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NCP4318 Tips and Tricks AND90154/D

LLC converter is a popular isolated dc-dc power conversion topology for high power applications. The primary-side winding of the transformer in LLC converter sees an ac current of the resonant tank. In lower output voltage scenarios, center-tapped windings are used for the secondary side of the transformer. Two diodes are used to rectify the output current of the secondary windings. To improve conversion efficiency of the LLC converter, people use a synchronous rectification (SR) technique on the output rectifying diodes. Synchronous rectification means using power transistors to replace the diodes. Within the diode conduction time duration, turn on the power transistor to replace the diode's conduction role. It takes the advantage of the on-resistance voltage drop of the power transistor being lower than forward voltage drop of the diodes, thanks to the low on-resistance $R_{DS(ON)}$ of modern power transistors, such as power MOSFETs.

NCP4318 is a synchronous rectification controller dedicated for LLC converters. Figure 1 shows a typical application circuit of NCP4318. It senses the voltage across drain and source pins of the SR MOSFETs through two sets of VD and VS pins. An R_{OFFSET} is placed in series of each VD and drain pin connection. NCP4318 has two VG pins to drive the respective SR MOSFET when its body diode can be forward biased. VDD of NCP4318 can be supplied by voltage not higher than 37 V, so the output voltage of the LLC converter can be directly used as NCP4318's power supply. Thus, NCP4318 can control the SR MOSFETs with very low external part counts.

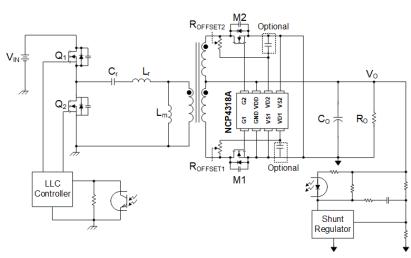
NCP4318 data sheet [1] had introduced basic operation principle of this controller. This application note provides further explanation for its practical operation in different scenarios.

Drain Voltage of SR MOSFETs

Figure 2 shows an example of the secondary-side currents and voltage waveform of SR MOSFETs. When the current in the L_r and L_m of the primary side of the LLC converter diverts from each other, the difference between them becomes the current transferred to the secondary side. Whatever MOSFET or the body diode conducts the secondary-side current, Figure 2 notes the current as I_{SD}, as the current is flowing from source to drain terminal of the SR MOSFET. When the current flows through M1, V_{DS} of M1 pulls low. If M2 conducts the secondary-side current, V_{DS} of M1 shows V_{OUT} plus reflected voltage from the transformer winding, which makes the voltage amplitude roughly two times of V_{OUT}.

In a below-resonant operation of the LLC converter, there is a duration that no current is transferred from the primary to the secondary side. The capacitor across the drain and source terminals of the two SR MOSFETs resonates with the equivalent L_r reflected to the secondary side, making a sub-resonance as in Figure 2.

Zooming in the V_{DS} and I_{SD} waveform when the I_{SD} current conducts, we get a waveform as shown in Figure 3. The body diode of the SR MOSFET conducts first and then NCP4318 generates gate signal, VG, making the SR MOSFET turned on. The amplitude of V_{DS} change from the forward voltage of the body diode to the voltage drop across the MOSFET's on-resistance. Thus, the conduction loss of the secondary-side current on the rectifying device, which means diodes, can be reduced. The gate signal will be turned off before the I_{SD} current drop to zero. The time interval between gate turning off and current dropping to zero is the dead time of the SR gate signal.





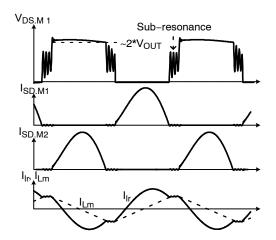


Figure 2. Typical SR Current and Voltage Waveforms of a Below-resonant LLC Converter

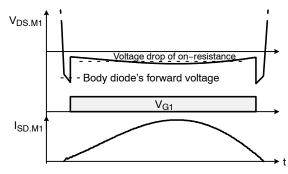


Figure 3. Zoomed-in Waveform of SR Current and Voltage

Dead Time Regulation and V_{TH-OFF} Range

Figure 4 (a) shows an ideal operating scenario of the SR MOSFET in LLC converters. When the body diode of the SR MOSFET conducts, voltage across its drain and source terminals, V_{DS} , goes negative. Its amplitude is the forward voltage of the body diode. NCP4318 senses the V_{DS} to turn on the SR MOSFET when the measured V_{DS} is lower than a turn-on threshold voltage noted as V_{TH-ON} in the figure. Since turned on the SR MOSFET, V_{DS} shows the voltage drop on the R_{DS-ON}. As the source-to-drain current I_{SD} drops, V_{DS} rise to a value close to 0 mV, and NCP4318 turns off the SR MOSFET based on a turn-off threshold voltage V_{TH-OFF} . Then, I_{SD} conducts via body diode for the remaining duration of non-zero I_{SD}.

In practical scenarios, there are parasitic inductance everywhere in the current conducting path. Even if two separate pins are used to sense the differential voltage V_{DS} ,

stray inductance can still be found in the short PCB trace and the MOSFET package. The stray inductance generates a voltage difference V_{LS} when amplitude of the flowing-through current changes. The sensed V_{DS} becomes a summation of V_{LS} and $-I_{SD} \cdot R_{DS(ON)}$. When I_{SD} drops, V_{LS} becomes positive, which raises V_{DS} voltage and makes the SR controller turn off the SR MOSFET prematurely, as shown in Figure 4 (b).

To overcome the premature turn-off phenomenon, NCP4318 has a range of adjustable V_{TH-OFF} levels and it can adjust the V_{TH-OFF} by optimizing its turning-off instant and adjusts the V_{TH-OFF} to regulate the dead time. For avoiding overreaction of the V_{TH-OFF} adjustment, the optimized dead time is defined as a hysteresis band. NCP4318 adjusts V_{TH-OFF} higher for the dead time being longer than $t_{DEAD-HBAND}$ and lower for the dead time being shorter than $t_{DEAD-HBAND}$. More, the V_{TH-OFF} is adjusted with high resolution by the combination of V_{TH-OFF} and I_{OFFSET} . These are depicted in Figures 6 and 7.

