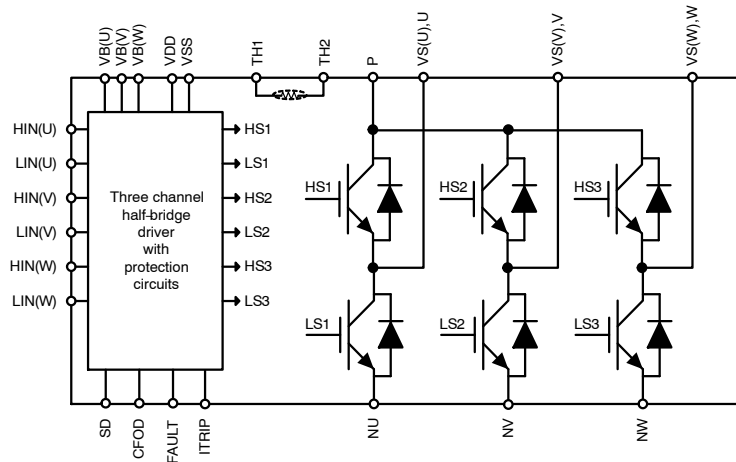


Figure 1. Function Diagram

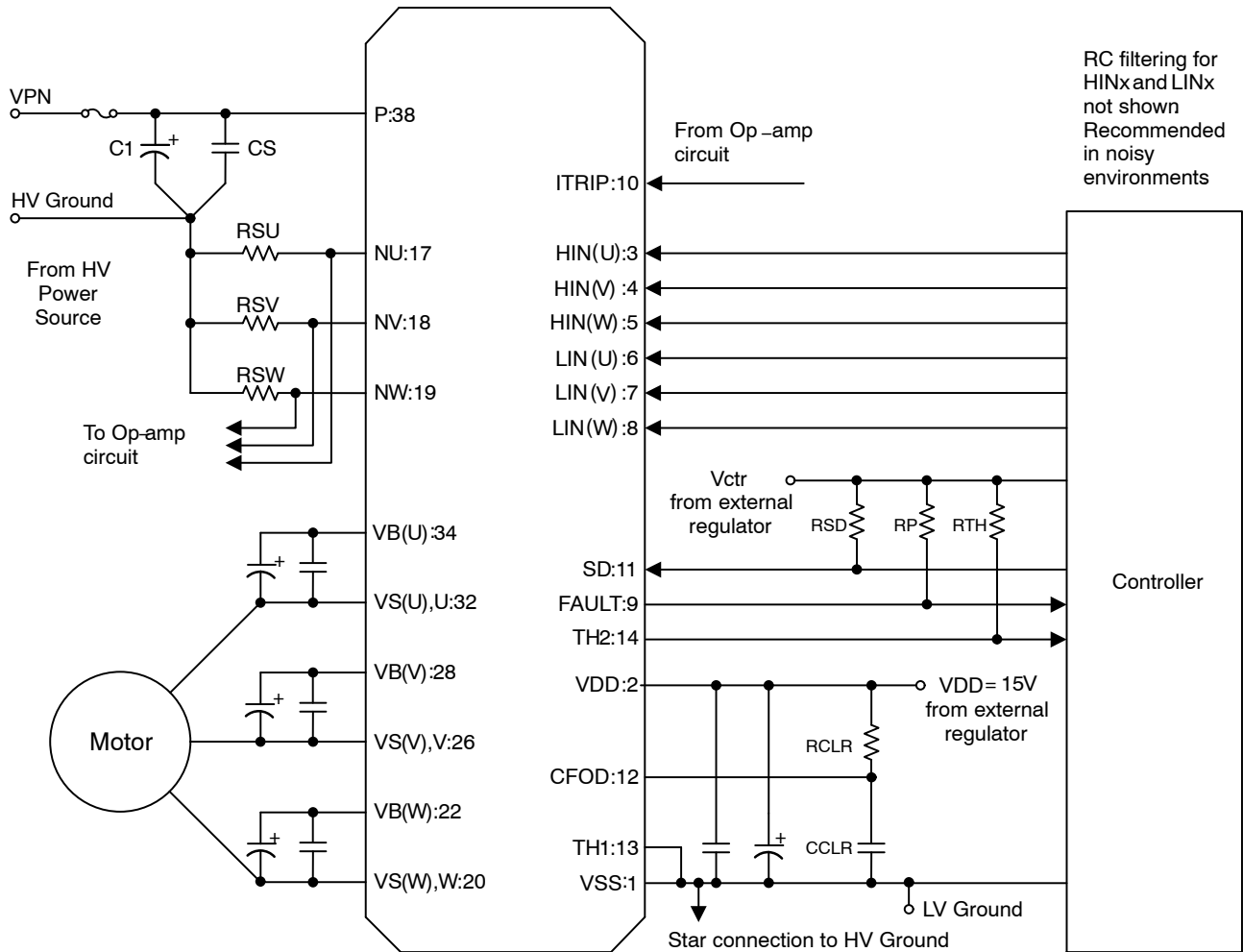


Figure 2. Application Schematic

NFAQ1560R43TB

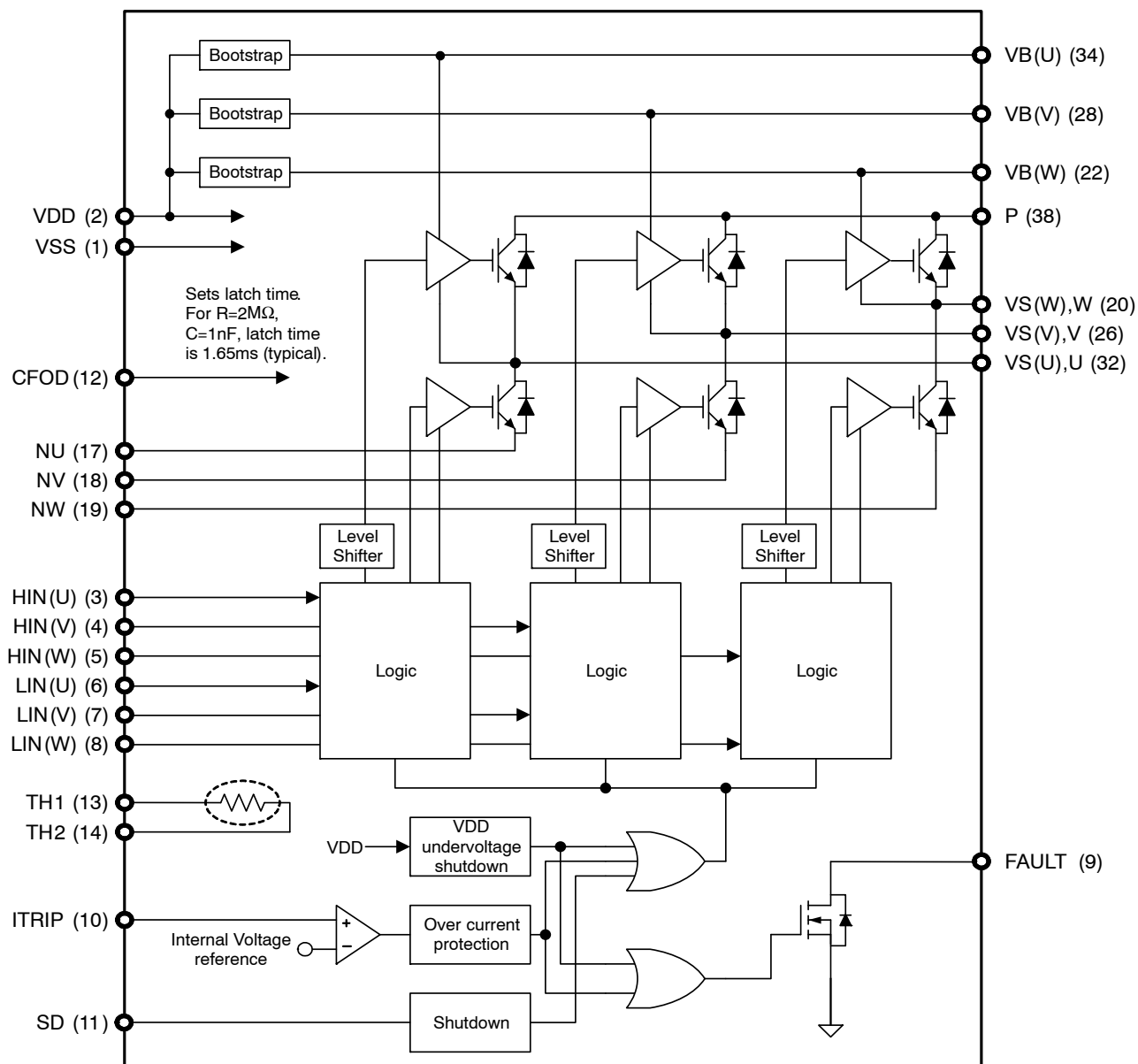


Figure 3. Simplified Block Diagram

NFAQ1560R43TB

PIN FUNCTION DESCRIPTION

Pin	Name	Description
1	VSS	Low-Side Common Supply Ground
2	VDD	Low-Side Bias Voltage for IC and IGBTs Driving
3	HIN(U)	Signal Input for High-Side U Phase
4	HIN(V)	Signal Input for High-Side V Phase
5	HIN(W)	Signal Input for High-Side W Phase
6	LIN(U)	Signal Input for Low-Side U Phase
7	LIN(V)	Signal Input for Low-Side V Phase
8	LIN(W)	Signal Input for Low-Side W Phase
9	FAULT	Fault output
10	ITRIP	Input for Over Current Protection
11	SD	Shut Down Input
12	CFOD	Capacitor and Resistor for Fault Output Duration Selection
13	TH1	Thermistor Bias Voltage
14	TH2	Series Resistor for Thermistor
17	NU	Negative DC-Link Input for U Phase
18	NV	Negative DC-Link Input for V Phase
19	NW	Negative DC-Link Input for W Phase
20	VS(W), W	High-Side Bias Voltage GND for W phase IGBT Driving, Output for W Phase
22	VB(W)	High-Side Bias Voltage for W phase IGBT Driving
26	VS(V), V	High-Side Bias Voltage GND for V phase IGBT Driving, Output for V Phase
28	VB(V)	High-Side Bias Voltage for V phase IGBT Driving
32	VS(U), U	High-Side Bias Voltage GND for U phase IGBT Driving, Output for U Phase
34	VB(U)	High-Side Bias Voltage for U phase IGBT Driving
38	P	Positive DC-Link Input

NOTE: Pins 15, 16, 21, 23, 24, 25, 27, 29, 30, 31, 33, 35, 36 and 37 are not present

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ABSOLUTE MAXIMUM RATINGS at $T_C = 25^\circ\text{C}$ (Note 1)

Parameter	Symbol	Conditions	Rating	Unit
Supply Voltage	V_{PN}	P – NU, NV, NW, V_{PN} (surge) < 500 V (Note 2)	450	V
