

Motion SPM[®] 5 Series FSB50550BB

General Description

The FSB50550BB is an advanced Motion SPM 5 module providing a fully-featured, high-performance inverter output stage for AC Induction, BLDC and PMSM motors. These modules integrate optimized gate drive of the built-in MOSFETs (FRFET® technology) to minimize EMI and losses, while also providing multiple on-module protection features including under-voltage lockouts and thermal monitoring. The built-in high-speed HVIC requires only a single supply voltage and translates the incoming logic-level gate inputs to the high-voltage, high-current drive signals required to properly drive the module's internal MOSFETs. Separate open-source MOSFET terminals are available for each phase to support the widest variety of control algorithms.

Features

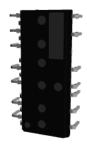
- Gate Driver Resistance $R_{ON} = 4.5 \text{ k}\Omega$, $R_{OFF} = 1.2 \text{ k}\Omega$
- Optimized for over 10 kHz Switching Frequency
- 500 V FRFET MOSFET 3-Phase Inverter with Gate Drivers and Protection
- Built-In Bootstrap Diodes Simplify PCB Layout
- Separate Open-Source Pins from Low-Side MOSFETs for Three-Phase Current-Sensing
- Active-HIGH Interface, Works with 3.3/5 V Logic, Schmitt-Trigger Input
- Optimized for Low Electromagnetic Interference
- HVIC Temperature-Sensing Built-In for Temperature Monitoring
- HVIC for Gate Driving and Under-Voltage Protection
- Isolation Rating: 1500 V_{rms}/min.
- This Device is Pb-Free and is RoHS Compliant

Applications

• 3-Phase Inverter Driver for Small Power AC Motor Drives

Related Source

- RD-FSB50450AS Reference Design for Motion SPM 5 Series Ver.2.
- AN-9082 Motion SPM5 Series Thermal Performance by Contact Pressure



SPM5T-021/21LD CASE MODET

MARKING DIAGRAM

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FSB50550BB ZKKXYY

FSB50550BB = Specific Device Code Z = Assembly Code

KK = Lot Run Traceability Code

XYY = Date Code

ORDERING INFORMATION

See detailed ordering and shipping information on page 2 of this data sheet.

ORDERING INFORMATION

Device	Device Marking	Package	Packing Type	Quantity
FSB50550BB	FSB50550BB	SPM5T-021 (Pb-Free)	Rail	15

ARSOLLITE MAYIMLIM BATINGS

Symbol	Parameter	Conditions	Rating	Unit
IVERTER PA	ART (Each MOSFET Unless Otherwise Specifie	d)	•	
V _{DSS}	Drain-Source Voltage of Each MOSFET		500	V
*I _{D 25}	Each MOSFET Drain Current, Continuous	T _C = 25°C	3.0	Α
*I _{D 80}	Each MOSFET Drain Current, Continuous	T _C = 80°C	1.9	Α
*I _{DP}	Each MOSFET Drain Current, Peak	T _C = 25°C, PW < 100 μs	7.0	Α
*I _{DRMS}	Each FRFET Drain Current, Rms	T _C = 80°C, F _{PWM} < 20 kHz	1.3	A _{rms}
ONTROL PA	RT (Each HVIC Unless Otherwise Specified)			
V_{DD}	Control Supply Voltage	Applied Between V _{DD} and COM	20	V
V_{BS}	High-side Bias Voltage	Applied Between V _B and V _S	20	V
V _{IN}	Input Signal Voltage	Applied Between IN and COM	-0.3~V _{DD} + 0.3	V
OOTSTRAP	DIODE PART (Each Bootstrap Diode Unless O	therwise Specified.)		
V_{RRMB}	Maximum Repetitive Reverse Voltage		500	V
* I _{FB}	Forward Current	T _C = 25°C	0.5	Α
* I _{FPB}	Forward Current (Peak)	T _C = 25°C, Under 1 ms Pulse Width	2.0	Α
HERMAL RE	SISTANCE			
$R_{th(j-c)Q}$	Junction to Case Thermal Resistance (Note 1)	Each FET under inverter operating condition (Note 1)	8.9	°C/W
OTAL SYSTE	ЕМ			
T _J	Operating Junction Temperature		-40~150	°C
T _{STG}	Storage Temperature		-40~125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, 1 minute, Connect Pins to Heat Sink Plate	1500	V _{rms}

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected. NOTES:

- For the measurement point of case temperature T_C, Please refer to Figure 4.
 Marking "*" is calculation value or design factor.