The I_{OFFSET} and R_{OFFSET} changes the V_{DS} detected in the VD and VS pins, making the turn-off criterion become

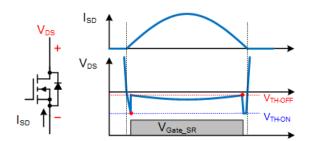
$$V_{DS} + I_{OFFSET} \cdot R_{OFFSET} - V_{TH-OFF} = 0.$$
 (eq. 1)

So, we can define a virtual V_{TH-OFF} as a combination of V_{TH-OFF} and I_{OFFSET} 's effects as

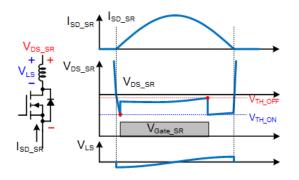
Virtual
$$V_{TH-OFF} = V_{TH-OFF} - R_{OFFSET} \cdot I_{OFFSET}$$
.
(eq. 2)

With both V_{TH-OFF} and I_{OFFSET} as variables, V_{TH-OFF} is defined as larger step and I_{OFFSET} is defines as smaller step of the adjustment of the virtual V_{TH-OFF}. Both of them are controlled by 5-bit digital numbers, so there are totally 1024 variations of the combination. Stepping down of the virtual V_{TH-OFF} can happen in every switching cycle for a fast response. However, stepping up of the virtual V_{TH-OFF} needs 128 consecutive switching cycles having t_{DEAD} > t_{DEAD-HBAND}. This is for avoiding too fast dead time reduction that may interfere the feedback loop of LLC control.

 I_{OFFSET} varies between 0 and 310 µA, and NCP4318 has two different step size for V_{TH-OFF} . To make the IOFFSET ROFFSET fill the step size of V_{TH-OFF}, the recommended R_{OFFSET} value is 30 Ω for $V_{TH-OFF-STEP} = 8$ mV and 15 Ω for $V_{TH-OFF-STEP} = 4$ mV. More, except the $V_{TH-OFF-STEP}$ options, NCP4318 also has two different options for $V_{TH-OFF-MIN}$. $V_{TH-OFF-MIN}$ and $V_{TH-OFF-STEP}$ defines the variable range of V_{TH-OFF} . Larger $V_{TH-OFF-STEP}$ leads to higher $V_{TH-OFF-MAX}$.



a) Without Stray Inductance



a) With Stray Inductance

Figure 4. Effect of Stray Inductance on V_{DS}

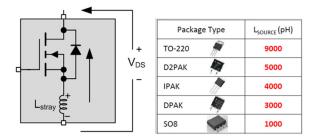


Figure 5. Stray Inductance of the MOSFET Package

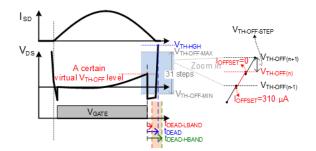


Figure 6. Hysteresis Band of Dead Time Regulation by Adjusting the Virtual V_{TH-OFF}

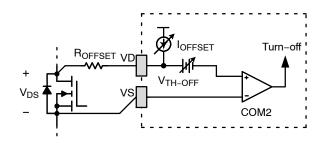


Figure 7. I_{OFFSET} and the Virtual V_{TH-OFF}

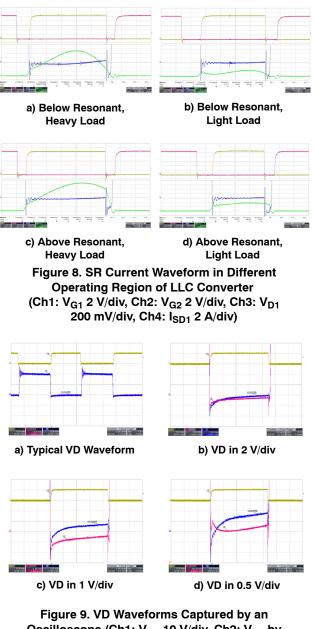
$$V_{TH-OFF-MAX} = V_{TH-OFF-MIN} + 31 \cdot V_{TH-OFF-STEP}$$
 (eq. 3)

Wider range of V_{TH-OFF} may be required when the stray inductance of the SR MOSFET is higher, such as with TO-220 package, or the LLC is operating in below-resonant region mostly. When the LLC converter operates in below-resonant region, as in Figure 8 (a) and (b), variation in current slope tends to be larger. Thus, the effect of stray inductance on V_{DS} becomes stronger. If the variable range of V_{TH-OFF} is not large enough, the dead time will be larger in heavy load condition. It is due to saturation of the adjustable V_{TH-OFF} range; the required V_{TH-OFF} for the wanted dead time is higher than $V_{TH-OFF-MAX}$. So, when the dead time is well regulated in light-load conditions and becomes too large in heavy-load conditions, look for $V_{TH-OFF-STEP} = 8$ mV IC option, which provides higher $V_{TH-OFF-MAX}$.

Inspecting VD Waveform on Oscilloscope

The operation of NCP4318 is based on detecting the voltage across drain and source terminals of SR MOSFETs to decide whether the VG signal should be high or low. For an LLC converter with 19.5 V of output voltage, typical VD waveform is like Figure 9 (a) and has an amplitude of around 40 V, but the portion of interest for VD waveform during the SR operation is in the range of $-1\sim1$ V.

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Oscilloscope (Ch1: V_{G1} 10 V/div, Ch2: V_{D1} by Standard Probe, Ch3: V_{D1} by Differential Probe)

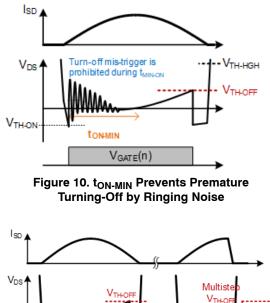
When you try to check VD waveform in the range of interest for NCP4318 by oscilloscope, some non-ideal waveform may be captured due to oscilloscope's characteristics. In the Figure 9, channel #2 and #3 are capturing the same VD signal with different probes. Channel #2 is with standard 10x probe and channel #3 uses a differential probe set at 1/20 of signal ratio. Comparing Figure 9 (b) and (c) for the y-axis zoom-in of the VD signal around 0 V, the shape of VD is slightly different between two kinds of probes. Also, when the voltage scale changes, DC offset of the signal may also change. In Figure 9 (d), the waveform captured by the standard 10x probe is even distorted in its wave shape.