Collector–Emitter Voltage	V_{CES}	P – U, V, W; U – NU; V – NV; W – NW	600	V
Each IGBT Collector Current	I_C	P, U, V, W, NU, NV, NW terminal current	± 15	A
		P, U, V, W, NU, NV, NW terminal current, $T_C = 100^\circ\text{C}$	± 7.5	A
Each IGBT Collector Current (Peak)	I_{Cp}	$T_C = 25^\circ\text{C}$, Under 1 ms Pulse Width	± 30	A
Corrector Dissipation	P_C	$T_C = 25^\circ\text{C}$, Per One Chip (IGBT Part)	50	W
		$T_C = 25^\circ\text{C}$, Per One Chip (FRD Part)	26.5	W
High–Side Control Bias voltage	V_{BS}	$V_B(U) - V_S(U)$, $V_B(V) - V_S(V)$, $V_B(W) - V_S(W)$ (Note 3)	–0.3 to +20.0	V
Control Supply Voltage	V_{DD}	$V_{DD} - V_{SS}$	–0.3 to +20.0	V
Input Signal Voltage	V_{IN}	$H_{IN}(U)$, $H_{IN}(V)$, $H_{IN}(W)$, $L_{IN}(U)$, $L_{IN}(V)$, $L_{IN}(W) - V_{SS}$	–0.3 to V_{DD}	V
FAULT Terminal Voltage	V_{FAULT}	FAULT – VSS	–0.3 to V_{DD}	V
CFOD Terminal Voltage	V_{CFOD}	CFOD – VSS	–0.3 to V_{DD}	V
SD Terminal Voltage	V_{SD}	SD – VSS	–0.3 to V_{DD}	V
Current Sensing Input Voltage	V_{ITRIP}	ITRIP – VSS	–0.3 to +10.0	V
Operating Junction Temperature	T_j		150	$^\circ\text{C}$
Storage Temperature	T_{stg}		–40 to +125	$^\circ\text{C}$
Module Case Operation Temperature	T_C		–40 to +125	$^\circ\text{C}$
Tightening Torque	MT	Case mounting screws	0.6	Nm
Isolation Voltage	V_{iso}	50 Hz sine wave AC 1 minute (Note 4)	2000	Vrms

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. Refer to ELECTRICAL CHARACTERISTICS, RECOMMENDED OPERATING RANGES and/or APPLICATION INFORMATION for Safe Operating parameters
2. This surge voltage developed by the switching operation due to the wiring inductance between P and NU, NV, NW terminal.
3. $V_{BS} = V_B(U) - V_S(U)$, $V_B(V) - V_S(V)$, $V_B(W) - V_S(W)$
4. Test conditions : AC2500V, 1 s