PIN DESCRIPTIONS

Pin No.	Pin Name	Pin Description
1	COM	IC Common Supply Ground
2	V _{B(U)}	Bias Voltage for U-Phase High-Side MOSFET Driving
3	V _{DD(U)}	Bias Voltage for U-Phase IC and Low-Side MOSFET Driving
4	IN _(UH)	Signal Input for U-Phase High-Side
5	IN _(UL)	Signal Input for U-Phase Low-Side
6	N.C	No Connection
7	V _{B(V)}	Bias Voltage for V-Phase High Side MOSFET Driving
8	V _{DD(V)}	Bias Voltage for V-Phase IC and Low Side MOSFET Driving
9	IN _(VH)	Signal Input for V-Phase High-Side
10	IN _(VL)	Signal Input for V-Phase Low-Side
11	N.C	No Connection
12	V _{B(W)}	Bias Voltage for W-Phase High-Side MOSFET Driving
13	V _{DD(W)}	Bias Voltage for W-Phase IC and Low-Side MOSFET Driving
14	IN _(WH)	Signal Input for W-Phase High-Side
15	IN _(WL)	Signal Input for W-Phase Low-Side
16	V _{TS}	Output for HVIC Temperature Sensing
17	Р	Positive DC-Link Input
18	U, V _{S(U)}	Output for U-Phase & Bias Voltage Ground for High-Side MOSFET Driving
19	N _U	Negative DC-Link Input for U-Phase
20	N _V	Negative DC-Link Input for V-Phase
21	V, V _{S(V)}	Output for V-Phase & Bias Voltage Ground for High-Side MOSFET Driving
22	N _W	Negative DC-Link Input for W-Phase
23	W, V _{S(W)}	Output for W Phase & Bias Voltage Ground for High-Side MOSFET Driving

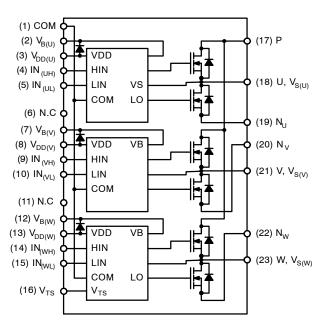


Figure 1. Pin Configuration and Internal Block Diagram (Bottom View)

NOTE:

3. Source terminal of each low-side MOSFET is not connected to supply ground or bias voltage ground inside Motion SPM 5 product. External connections should be made as indicated in Figure 3.