Overall, the waveform captured by differential probes shows a much correct wave shape, but the oscilloscope may introduce some voltage offset at different voltage scale according to the oscilloscope's characteristics. Inspecting the behavior of SR controller by capturing VD signal has no problem but capturing threshold voltage like V_{TH-OFF} may not be easy in an operating LLC converter.

Minimum On-Time and Multi-Step V_{TH-OFF}

When SR gate is turning on, V_{DS} may show ringing due to parasitic components. NCP4318 has a minimum on-time (t_{ON-MIN}) to avoid premature gate turning off by the parasitic ringing.

In a load-transient condition under above-resonant operation, the SR conduction time may reduce a lot in consecutive cycles. NCP4318 has a multi-step V_{TH-OFF} to deal with sudden reduction on the SR conduction time. The multi-step V_{TH-OFF} means to have lowered V_{TH-OFF} in a time duration defined as $K_{2ND-TOFF}$.



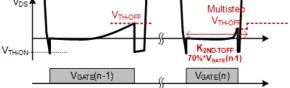
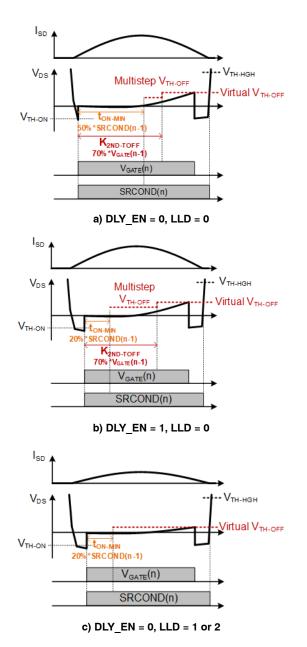


Figure 11. Multistep V_{TH-OFF} Turns Off SR GATE Earlier when SR Conducting Duration Reduces

Both t_{ON-MIN} and $K_{2ND-TOFF}$ response to operating information of its previous switching cycle, making them adaptive to operating conditions. The t_{ON-MIN} refers to a SRCOND signal, and $K_{2ND-TOFF}$ refers to gate on-time. More, t_{ON-MIN} and $K_{2ND-TOFF}$ change according to operating-mode flags DLY_EN and LLD respectively. Definition and variation of SRCOND, t_{ON-MIN} , and $K_{2ND-TOFF}$ under different operating modes of NCP4318 are depicted in Figure 12.





Leading-Edge Inversion Current and t_{ON-DLY2}

For an LLC converter operating in below-resonant region and light-load condition, current may conduct two times in one switching cycle for a rectifier branch. This phenomenon had been explained in [2] as capacitive current. The main reason is that the amplitude of the C_r voltage is not enough, so the Lr current doesn't built up at the beginning of the primary-side However, on time. the COSS charging/discharging during the switching transition make the SR MOSFET's body diode conducts for a short period. If SR MOSFET turns on in the short period, it results in leading-edge inversion current in the SR MOSFET conducting duration, which makes additional conduction loss.

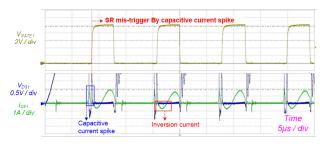


Figure 13. Leading-edge Inversion Current

When the leading-edge inversion current happens, the current inversion detection function SRCINV will be triggered once. Then, turning-on criterion of VG1 and VG2 become requiring VD1 and VD2 to be lower than V_{TH-ON} continuously for a $t_{ON-DLY2}$ duration. To avoid conducting inversion current, the $t_{ON-DLY2}$ needs to be longer than the discharging time of the capacitive current and period of the following sub-resonance.

NCP4318 offers various $t_{ON-DLY2}$ options from 240 ns to 1580 ns. For an LLC converter operating in above-resonant region, $t_{ON-DLY2}$ doesn't need to be too long. It may still work in below-resonant region during its input bulk voltage hold-up time during power-off, which is usually a heavy-load condition. However, when an LLC converter can operate in below-resonant region with light load condition, longer $t_{ON-DLY2}$ may be required for avoiding the leading-edge inversion current.

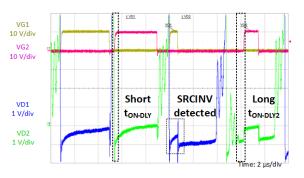
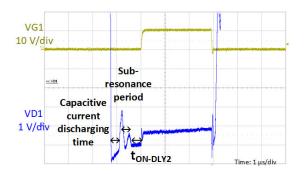


Figure 14. ton-DLY Changing Instant





SRCINV makes turning-on delay time as the longer $t_{ON-DLY2}$, instead of a short t_{ON-DLY} . To recover back to the short t_{ON-DLY} , NCP4318 inspects V_D waveform before SR gate turning on. If V_D crosses below V_{TH-ON} for only one time, a $\eta_{INV-EXT}$ counter adds by one. This counter resets when the V_D < V_{TH-ON} event happens more than one time in one switching cycle. When the $\eta_{INV-EXT}$ counter has reached 16000, the criterion of turning on the SR gain recovers back to t_{ON-DLY} , which is simply a propagation delay. It can also be witnessed in Figure 16 that the recovering from $t_{ON-DLY2}$ of one channel is independent from the other channel.

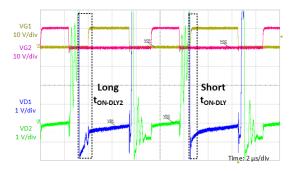


Figure 16. Recovering from the Long t_{ON-DLY2}

Soft Start and VDD Connection

Although the steady-state operation of an LLC converter is pulse-frequency modulation (PFM) with designed frequency range, different LLC controllers may have different process of initiating its switching operating after power on. After V_{DD} exceeds $V_{DD-GATE-ON}$, NCP4318 counts switching cycle of the LLC converter and skips the SR gate output for the first 256 cycles to avoid any unpredicted behavior from the LLC controller. V_{DD} of NCP4318 can be connected to V_{OUT} or an auxiliary power source. With different connection, the SR gate starts at different moment when the LLC converter start its switching operation.