RECOMMENDED OPERATING RANGES

Rating	Symbol	Conditions	Min	Typ	Max	Unit
Supply Voltage	V_{PN}	P – NU, NV, NW	0	280	450	V
High–Side Control Bias Voltage	V_{BS}	$V_B(U) - V_S(U)$, $V_B(V) - V_S(V)$, $V_B(W) - V_S(W)$	13.0	15	17.5	V
Control Supply Voltage	V_{DD}	$V_{DD} - V_{SS}$	14.0	15	16.5	V
ON–state Input Voltage	$V_{IN(ON)}$	$H_{IN}(U)$, $H_{IN}(V)$, $H_{IN}(W)$, $L_{IN}(U)$, $L_{IN}(V)$, $L_{IN}(W) - V_{SS}$	3.0	–	5.0	V
OFF–state Input Voltage	$V_{IN(OFF)}$		0	–	0.3	V
PWM Frequency	f_{PWM}		1	–	20	kHz
Dead Time	DT	Turn–off to Turn–on (external)	1	–	–	μs
Allowable Input Pulse Width	PWIN	ON and OFF	1	–	–	μs
Tightening Torque		'M3' Type Screw	0.4	–	0.6	Nm

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

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ELECTRICAL CHARACTERISTICS at $T_C = 25^\circ\text{C}$, $V_{\text{BIAS}} (V_{\text{BS}}, V_{\text{DD}}) = 15\text{ V}$ unless otherwise noted.

Parameter	Test Conditions	Symbol	Min	Typ	Max	Unit
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POWER OUTPUT SECTION

Collector–Emitter Leakage Current	$V_{\text{CE}} = 600\text{ V}$	I_{CES}	–	–	100	μA
Collector–Emitter Saturation Voltage	$I_{\text{N}} = 5\text{ V}$, $I_{\text{C}} = 15\text{ A}$, $T_{\text{J}} = 25^\circ\text{C}$	$V_{\text{CE(sat)}}$	1.45	1.7	2.2	V
	$I_{\text{N}} = 5\text{ V}$, $I_{\text{C}} = 7.5\text{ A}$, $T_{\text{J}} = 100^\circ\text{C}$		–	1.4	–	V
FWDi Forward Voltage	$I_{\text{N}} = 0\text{ V}$, $I_{\text{C}} = -15\text{ A}$, $T_{\text{J}} = 25^\circ\text{C}$	V_{F}	–	2.0	2.5	V
	$I_{\text{N}} = 0\text{ V}$, $I_{\text{C}} = -7.5\text{ A}$, $T_{\text{J}} = 100^\circ\text{C}$		–	1.6	–	V
Junction to Case Thermal Resistance	Inverter IGBT Part (per 1/6 Module)	$R_{\text{th(j-c)Q}}$	–	–	2.5	$^\circ\text{C/W}$
	Inverter FRD Part (per 1/6 Module)	$R_{\text{th(j-c)F}}$	–	–	4.7	$^\circ\text{C/W}$

SWITCHING CHARACTER

Switching Time	$I_{\text{C}} = 15\text{ A}$, $V_{\text{PN}} = 300\text{ V}$, $T_{\text{J}} = 25^\circ\text{C}$, Inductive Switching	t_{ON}	–	0.4	1.1	μs
		t_{OFF}	–	0.5	1.2	μs
Turn-on Switching Loss	$I_{\text{C}} = 15\text{ A}$, $V_{\text{PN}} = 300\text{ V}$, $T_{\text{J}} = 25^\circ\text{C}$	E_{ON}	–	360	–	μJ
Turn-off Switching Loss		E_{OFF}	–	260	–	μJ
Total Switching Loss		E_{TOT}	–	620	–	μJ
Turn-on Switching Loss	$I_{\text{C}} = 7.5\text{ A}$, $V_{\text{PN}} = 300\text{ V}$, $T_{\text{J}} = 100^\circ\text{C}$	E_{ON}	–	180	–	μJ
Turn-off Switching Loss		E_{OFF}	–	180	–	μJ
Total Switching Loss		E_{TOT}	–	360	–	μJ
Diode Reverse Recovery Energy	$I_{\text{C}} = 7.5\text{ A}$, $V_{\text{PN}} = 300\text{ V}$, $T_{\text{J}} = 100^\circ\text{C}$, (di/dt set by internal driver)	E_{REC}	–	110	–	μJ
Diode Reverse Recovery Time		t_{RR}	–	120	–	ns
Reverse Bias Safe Operating Area	$I_{\text{C}} = 30\text{ A}$, $V_{\text{CE}} = 450\text{ V}$	RBSOA	Full Square			
Short Circuit Safe Operating Area	$V_{\text{CE}} = 400\text{ V}$, $T_{\text{J}} = 100^\circ\text{C}$	SCSOA	4	–	–	μs

DRIVER SECTION

Quiescent VBS Supply Current	$V_{\text{BS}} = 15\text{ V}$, $H_{\text{IN}} = 0\text{ V}$, per driver	I_{QBS}	–	0.08	0.4	mA
Quiescent VDD Supply Current	$V_{\text{DD}} = 15\text{ V}$, $L_{\text{IN}} = 0\text{ V}$, $V_{\text{DD}} - V_{\text{SS}}$	I_{QDD}	–	0.95	3.0	mA
ON Threshold Voltage	$H_{\text{IN}}(\text{U})$, $H_{\text{IN}}(\text{V})$, $H_{\text{IN}}(\text{W})$, $L_{\text{IN}}(\text{U})$, $L_{\text{IN}}(\text{V})$, $L_{\text{IN}}(\text{W}) - V_{\text{SS}}$	$V_{\text{IN(ON)}}$	–	–	2.5	V
OFF Threshold Voltage		$V_{\text{IN(OFF)}}$	0.8	–	–	V
Logic 1 Input Current	$V_{\text{IN}} = +3.3\text{ V}$	$I_{\text{IN+}}$	–	660	900	μA
Logic 0 Input Current	$V_{\text{IN}} = 0\text{ V}$	$I_{\text{IN-}}$	–	–	3	μA
Bootstrap ON Resistance	$I_{\text{B}} = 1\text{ mA}$	RB	–	500	–	Ω
FAULT Terminal Sink Current	FAULT: ON / $V_{\text{FAULT}} = 0.1\text{ V}$	I_{oSD}	–	2	–	mA
Fault–Output Pulse Width	FAULT – VSS From time fault condition clear $R = 2\text{ M}\Omega$, $C = 1\text{ nF}$	t_{FOD}	1.1	1.65	2.2	ms
CFOD Threshold	CFOD – VSS	V_{CFOD}	–	8	–	V
Shut Down Threshold	SD – VSS	$V_{\text{SD+}}$	–	–	2.5	V
		$V_{\text{SD-}}$	0.8	–	–	V
ITRIP Trip Level	ITRIP – VSS	V_{ITRIP}	0.44	0.49	0.54	V
ITRIP to Shutdown Propagation Delay		t_{ITRIP}	–	1.1	–	μs
ITRIP Blanking Time		t_{ITRIPBL}	250	350	–	ns
High–Side Control Bias Voltage Under–Voltage Protection	Reset Level	UVBSR	10.3	11.1	11.9	V
	Detection Level	UVBSD	10.1	10.9	11.7	V
	Hysteresis	UVBSH	–	0.2	–	V

ELECTRICAL CHARACTERISTICS at $T_C = 25^\circ\text{C}$, $V_{\text{BIAS}} (V_{\text{BS}}, V_{\text{DD}}) = 15\text{ V}$ unless otherwise noted.