Symbol	Parameter	V _{DD} = V _{BS} = 15 V Unless Otherwise Specified.) Test Conditions			Тур.	Max.	Unit		
	I R PART (Each MOSFET Unless Otherwise			Min.		<u>.</u>			
BV _{DSS}	Drain – Source Breakdown Voltage	V _{IN} = 0 V, I _D = 1 mA (Note 4)			_	_	V		
I _{DSS}	Zero Gate Voltage Drain Current	V _{IN} = 0 V, V _{DS} = 500 V			_	1	mA		
R _{DS(on)}	Static Drain – Source Turn–On			_	2.3	3.0	Ω		
T DS(on)	Resistance	VDD = VBS = 10 V, VIIV	$V_{DD} = V_{BS} = 15 \text{ V}, V_{IN} = 5 \text{ V}, I_D = 1.2 \text{ A}$		2.0	0.0	55		
V _{SD}	Drain – Source Diode Forward Voltage	$V_{DD} = V_{BS} = 15 \text{ V}, V_{IN}$	_I = 0 V, I _D = -1.2 A	_	-	1.3	V		
t _{ON}	Switching Times	V_{PN} = 300 V, V_{DD} = V_{BS} = 15 V, I_{D} = 1.2 A V_{IN} = 0 V \leftrightarrow 5 V, Inductive Load L = 3 mH		460	780	1100	ns		
t _{OFF}		High- and Low-Side I		1001	1660	2300	ns		
t _{rr}	1	(Note 5)		_	230	-	ns		
E _{ON}	1			-	69	-	μJ		
E _{OFF}	1			-	17	-	μJ		
RBSOA	Reverse Bias Safe Operating Area	V _{DS} = BV _{DSS} , T _J = 15 High- and Low-Side	V_{PN} = 400 V, V_{DD} = V_{BS} = 15 V, I_{D} = I_{DP} , V_{DS} = BV_{DSS} , T_{J} = 150°C High- and Low-Side MOSFET Switching (Note 6)			Full Square			
	L PART (Each HVIC Unless Otherwise Spe	<u>, </u>	T		1	1	I .		
I _{QDD}	Quiescent V _{DD} Current	V _{DD} = 15 V, V _{IN} = 0 V	Applied between V _{DD} and COM	-	-	200	μΑ		
I _{QBS}	Quiescent V _{BS} Current	V _{BS} = 15 V, V _{IN} = 0 V	$ \begin{array}{c} \text{Applied between } V_{B(U)} - U, \\ V_{B(V)} - V, V_{B(W)} - W \end{array} $	-	-	100	μΑ		
I _{PDD}	Operating V _{DD} Supply Current	V _{DD} – COM	V _{DD} = 15 V, f _{PWM} = 20 kHz, duty = 50%, Applied to One PWM Signal Input for Low–Side	-	_	900	μΑ		
I _{PBS}	Operating V _{BS} Supply Current	$ \begin{aligned} &V_{B(U)} - V_{S(U)}, \\ &V_{B(V)} - V_{S(V)}, \\ &V_{B(W)} - V_{S(W)} \end{aligned} $	$\begin{split} &V_{DD} = V_{BS} = 15 \text{ V,} \\ &f_{PWM} = 20 \text{ kHz,} \\ &\text{Duty} = 50\%, \text{ Applied to} \\ &\text{One PWM Signal Input} \\ &\text{for High-Side} \end{split}$	1	-	800	μΑ		
UV _{DDD}	Low-Side Under-Voltage Protection	V _{DD} Under-Voltage P	rotection Detection Level	7.4	8.0	9.4	V		
UV _{DDR}	(Figure 8)	V _{DD} Under-Voltage Protection Reset Level		8.0	8.9	9.8	V		
UV _{BSD}	High-Side Under-Voltage Protection	V _{BS} Under-Voltage Protection Detection Level		7.4	8.0	9.4	V		
UV _{BSR}	(Figure 9)	V _{BS} Under-Voltage Pi	rotection Reset Level	8.0	8.9	9.8	V		
V _{TS}	HVIC Temperature Sensing Voltage Output	V _{DD} = 15 V, T _{HVIC} = 2	V _{DD} = 15 V, T _{HVIC} = 25°C (Note 7)		790	980	mV		
V _{IH}	ON Threshold Voltage	Logic HIGH Level	Applied between V _{IN} and	-	-	2.9	V		
V _{IL}	OFF Threshold Voltage	Logic LOW Level	COM	0.8	-	-	V		
R _{ON}	Gate Driver ON Output Resistance		1		4.5	5.4	kΩ		
R _{OFF}	Gate Driver OFF Output Resistance			0.96	1.2	1.44	kΩ		
	RAP DIODE PART (Each Bootstrap Diode		ed)		•	•			
V_{FB}	Forward Voltage	I _F = 0.1 A, T _C = 25°C	(Note 8)	-	2.5	-	V		
t _{rrB}	Reverse Recovery Time	I _F = 0.1 A, T _C = 25°C			80	_	ns		
	<u>I</u>	1		1	1				

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

RECOMMENDED OPERATING CONDITION

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
V_{PN}	Supply Voltage	Applied between P and N	_	300	400	V
V_{DD}	Control Supply Voltage	Applied between V _{DD} and COM	13.5	15.0	18.5	V
V _{BS}	High-Side Bias Voltage	Applied between V _B and V _S	13.5	15.0	18.5	V
V _{IN(ON)}	Input ON Threshold Voltage	Applied between V _{IN} and COM	3.0	_	V_{DD}	V
V _{IN(OFF)}	Input OFF Threshold Voltage		0	_	0.6	V
t _{dead}	Blanking Time for Preventing Arm-Short	V _{DD} = V _{BS} = 13.5~16.5 V, T _J ≤ 150°C	2	_	-	μs
		$V_{DD} = V_{BS} = 12.3 \sim 14.4 \text{ V}, T_J \le 150 ^{\circ}\text{C}$	1	_	-	μs
f _{PWM}	PWM Switching Frequency	T _J ≤ 150°C	-	15	-	kHz