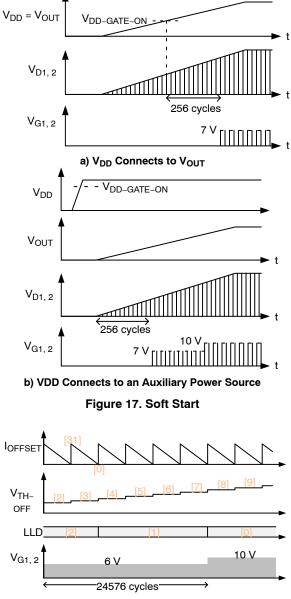


Figure 18. I_{OFFSET}, V_{TH-OFF}, LLD, and V_{GATE} when the Virtual V_{TH-OFF} Keeps Increasing

When NCP4318 starts to deliver SR gate signals during soft start, amplitude of V_{G1} and V_{G2} starts with 7 V. If the adaptive gate voltage control is not enabled, V_{G1} and V_{G2} changes its amplitude to 10 V after another 256 switching cycles. However, when the adaptive gate voltage control is enabled, amplitude of V_{G1} and V_{G2} will be decided by the LLD status. Take NCP4318ALC as an example. Its VTH-OFF-MIN, VTH-OFF-STEP, and VTH-OFF-RST are -6, 4, and 2 mV, which means, at powering on, its V_{TH-OFF} reset to the 2^{nd} step ((2 mV - (-6 mV)) / 4 mV = 2^{nd} step), in which the 32 steps of V_{TH-OFF} are noted as $0~31^{st}$ steps. V_{GATE} amplitude changes to 10 V when the V_{TH-OFF} is higher than the 7th step. Each V_{TH-OFF} step includes 32 steps of I_{OFFSET} change, and it takes 128 switching cycles for the virtual VTH-OFF to increase by one step of IOFFSET change. Assuming the virtual V_{TH-OFF} keeps increasing during the process, it will take roughly $(7 - 2 + 1) \cdot 32 \cdot 128 = 24576$ switching cycles to make V_{TH-OFF} rise to the level that makes V_{GATE} change to 10 V. Overall, when the adaptive gate voltage control is enabled, the number of 7 V gate pulses during soft start is much larger than 256.

Similar to the soft start, with different VDD connection, SR gate signal stops at different moment when V_{OUT} drops during power off. In case VDD is supplied from V_{OUT} , VG1 and VG2 stops when V_{OUT} drops below $V_{DD-GATE-OFF}$, even if the primary side LLC controller still delivers gate pulses to the LLC converter.

Working with LLC Controllers with a Light-load Mode

Instead of operating the LLC converter with pulse-frequency modulation (PFM) with 50% of duty cycle, some LLC controller provides special primary-side gate drive pattern to improve light-load efficiency. Let's call it a light-load mode here. The idea is to make the LLC converter delivers similar amplitude of current to the secondary side with similar primary-side pulse on-time, while modulating a dormant duration to adjust average delivered power.

In this mode of operation, the rectifier currents don't grow in every primary-side gate pulse. Whether the rectifier currents grow or not depends on the design of the primary-side pulse packet. For example, in Figure 19, you see $M_L-M_U-M_L$ primary-side pulse packets. Figure 19 (b) shows shorter on-time in the last M_L of the packet. It results in no energy delivering during the M_U pulse duration due to the resulting C_r voltage in that duration.

Whatever the light-load-mode packet is, while the rectifier currents grow, we want the respective SR gate to turn on, like what we can see in Figure 20. To better cope with the light-load mode operation, you can select NCP4318 with its parameters adjusted as described below.

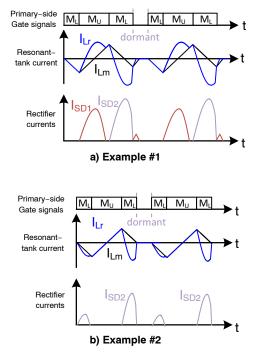


Figure 19. Examples of Light-load Mode Current Waveforms

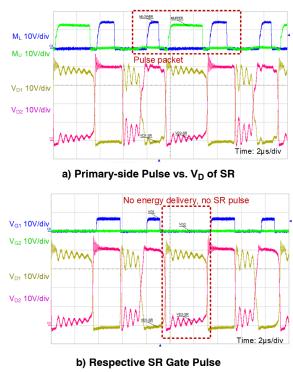


Figure 20. Waveform of NCP4318 Working with Light-Load Mode

Shorter t_{ON-DLY2}

NCP4318 utilizes t_{ON-DLY2} to deal with the leading-edge inversion current happening in light-load conditions. When the LLC converter operates in the light-load mode, the leading-edge inversion current may not happen. In addition, the modulated dormant period, which had been indicated in Figure 19, can be longer than $t_{GRN2-ENT}$, making $t_{ON-DLY2}$ be activated. Thus, to work with LLC controllers with such kind of light-load mode, the t_{ON-DLY2} parameter should be shorter, such as 240 ns in NCP4318AHD.

However, sometimes the leading-edge inversion current may still happen in light-load mode. The primary shutdown may be triggered in this condition, as shown in Figure 21. In this situation, slightly longer $t_{ON-DLY2}$ to cover the capacitive current spike can help the SR operate much stably.