Parameter	Test Conditions	Symbol	Min	Typ	Max	Unit
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DRIVER SECTION

Supply Voltage Under-Voltage Protection	Reset Level	UVDDR	10.3	11.1	11.7	V
	Detection Level	UVDDD	10.1	10.9	11.5	V
	Hysteresis	UVDDH	–	0.2	–	V

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

TYPICAL CHARACTERISTICS

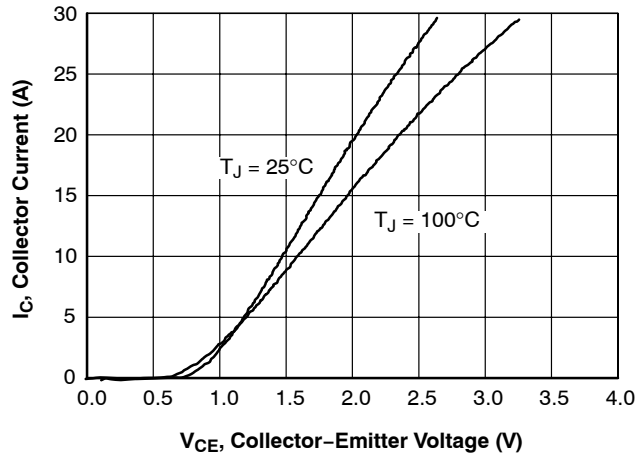


Figure 4. V_{CE} versus I_{C} for Different Temperatures ($V_{\text{DD}} = 15\text{ V}$)

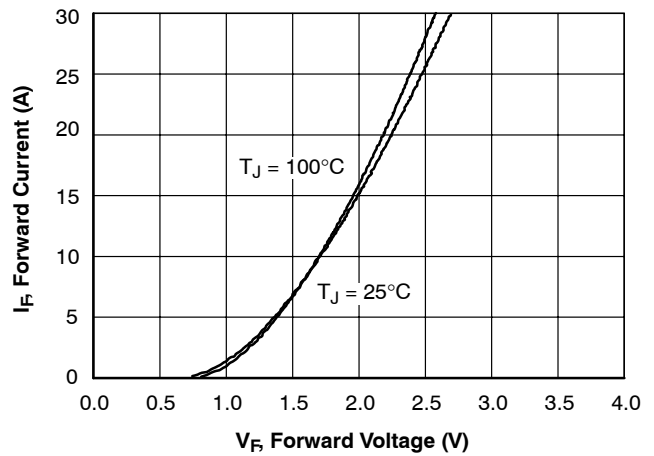


Figure 5. V_{F} versus I_{F} for Different Temperatures

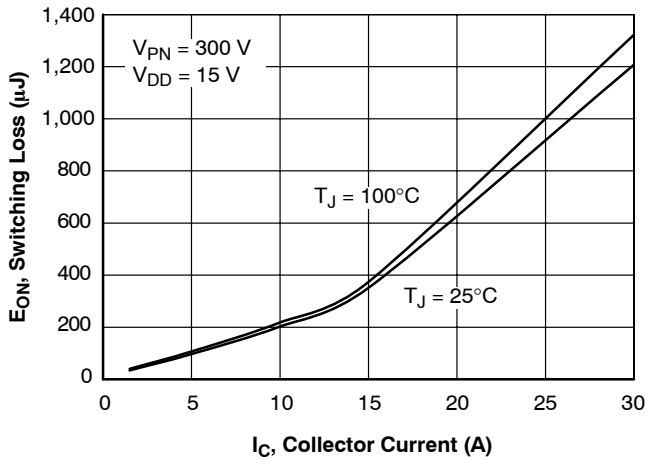


Figure 6. E_{ON} versus I_{C} for Different Temperatures

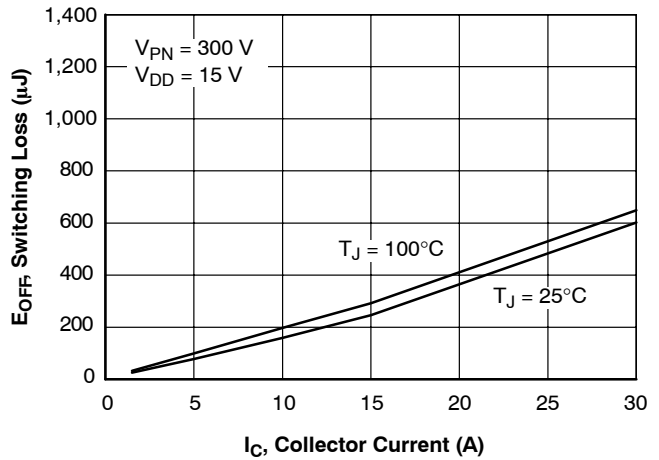


Figure 7. E_{OFF} versus I_{C} for Different Temperatures

TYPICAL CHARACTERISTICS (Continued)

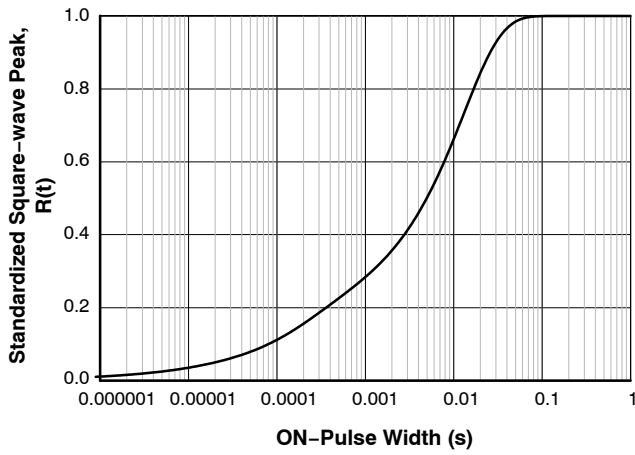


Figure 8. Thermal Impedance Plot (IGBT)

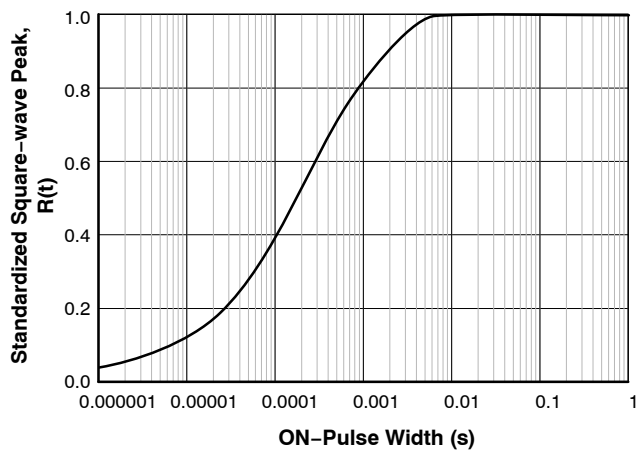


Figure 9. Thermal Impedance Plot (FRD)