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

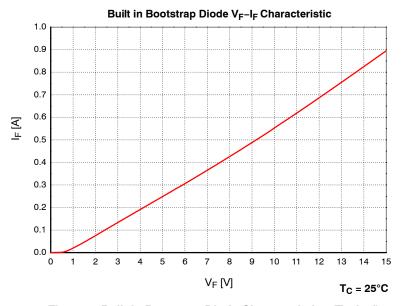


Figure 2. Built in Bootstrap Diode Characteristics (Typical)

NOTES:

- 4. BV_{DSS} is the absolute maximum voltage rating between drain and source terminal of each MOSFET inside Motion SPM 5 product. V_{PN} should be sufficiently less than this value considering the effect of the stray inductance so that V_{PN} should not exceed BV_{DSS} in any case.
- 5. t_{ON} and t_{OFF} include the propagation delay of the internal drive IC. Listed values are measured at the laboratory test condition, and they can be different according to the field applications due to the effect of different printed circuit boards and wirings. Please see Figure 6 for the switching time definition with the switching test circuit of Figure 7.
- 6. The peak current and voltage of each MOSFET during the switching operation should be included in the Safe Operating Area (SOA). Please see Figure 7 for the RBSOA test circuit that is same as the switching test circuit.
- 7. Vts is only for sensing-temperature of module and cannot shutdown MOSFETs automatically.
- 8. Built in bootstrap diode includes around 15 Ω resistance characteristic. Please refer to Figure 2.

These values depend on PWM control algorithm * Example Circuit: V phase +15 V HIN LIN Output Note VDD VΒ Inverte 0 0 Ζ Both FRFET Off Output HIN НΩ 0 0 Low side FRFET Or MCU LIN VS High side FRFET On 1 0 V_{DC} C_3 СОМ LO Forbidden Shoot through 1 1 Open Open Same as (0,0) One Leg Diagram of Motion SPM 5 Product 10 * Example of Bootstrap Parameters $C_1 = C_2 = 1 \mu F$ Ceramic Capacitor

Figure 3. Recommended MCU Interface and Bootstrap Circuit with Parameters

NOTES:

- Parameters for bootstrap circuit elements are dependent on PWM algorithm. For 15 kHz of switching frequency, typical example of parameters is shown above.
- 10. RC-coupling (R₅ and C₅) and C₄ at each input of Motion SPM and MCU (Indicated as Dotted Lines) may be used to prevent improper signal due to surge-noise.
- 11. Bold lines should be short and thick in PCB pattern to have small stray inductance of circuit, which results in the reduction of surge-voltage. Bypass capacitors such as C₁, C₂ and C₃ should have good high-frequency characteristics to absorb high-frequency ripple-current.

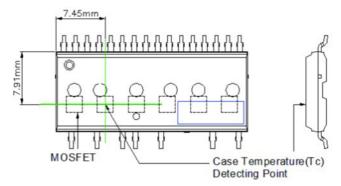


Figure 4. Case Temperature Measurement

NOTE:

12. Attach the thermocouple on top of the heat-sink of SPM 5 package (between SPM 5 package and heatsink if applied) to get the correct temperature measurement.