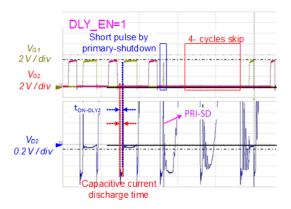
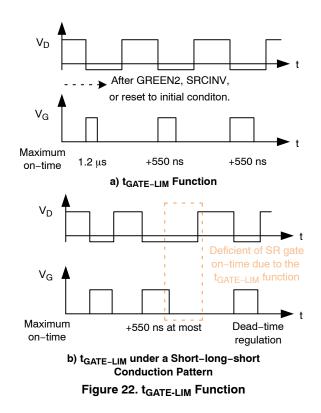


Figure 21. A Light-load Mode with Leading-edge **Inversion Current Makes Primary Shutdown Protection Triggered**

Disable t_{GATE-LIM}

The SR conduction duration of the light-load mode may vary a lot in consecutive switching cycles. NCP4318 has an optional tGATE-LIM function that makes the SR gate on-time increase gradually, as shown in Figure 22 (a). When the SR operation is reset by power-on, SRCINV, or other protections, the on-time of SR gate pulses starts from 1.2 µs. The increment rate of the SR gate pulses from their previous cycles is limited to 550 ns. Apparently, that function will make the SR gate on-time always small when the SR conduction duration shows a repetitive short-long-short pattern, as shown in Figure 22 (b). In a light-load mode, the primary-side gate pulses of the LLC converter tend to be not consistent, so as the SR conduction duration. Thus, the $t_{GATE-LIM}$ function should be disabled to make the SR gate on-time follows the actual conduction duration detected from V_{DS} signal.



Reduce t_{OFF-MIN}

NCP4318 has a tOFF-MIN function which avoids SR gate to be turned on by the noise generated around its turn-off transition. SR gate is prohibited to be turned on again after turning off within a tOFF-MIN time window. In the light-load mode operation, if the dormant duration, as in Figure 19, is very short, the SR gate may need to be turned on again after it has just been turned off before the short dormant duration. In this condition, we want the toFF-MIN parameter of NCP4318 to be shorter.

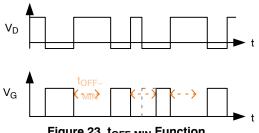


Figure 23. t_{OFF-MIN} Function

NCP4318 has shorter toFF-MIN option for both its H-version and L-version. In addition, since tON-DLY2 itself can be seen as a minimum off-time, NCP4318 also offers an option to disable t_{OFF-MIN} when t_{ON-DLY2} has been activated.

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Estimating Gate-drive Power Consumption

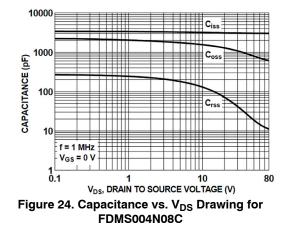
The operation of SR is to turn on the MOSFET when the body diode is in conduction and turn off the MOSFET to let the body diode takes over at the end of the conducting duration. Load of the gate driver is C_{ISS} and C_{RSS} of the MOSFET at $V_{DS} \approx 0V$. The VDD pin's sinking current, I_{DD} , can be estimated as below.

$$C_{TOTAL} \equiv \Sigma_{all_MOSFETs} (C_{ISS} (V_{DS} = 0) + C_{RSS} (V_{DS} = 0))$$
(eq. 4)
$$I_{DD_{VG_loaded}} = I_{DD_{VG_open}} + C_{TOTAL} \cdot V_{GATE} \cdot f_{SW}$$
(eq. 5)

For example, the MOSFET FDMS004N08C shows $C_{ISS} \approx 3200 \text{ pF}$ and $C_{RSS} \approx 270 \text{ pF}$. When we put two MOSFET in parallel for each VG channel and make the LLC converter operate at 103 kHz at full load, the total average current consumption of the gate drivers is $(3200 \text{ pF} + 270 \text{ pF}) \times 2 \times 2 \times 10.5 \text{ V} \times 103 \text{ kHz} = 15 \text{ mA}.$ When V_G pins are open, the measured I_{DD} is as 3 mA. So, the total I_{DD} is 18 mA.

 $C_{TOTAL} \times$

Figure 1,



The total power consumption of NCP4318 is $V_{DD}*I_{DD}$, but not all power needs to be eventually dissipated as heat on NCP4318. The gate-drive portion of the power consumption have some variation based on external circuitry. For example, when there is a series resistor R_G in the turning-on current path, it slows down the turn-on slew rate and makes the power dissipated on RDRV-SOURCE becomes

$$E_{DRV-SOURCE} = \left(V_{DD} \cdot C_{TOTAL} \cdot V_{GATE-MAX} - 0.5 \cdot C_{TOTAL} \cdot V_{GATE-MAX}^{2}\right) \cdot \frac{N_{DRV-SOURCE}}{R_{DRV-SOURCE} + R_{G}}$$
(eq. 6)
which implied that part of power dissipation will be directed
from R_{DRV-SOURCE} to the external R_G. Also, the total energy
that needs to be dissipated during gate turning off is 0.5 ×
C_{TOTAL} × V_{GATE-MAX}². The turn-off energy can be directed
to an external PNP bipolar transistor when it is used in the
turn-off circuit. However, with the simplest connection in
Figure 1, which connects VG pins to MOSFET's gate
terminal without any additional elements, the gate drive
power dissipation will be all on the NCP4318 chip.
$$P_{DRV} = V_{DD} \cdot C_{TOTAL} \cdot V_{GATE-MAX} \cdot f_{SW} \quad (eq. 7)$$
a) Gate Current Sourcing

b) Gate Current Sinking

Figure 25. Gate Current Sourcing and Sinking **Situation with Additional Elements**

Keeping MOSFET Turn-on Delay Time within tDB-HGH

We have mentioned a V_{TH-HGH} parameter in previous paragraphs. V_{TH-HGH} defines the end of SRCOND signal as in Figure 12 and so involves in definition of dead time as in Figure 6. The value of V_{TH-HGH} is much higher than V_{TH-OFF}. V_D > V_{TH-HGH} indicates finish of current conduction in MOSFET or its body diode. Note that V_{TH-OFF} is compared with V_D-V_S, while V_{TH-HGH} is compared with V_D-V_{GND}.

The comparison of V_D and V_{TH-HGH} has a leading–edge blanking time t_{DB-HGH}, counting from assertion of the SRCOND signal, which is also the same instant that the gate–drive output starts rising. The value of t_{DB-HGH} is 450 ns for L–version and 350 ns for H–version NCP4318. Within the leading–edge blanking time, V_D > V_{TH-HGH} won't reset the SRCOND signal.