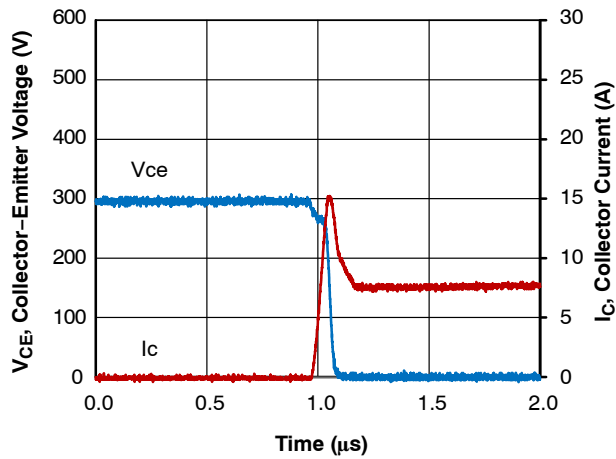


Figure 10. Turn-on Waveform $T_j = 100^\circ\text{C}$, $V_{CC} = 300\text{ V}$

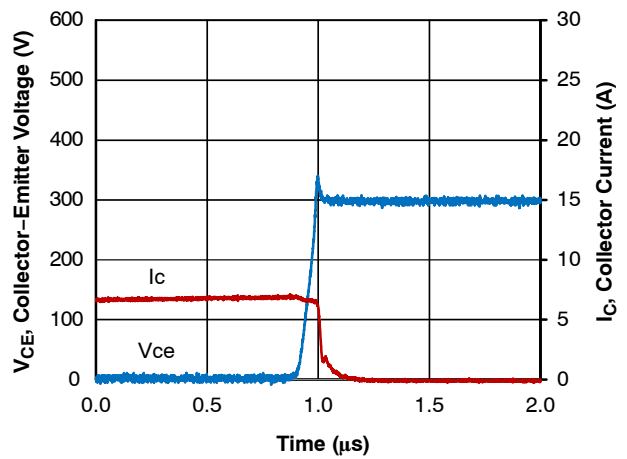
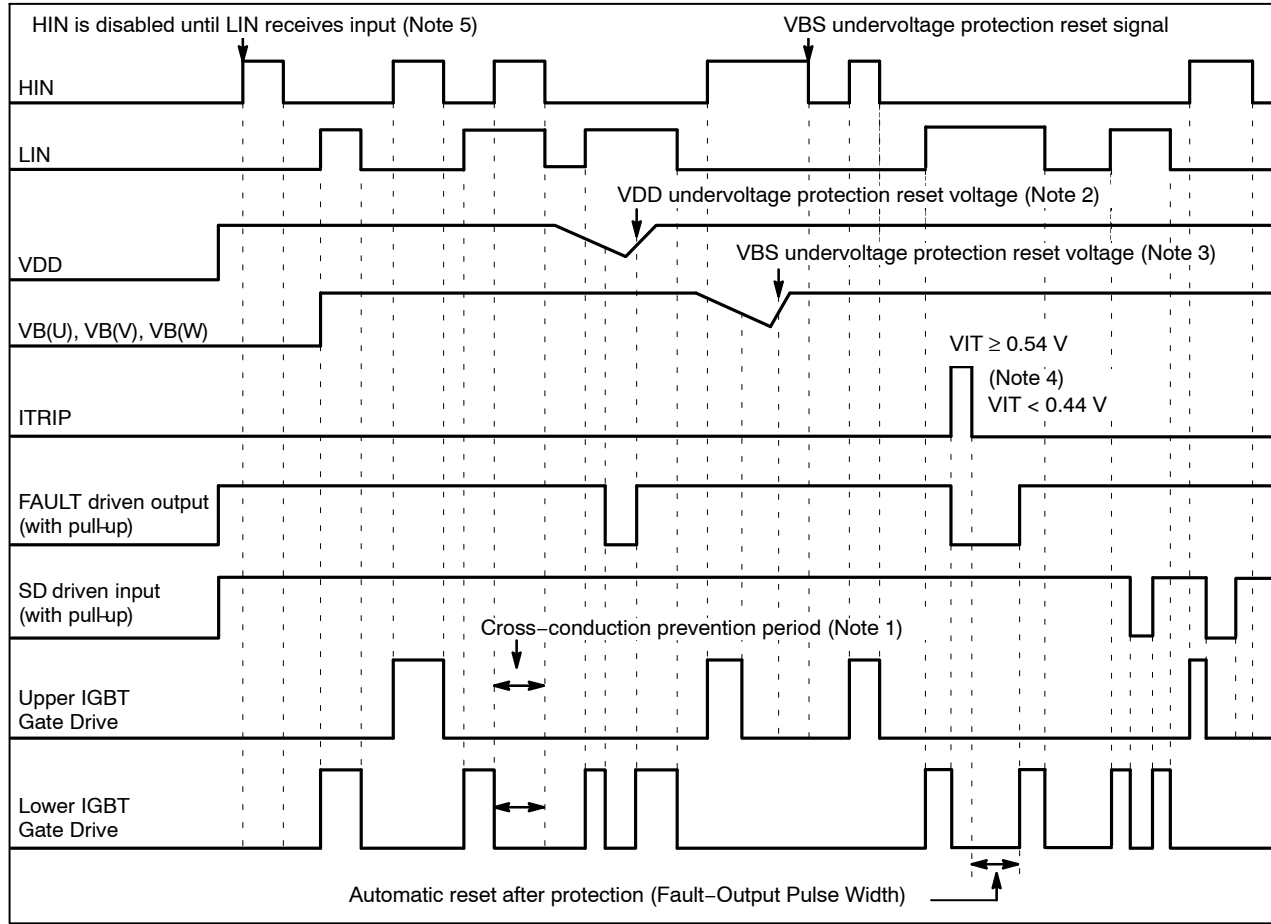


Figure 11. Turn-off Waveform $T_j = 100^\circ\text{C}$, $V_{CC} = 300\text{ V}$

APPLICATIONS INFORMATION

Input / Output Timing Chart



NOTES:

1. This section of the timing diagram shows the effect of cross-conduction prevention.
2. This section of the timing diagram shows that when the voltage on VDD decreases sufficiently all gate output signals will go low, switching off all six IGBTs. When the voltage on VDD rises sufficiently, normal operation will resume.
3. This section shows that when the bootstrap voltage on VB(U) (VB(V), VB(W)) drops, the corresponding high side output U (V, W) is switched off. When the voltage on VB(U) (VB(V), VB(W)) rises sufficiently, normal operation will resume.
4. This section shows that when the voltage on ITRIP exceeds the threshold, all IGBTs are turned off. Normal operation resumes later after the over-current condition is removed.
5. After VDD has risen above the threshold to enable normal operation, the driver waits to receive an input signal on the LIN input before enabling the driver for the HIN signal.