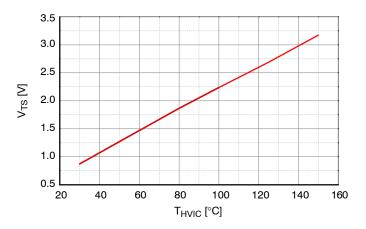


Figure 5. Temperature Profile of V_{TS} (Typical)

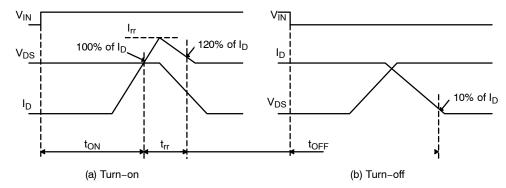


Figure 6. Switching Time Definitions

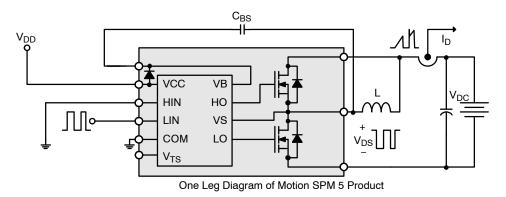


Figure 7. Switching and RBSOA (Single-Pulse) Test Circuit (Low-side)

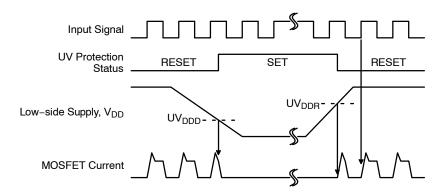


Figure 8. Under-Voltage Protection (Low-Side)

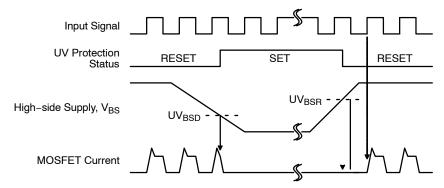


Figure 9. Under-Voltage Protection (High-Side)

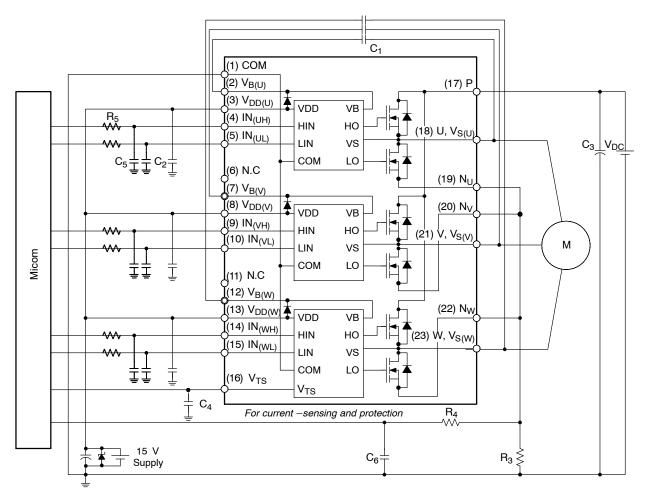


Figure 10. Example of Application Circuit

NOTES:

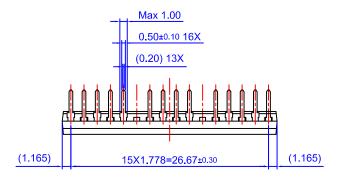
- 13. About pin position, refer to Figure 1.
- 14. RC-coupling (R₅ and C₅, R₄ and C₆) and C₄ at each input of Motion SPM 5 product and MCU are useful to prevent improper input signal caused by surge-noise.
- 15. The voltage–drop across R₃ affects the low–side switching performance and the bootstrap characteristics since it is placed between COM and the source terminal of the low–side MOSFET. For this reason, the voltage drop across R₃ should be less than 1 V in the steady–state.
- 16. Ground-wires and output terminals, should be thick and short in order to avoid surge-voltage and malfunction of HVIC.
- 17. All the filter capacitors should be connected close to Motion SPM 5 product, and they should have good characteristics for rejecting high-frequency ripple current.

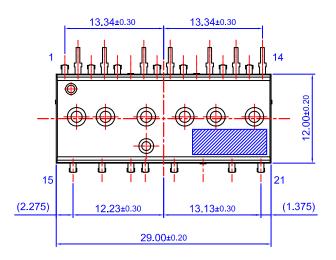
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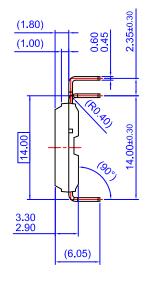


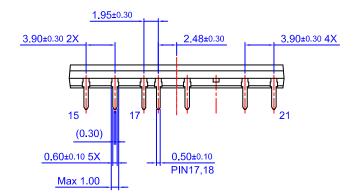
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