The values of these parameters imply a requirement for turning–on of MOSFET: V_{TH-HGH} being much higher than V_{TH-OFF} means V_D won't exceed V_{TH-HGH} when the MOSFET has been turned on; and, the existence of a leading–edge blanking time means the turning–on process of the MOSFET is expected to be finished within t_{DB-HGH}. By keeping the turn–on delay within t_{DB-HGH}, the blanking time helps prevent misjudging the termination moment of the MOSFET or body diode conduction. This ensures that the NCP4318 operates smoothly and stably without unexpected behavior. Otherwise, the SRCOND signal might reset incorrectly, which, in rare cases, could lead to missed triggering of the V_{TH-OFF} comparator.

So, what's the turn-on delay? GATE and SRCOND signals assert together, and the turning-on of MOSFET is achieved by sourcing a current from the GATE pin to charge the C_{ISS} of MOSFET, as depicted in Figure 26. The MOSFET is fully turned on when the voltage between its gate and source terminals reaches

$$V_{\rm GS(on)} = V_{\rm GS(th)}$$
 (eq. 8)

where $V_{GS(th)}$ is MOSFET turn-on threshold voltage specified on the MOSFET's data sheet. The instant that V_{GS} reaches $V_{GS(on)}$ marks the end of turn-on delay. Due to the resistive characteristic of the I_{SOURCE} path, MOSFET V_{GS} shows an exponential rising waveform, as shown in Figure 27. If the C_{ISS} is larger, the turning-on process will take longer time, meaning the turn-on delay will be longer.

To make sure the turning-on process finishes within t_{DB-HGH} , we suggest checking the MOSFET V_{GS} waveform in all load conditions in the design. To have some margin, aim at letting MOSFET V_{GS} exceed $V_{GS(on)}$ within 450 * 0.7 = 315 ns for L-version and 350 * 0.7 = 245 ns for H-version NCP4318. If you find the MOSFET V_{GS} rises too slowly, there are some actions you can take:

- 1. Reduce resistance of the I_{SOURCE} path. You may reduce the R_G resistance and/or shortening/widening copper trace of the path.
- 2. Check whether $V_{GATE-CLAMP}$ is reduced. NCP4318 may have variable $V_{GATE-CLAMP}$ to reduce gate-driving loss, and the lowered $V_{GAMP-CLAMP}$ lengthens turn-on delay time of MOSFET. Referring to Adaptive V_{GATE} Control section in NCP4318 data sheet, $V_{GATE-CLAMP}$ is adjusted according to V_{TH-OFF} level (output load condition), switching frequency, and chip junction temperature. Different orderable part numbers of NCP4318 have different triggering thresholds of reducing $V_{GATE-CLAMP}$ in these regards. When driving large C_{ISS} , you may want to have multi-level V_{GATE} and HFS function disabled.
- 3. Add an external gate driver. When C_{ISS} is very large, NCP4318's driving capability may not be enough to turn on MOSFET within t_{DB-HGH}. External gate drivers may have higher driving capability, which means its equivalent R_{DRV-SROUCE} is lower. The external gate driver can be a gate-driver IC or discrete totem-pole gate-driving circuit.

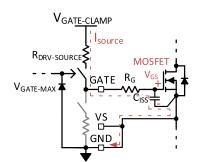


Figure 26. Gate Turning-on Current-sourcing Path

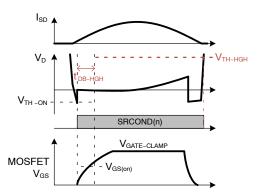


Figure 27. $t_{\mbox{\scriptsize DB-HGH}}$ and Exponential Rising of MOSFET $V_{\mbox{\scriptsize QS}}$

PCB Layout Recommendation

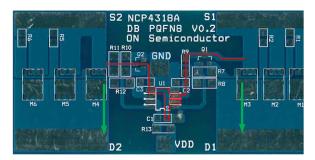
To explain the recommended PCB layout, let us look at the example of an SR daughter card with NCP4318A as its SR controller in Figure 28.

VD1 and VD2 pins for drain sensing are connected to drain pads at terminals that the flowing current, indicated as arrows, begins. It is not at any middle way of any possible current path. This connection avoids the noise generated by the changing current and the stray inductance on the PCB trace.

VS1 and VS2 pins are connected to SR MOSFET's source terminals and GND pin separately, forming a Y connection. GND pin also connect to a VDD capacitor.

Gate drive current goes from VG1 and VG2 to the respective source terminal of the MOSFET and returns to GND through the VS1 and VS2 connections. Keeping the loop area of VG and VS connections small avoids the gate drive current loop to interfere other parts of the circuit.

For a higher wattage application, gate charge for MOSFETs in each switching cycle can be higher. Using external PNP transistors Q1 and Q2 to help the turning-off process can be considered. The PNP transistors reduces turning-off current-loop area and alleviate the power consumption on the SR controller during the turning-off process.



a) Printed Circuit Board

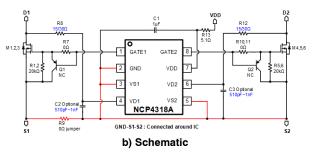
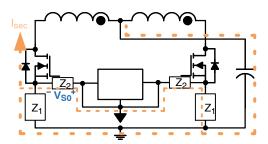


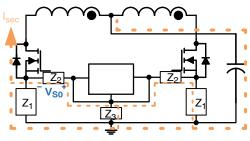
Figure 28. NCP4318A SR Daughter Card

The GND pin of NCP4318 is connected to LLC converter's output ground terminal through the VS connections. It doesn't need to connect to output ground with other additional connection. Figure 29 shows the connection methods of VS pins, GND pin, and the output ground of the LLC converter. It is assumed that the layout is perfectly symmetrical. Z_1 is the impedance between source pin of MOSFET and the output ground. Z_2 is the impedance

between VS pin and source pin of MOSFET. If there is additional connection between the GND pin and the output ground, the impedance is denoted as Z₃. Assume Z₁<<Z₂ and Z₁<<Z₃, for Z₁ being in the main current trace. The voltage difference V_{S0} between IC's VS pin and MOSFET's source pin can be derived as $I_{sec} \cdot Z_1/2$ for Figure 29 (a) and $I_{sec} \cdot Z_1 \cdot (Z_2 + Z_3)/(Z_2 + 2Z_3)$ for Figure 29 (b). The voltage difference V_{S0} in Figure 29 (a) is smaller between the two.