Figure 12. Input / Output Timing Chart

Table 1. INPUT / OUTPUT LOGIC TABLE

INPUT				OUTPUT			
HIN	LIN	ITRIP	SD	High side IGBT	Low side IGBT	U,V,W	FAULT
H	L	L	H	ON (Note 5)	OFF	P	OFF
L	H	L	H	OFF	ON	NU,NV,NW	OFF
L	L	L	H	OFF	OFF	High Impedance	OFF
H	H	L	H	OFF	OFF	High Impedance	OFF
X	X	H	X	OFF	OFF	High Impedance	ON
X	X	L	L	OFF	OFF	High Impedance	OFF

Table 2. THERMISTOR CHARACTERISTICS

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Resistance	R_{25}	$T_{th} = 25^{\circ}\text{C}$	99	100	101	$k\Omega$
	R_{100}	$T_{th} = 100^{\circ}\text{C}$	5.2	5.4	5.6	$k\Omega$
B-Constant (25 to 50°C)	B		4208	4250	4293	K
Temperature Range			-40	-	+125	$^{\circ}\text{C}$

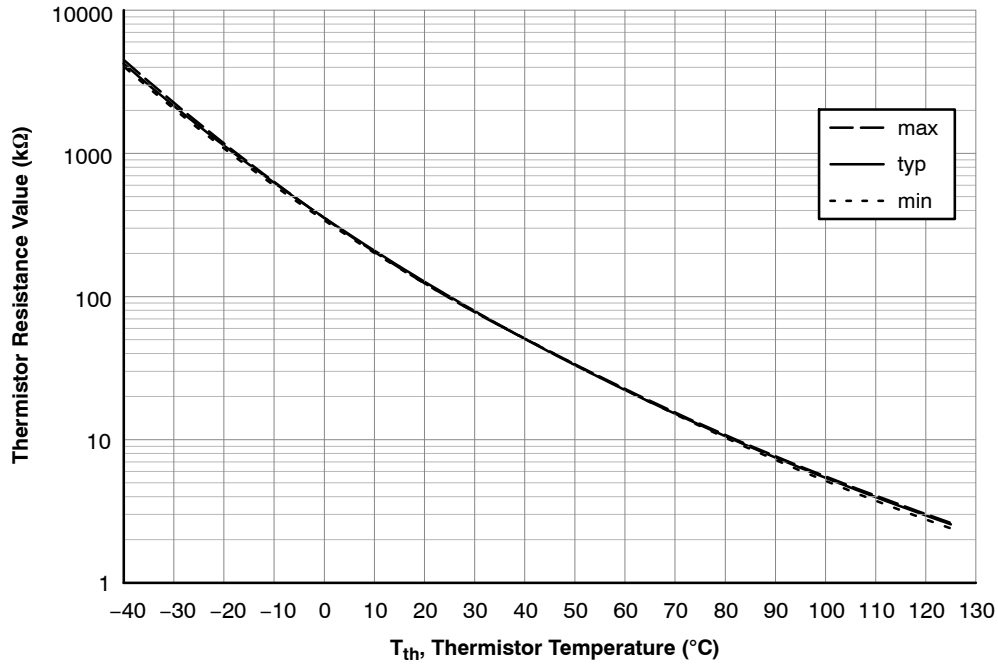


Figure 13. Thermistor Resistance versus Thermistor Temperature

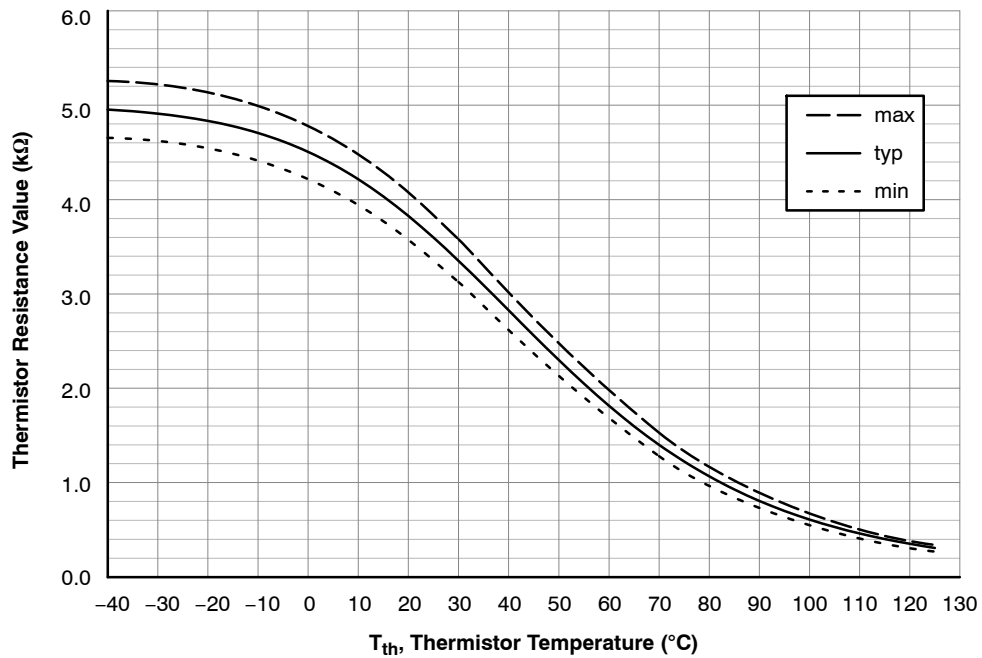


Figure 14. Thermistor Voltage versus Thermistor Temperature
Conditions: $R_{TH} = 39 k\Omega$, Pull-up Voltage 5.0 V (see Figure 2)

FAULT Pin

The FAULT output is an open drain output requiring a pull-up resistor. If the pull-up voltage is 5 V, use a pull-up resistor with a value of 6.8 kΩ or higher. If the pull-up voltage is 15 V, use a pull-up resistor with a value of 20 kΩ or higher. The FAULT output is triggered if there is a VDD undervoltage or an overcurrent condition.

Under-voltage Protection

If VDD goes below the VDD supply under-voltage lockout falling threshold, the FAULT output is switched on. The FAULT output stays on until VDD rises above the VDD supply under-voltage lockout rising threshold. After VDD has risen above the threshold to enable normal operation, the driver waits to receive an input signal on the LIN input before enabling the driver for the HIN signal.