a) IC round doesn't connect to output ground



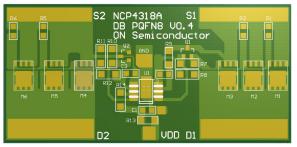
b) IC ground connects to output ground

Figure 29. Ground Connection and Current Flow

Enhancing Heat-Dissipation Capability of SOIC-8 EP Package

When NCP4318 needs to drive more paralleled SR MOSFETs in higher-output-current designs, power consumption on the gate driver of NCP4318 gets higher. Higher power consumption leads to higher junction temperature on the chip. NCP4318 has an SOIC-8 EP package variant in its lineup. This type of package provides exposed pad for direct thermal attachment, which makes lower the thermal impedance to the chip. To make good use of the package's characteristic, here we provide additional reminder on the PCB layout design.

The exposed pad can be connected to NCP4318's GND pin. When a PCB design still has some room to extend the copper area for GND, one way to enhance the thermal dissipation is to connect the GND copper area to the exposed pad of the package. This way, the copper area is utilized as heat-sinking copper. Make sure that the exposed pad connects exactly to the copper area. More, note that the GND copper area is signal ground for NCP4318, not power ground for the output of the LLC converter. If the PCB design is of multi-layer, you may consider drawing the ground copper area in the other layer of the same position as the IC and connecting the exposed pad to the ground copper area through thermal vias. The thermal vias can be spaced by 1 mm and have diameter of 0.3 mm. Figure 30 provides a design example.







b) Bottom side Figure 30. A PCB Layout with Thermal Vias for

Package with Exposed Pad

Situations That May Require Filtering Capacitors on the VD Pins

The application schematic of Figure 1 mentioned that a capacitor may be added between VD and GND pins. The added capacitor on VD pin forms a low-pass filter with R_{OFFSET} on the VD signal. Since the low-pass filter will lead to delay on the VD signal, time constant of the low-pass filter had better not to be larger than a number around 30 ns for a proper SR operation. So, use capacitor not greater than 2.2 nF for 15 Ω of R_{OFFSET}, and not greater than 1 nF for 30 Ω of R_{OFFSET}. Too large of a time constant delays VD signal too much, making the judged dead time being effectively subtracted by the time constant, which in turn may make the gate be turned off too late. The capacitor is not required in general cases for NCP4318 to operate normally. However, there are some cases that adding capacitors on VD pins may help.

Gate Turn-off Noise

When the gate capacitance of the MOSFET is huge, amplitude of the MOSFET turn-off current tends to be higher. The turn-off current of the gate driver can induce a voltage spike on the parasitic inductor in the current path, as described in Figure 31. If the spike is not higher than V_{TH-HGH} , it doesn't cause problem. However, if the spike makes V_D exceeds V_{TH-HGH} (0.85 V in typical), it may

mis-trigger abnormal-VD protection, or at least interfere the dead-time judgement. In such a situation, adding VD pin capacitors may help to filter the spike. Or there are also orderable part numbers of NCP4318 that has a higher V_{TH-HGH} of 1.5 V, which can be an alternative solution to this situation.

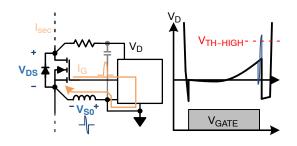


Figure 31. Effect of Gate Turn-off Current on V_{DS}

Misfiring on the SR Gate while the LLC Controller Shuts Down

Another example that adding a capacitor between VD and GND may help happens at shutting down of the LLC controller. When the primary side LLC controller shuts down its operation, the resonant tank stops delivering energy to the secondary side. The remaining energy in L_m and C_{OSS} of the primary-side power switches makes a resonance. The voltage across L_m reflects to the secondary side, making a slower ringing on V_{DS} of the SR MOSFETs. At the same time, the remaining energy in C_{OSS} of SR MOSFETs and leakage inductance on the secondary side makes an additional resonance at a much higher frequency. Waveform of the two resonances is shown in Figure 32.

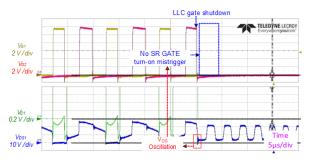


Figure 32. Added-up Resonances on VDS at LLC Controller Shutting Down

When the two resonances are added up, V_{DS} on the SR MOSFET may satisfy V_{TH-ON} and NCP4318 generates gate turn-on signal, which results in an inversion current conducted in the SR MOSFET. The SR inversion current detection function or the primary shutdown protection can turn off the SR gate immediately; however, it is even better if the V_G signal isn't turned on by the V_{DS} ringing. In such a case, adding a R-C snubber to the SR MOSFET or adding a capacitor for the VD signal can absorb or filter out the V_{DS} ringing, avoiding the mis-triggered SR gate pulse. Note that

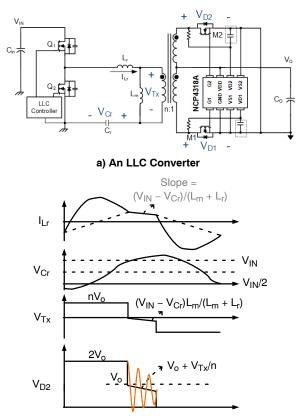
the R_{OFFSET} and VD pin capacitor equivalently form an R-C snubber to the SR MOSFET.

Mis-triggering of SR Gate During LLC Hold-up Time

Yet another example that adding VD pin capacitors may help happens during hold-up time. The LLC converter tends to operate in below-resonant region during the hold-up time, so sub-resonance can be seen in each switching cycle. In addition, since the load during hold-up time is usually heavy, turning-on delay of NCP4318 tends to be the shorter t_{ON-DLY} , which means the SR gate turns on immediately when $V_D < V_{TH-ON}$. Furthermore, the V_{Cr} amplitude tends to be high during the hold-up time.

In some design examples, the amplitude of V_{Cr} may be increased larger than V_{IN} . Thus, when the current in M1 cuts off and VD shows sub-resonance, the amplitude of the sub-resonance becomes larger than 2 x V_O , as depicted in Figure 33. It makes V_{D2} dips to a negative value, which may satisfy the V_{TH-ON} criterion and mis-triggers turning-on of M2. Same phenomenon happens on M1 on the other half cycle.

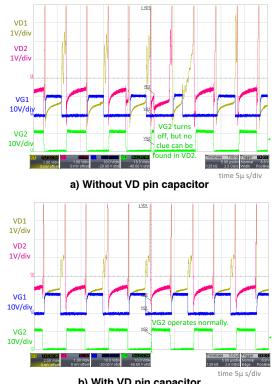
In this case, a snubber on SR MOSFETs damps the sub-resonance and makes the amplitude of the sub-resonance reduce faster. Thus, adding snubber, or using VD pin capacitor to form an equivalent snubber with R_{OFFSET}, helps avoiding the mis-triggering of SR gate signals.



b) Sub-resonance that Causes Mis-trigger of SR Gate Figure 33. Increased Sub-resonance Amplitude During Hold-up Time

SR Gate turns off by not-capturable noise

It had been observed that SR gate may sometimes be turned off while no clue can be found on its respective VD signal. Possible reasons may include radiated noise on the board or noise that is beyond resolution of oscilloscope. In Figure 34 (a), when the VG2 turned off, VD2 didn't show a waveform that satisfied V_{TH-OFF} or SRCINV. Although the oscilloscope didn't capture the problem, it was found that the problem can be solved by adding a capacitor on the VD2 pin. If that happens in your design too, adding capacitor on VD pins can be worth trying.



b) With VD pin capacitor
 Figure 34. SR Gate is Turned off
 by Not-capturable Noise

Common-mode Noise Affects Dead Time Regulation in Above-resonant Operation

In some LLC converter designs, due to parasitic components, such as inter-winding capacitor in the transformer or stray inductance on the secondary side, a high-frequency noise is induced while the primary-side switches do switching transition. When the LLC converter operates in above-resonant region, the switching transition happens before SR current commutating. If the magnitude of the noise is considerable, such as in Figure 35, the induced noise will hinder the dead-time regulation of NCP4318 to operate properly. The dead time will not be able to stay in the range of $t_{DEAD-LBAND} \sim t_{DEAD-HBAND}$ for the noise triggering turning-off of the SR gate signal.

If the noise frequency is as high as tens of MHz, adding filtering capacitor on VD pins to form a low-pass filter for the noise can be helpful to get rid of the noise. Even if the noise doesn't get filtered out completely, lowering magnitude on the noise may make the dead-time regulation get back to proper operation.

When the dead time is found to be always longer than $t_{\rm DEAD-HBAND}$ in all load conditions, please give this $V_{\rm DS}$ noise a check.

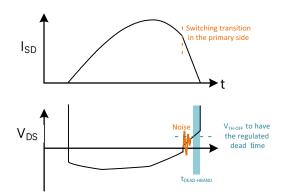


Figure 35. Induced Common-mode Noise on V_{DS} at Switching Transition of the Primary-side Switches

When L_r is not integrated into the transformer, the position of L_r matters in the generation of the common-mode noise. Consider two positions for L_r placement as in Figure 36 (a). For proper operation of the LLC converter, those two positions give no difference. However, when the inter-winding capacitor is considered, which is lumped as a C_{inter} in the figure, the two positions give different results for the common-mode noise.

The voltage on one side of the C_{inter} is notated as V_{TX} . As drawn in Figure 36 (b), the L_r position 1 makes V_{TX} equal to V_{Cr} , which changes gradually during the switching operation. Comparatively, when L_r is in position 2, the V_{TX} waveform shows sudden changes in switching transition of the primary side and current commutating of the secondary side.

When V_{TX} shows fast transitions, a displacement current will be induced on the C_{inter}. The induced current flows through the secondary-side circuit and returns on the EMI-suppressing capacitor C_Y. The current flowing through the secondary-side circuit excites parasitic components to resonate, resulting in the noise shown in Figure 35.

So, when a design has a non-integrated L_r , the L_r had better be placed in the position 1, which induces less noise on the secondary-side circuit.

If the noise is found to be not manageable in some rare cases, the NCP4318 functional option of disabling dead-time regulation may be considered. However, solving the noise through circuit modification is encouraged.

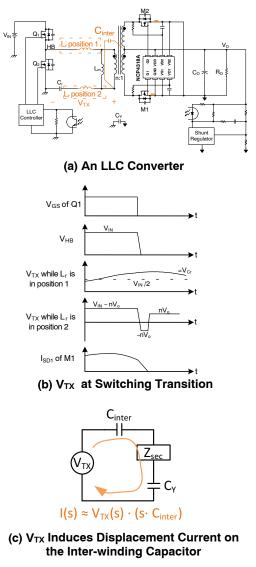


Figure 36. Inter-winding Capacitance and Placement of L_r

Conclusion

NCP4318 is an SR controller for LLC converters with center-tapped secondary-side configuration. With highly integrated functionalities, NCP4318 controls the SR power switches with very few additional circuit elements. NCP4318 delivers the driving pulses for SR power switches that maximize the efficiency of LLC converters. With sophisticated protections, NCP4318 responds to sudden changes in the operation of LLC converters with appropriate actions in the gate drive signals.

NCP4318 has several orderable part numbers (OPNs) that provides different function sets and parameter values. For different LLC converter designs, the required function sets and parameter values may vary. This application note is meant to share the insights for selecting the appropriate OPN by explaining the functionalities in much detail. Some circuit design tips are provided to ease the difficulties that one might sometimes confront when designing LLC converters with NPC4318 for the SR control.

References

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- [2] LLC Resonant Converter Synchronous Rectification Design using FAN6248 <u>https://www.onsemi.com/pub/collateral/and9618d.pdf</u>

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