Overcurrent Protection

An over-current condition is detected if the voltage on the ITRIP pin is larger than the reference voltage. There is a blanking time of typically 350 ns to improve noise immunity. After a shutdown propagation delay of typically 1.1 μs, the FAULT output is switched on. The FAULT output is held on for a time determined by the resistor and capacitor connected to the CFOD pin. If RCLR = 2 MΩ and CCLR = 1 nF, the FAULT output is switched on for 1.65 ms (typ.) because the FAULT pin goes back to high impedance when CFOD is higher than 8 V (typ.).

The over-current protection threshold should be set to be equal or lower to 2 times the module rated current (Io).

An additional fuse is recommended to protect against system level or abnormal over-current fault conditions.

Capacitors on High Voltage and VDD Supplies

Both the high voltage and VDD supplies require an electrolytic capacitor and an additional high frequency capacitor. The recommended value of the high frequency capacitor is between 100 nF and 10 μF.

SD Pin

The SD terminal pin is used to enable or shut down the built-in driver. If the voltage on the SD pin rises above the VSD+ voltage, the output drivers are enabled. If the voltage on the SD pin falls below the VSD- voltage, the drivers are disabled.

Minimum Input Pulse Width

When input pulse width is less than 1 μs, an output may not react to the pulse. (Both ON signal and OFF signal)

Calculation of Bootstrap Capacitor Value

The bootstrap capacitor value CB is calculated using the following approach. The following parameters influence the choice of bootstrap capacitor:

- VBS: Bootstrap power supply.
15 V is recommended.
- QG: Total gate charge of IGBT at VBS = 15 V.
8 nC.
- UVLO: Falling threshold for UVLO.
Specified as 12 V.
- IDMAX: High side drive power dissipation.
Specified as 0.4 mA.
- TONMAX: Maximum ON pulse width of high side IGBT.

Capacitance calculation formula:

$$CB = (QG + IDMAX * TONMAX) / (VBS - UVLO)$$

CB is recommended to be approximately 3 times the value calculated above. The recommended value of CB is in the range of 1 to 47 μF, however, the value needs to be verified prior to production. When not using the bootstrap circuit, each high side driver power supply requires an external independent power supply.

The internal bootstrap circuit uses a MOSFET. The turn on time of this MOSFET is synchronized with the turn on of the low side IGBT. The bootstrap capacitor is charged by turning on the low side IGBT.

If the low side IGBT is held on for a long period of time (more than one second for example), the bootstrap voltage on the high side MOSFET will slowly discharge.

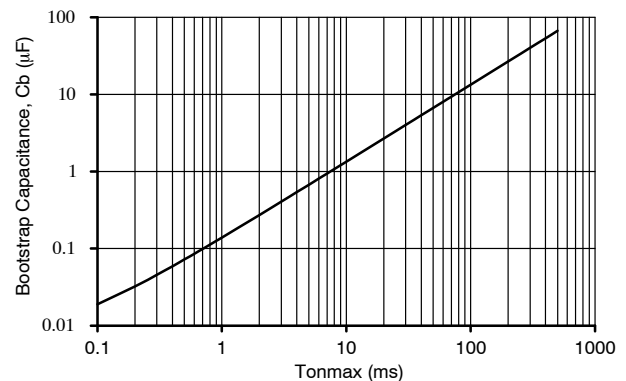


Figure 15. Bootstrap Capacitance versus Tonmax

TEST CIRCUITS

• ICES

	U+	V+	W+	U-	V-	W-
A	38	38	38	32	26	20
B	32	26	20	17	18	19

U+, V+, W+ : High side phase

U-, V-, W- : Low side phase

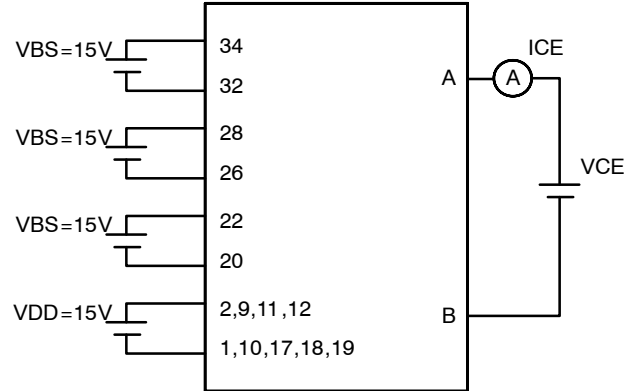


Figure 16. Test Circuit for I_{CE}

• $V_{CE(sat)}$ (Test by pulse)

	U+	V+	W+	U-	V-	W-
A	38	38	38	32	26	20
B	32	26	20	17	18	19
C	3	4	5	6	7	8

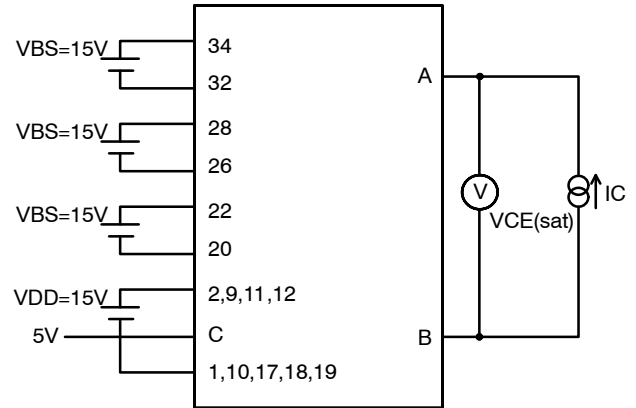


Figure 17. Test Circuit for $V_{CE(sat)}$

• V_F (Test by pulse)

	U+	V+	W+	U-	V-	W-
A	38	38	38	32	26	20
B	32	26	20	17	18	19

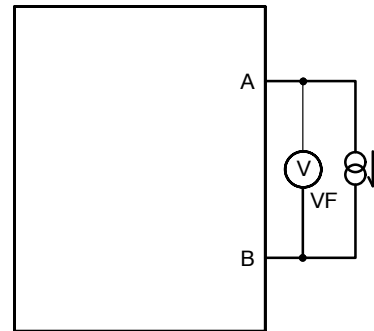


Figure 18. Test Circuit for V_F

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- RB (Test by pulse)

	U+	V+	W+
A	2	2	2
B	34	28	22
C	6	7	8

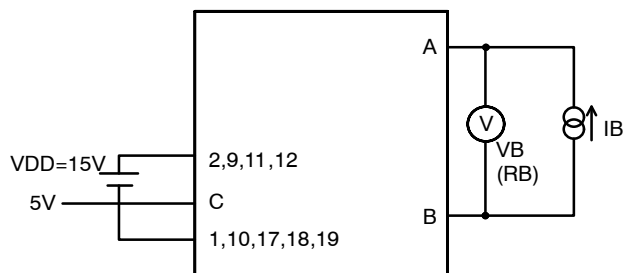


Figure 19. Test Circuit for RB

- IQBS, IQDD

	VBS U+	VBS V+	VBS W+	V _{DD}
A	34	28	22	2
B	32	26	20	1

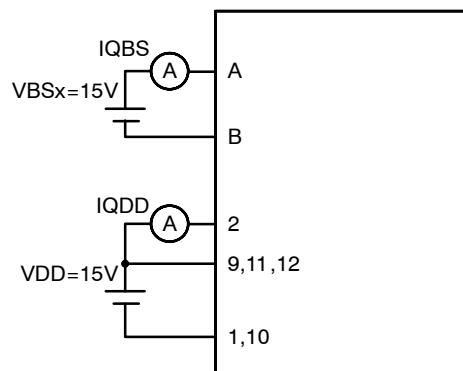


Figure 20. Test Circuit for I_D

- Switching Time (The circuit is a representative example of the Inverter Low side U phase.)

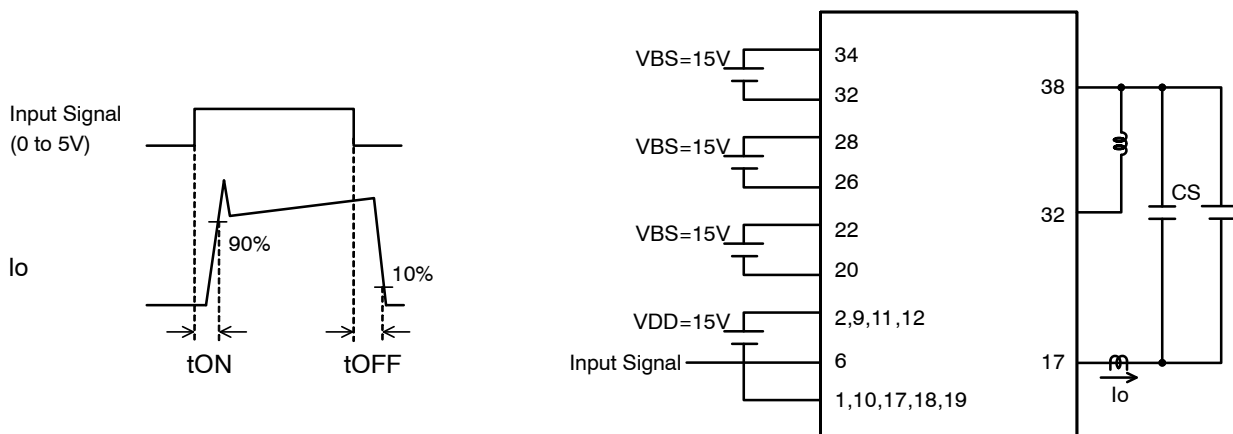
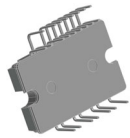
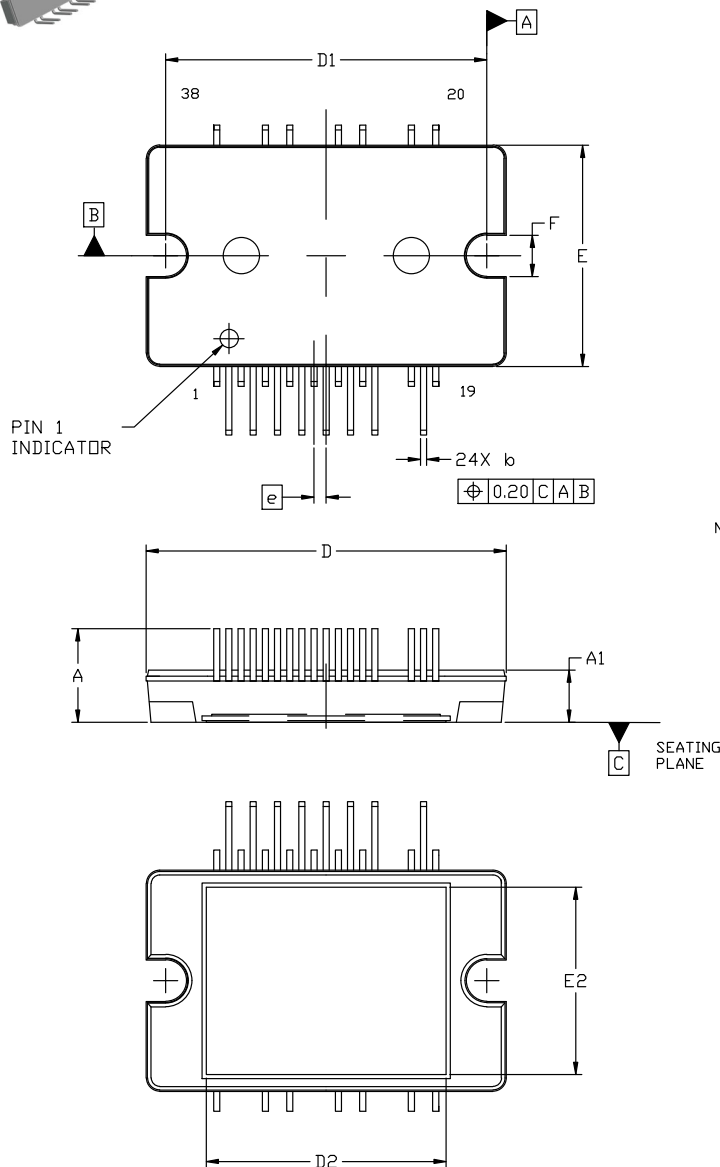


Figure 21. Test Circuit for Switching Time

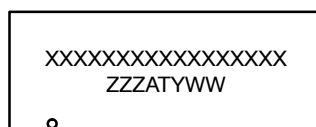

DIP38, 29.60x18.20x7.70, 1.00P (EP-4)
CASE 125BS
ISSUE B

DATE 26 APR 2023


NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 2009.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. DIMENSION b APPLIES TO THE PLATED LEAD AND IS MEASURED BETWEEN 0.10 AND 0.25 FROM THE LEAD TIP.
4. PACKAGE IS MISSING PINS: 15, 16, 21, 23, 24, 25, 27, 29, 30, 31, 33, 35, 36, AND 37.

DIM	MILLIMETERS		
	MIN.	NOM.	MAX.
A	7.20	7.70	8.20
A1	4.00	4.30	4.60
A2	3.10	3.40	3.70
b	0.40	0.50	0.60
c	0.35	0.40	0.60
D	29.10	29.60	30.10
D1	26.30	26.40	26.50
D2	19.20	19.70	20.20
E	17.70	18.20	18.70
E2	14.90	15.40	15.90
E3	19.50	20.00	20.50
E4	20.00	20.50	21.00
E5	3.50	4.00	4.50
e	1.00 BSC		
F	2.90	3.40	3.90
G	4°	5°	6°

GENERIC
MARKING DIAGRAM*


XXXX = Specific Device Code
 ZZZ = Lot ID
 AT = Assembly & Test Location
 Y = Year
 WW = Work Week

*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "•", may or may not be present. Some products may not follow the Generic Marking.

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