

07/22/2013

# **Test Procedure for the NCV7383GEVK**

# **Required Equipment**

- Dual channel Oscilloscope
- Bench Power Supply
- Voltmeter
- Two NCV7383 Evaluation Boards
- Two 12V power supply adapters
- Two FlexRay bus cable assemblies

# **Test procedure Step 1:**

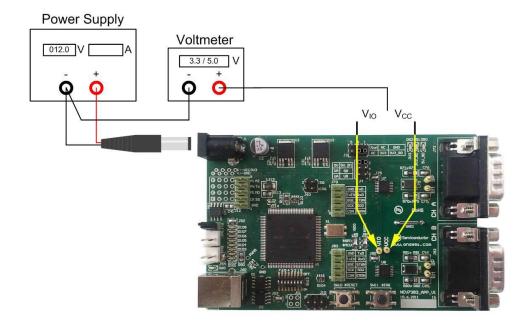


Figure 1. Input current and voltage regulators output voltage test

- 1. Set the boards to default configuration according to Error! Reference source not found. section.
- 2. Select one of the bus termination concepts (Bus Termination Configuration section) and adapt the respective parts. End node bus termination is recommended for 2-nodes network.
- 3. Connect the setup as shown above.
- 4. Apply an input voltage,  $V_{BAT} = 12 \text{ V}$
- 5. Check  $I_{IN}$ ,  $V_{CC}$  and  $V_{IO}$

#### Table 1. Desired Results

$$\begin{split} I_{IN} &= 65 \text{ mA to } 75 \text{ mA} \\ V_{CC} &= 4.9 \text{ V to } 5.1 \text{ V} \\ V_{IO} &= 3.2 \text{ V to } 3.4 \text{ V} \end{split}$$

#### **Test procedure Step 2:**

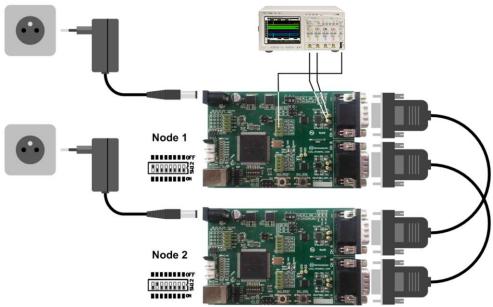


Figure 2. Simple FlexRay network configuration

- 1. Connect two boards according to figure above.
- 2. Set a different board address on each board. One of the boards must be set with address 1 and is considered as Master Board. Node address is configurable by address switch (SW12).
- 3. Connect an oscilloscope to BP and BM test-points (Channel A or B).
- 4. After the power supply is applied, FlexRay communication should be automatically initialized, what should be signaled by one of the LEDs (LED4-LED8) on both nodes. Communication on FlexRay bus should be visible on oscilloscope (BP and BM test-points).
- 5. Press and hold SW11 (#IRQ) on Node 1 for more than 3 seconds. Both nodes should be switched to STANDBY mode. FlexRay communication is stopped and the current consumption should be reduced.
- 6. Press the #IRQ button on any node. Both nodes should be woken up and the FlexRay communication should be restarted.

#### **Results:**

The following waveforms should be visible in Normal mode (Figure 3) and in Standby mode (Figure 4).

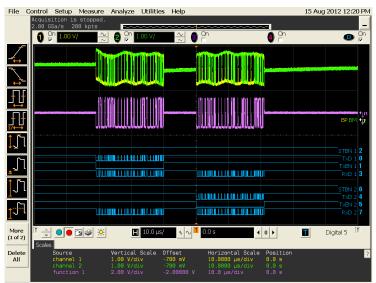


Figure 3. Normal mode

Battery current consumption is typ. 70 mA per node in Normal mode.

File Control	Setup Measure	Analyze Utilities	s Help		15 /	Aug 2012 12:20 Pl
2.00 G	Sa/s 200 kpts	2 <sup>On</sup> 1.00 V/	~ 0 0	n		
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+ <u>v</u> ,						STBN 1 2 TxD 1 0
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Delete All	Source channel 1	1.00 V/div	Offset -700 mV	Horizontal Scale 10.0000 µs/div	0.0 s	
	channel 2 function 1		-700 mV -2.00000 V	10.0000 µs/div 10.0 µs/div	0.0 s 0.0 s	

Figure 4. Standby mode

Battery current consumption is typ. 10 mA per node in Standby mode. Most of the current is consumed by the power supplies LED indicators.

# **Jumpers and Default Configuration**

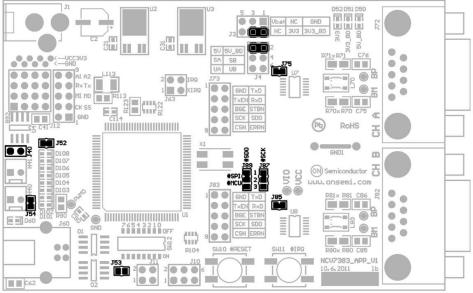


Figure 5. Jumpers and Soldering Straps

Table 3	. 2-pin	Jumper
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Open
Closed

Table 2. 3-pin Jumper

123		
	Open	
	Closed position 1-2	
	Closed position 2-3	

Jumper	Function	Configuration	Description	Default	
J3 Bus Driver VIO supply		Open	Bus Driver VIO unsupplied	Closed	
		Closed	Bus Driver VIO connected to voltage regulator output	3V3 – 3V3_BD	
		Open Bus Driver VCC unsupplied		Closed 5V – 5V_BD	
J4 Bus Driver VCC supply		Closed	Bus Driver VCC connected to voltage regulator output		
J40	CAN bus termination	Open	CAN bus without termination	Closed	
J40	CAN bus termination	Closed	CAN bus with 120Ω termination		
150		Open	LEDs Disabled		
J52	General purpose LED	Closed	LEDs Enabled	Closed	
150		Open UART Disabled		Onen	
J53 UA	UART power supply	Closed	UART Enabled	Open	
15.4		Open LED D101 disabled, PWM0 enabled		Olasad	
J54	MCU output mcu_PP0 function	Closed	LED D101 enabled, PWM0 not recommended	Closed	
		Open	SCK_B disconnected		
J87 Chan	Channel B SCK pin connection	Closed 1-2	SCK_B connected to common hardware SPI interface	Closed 1-2	
		Closed 2-3	SCK_B connected to separated software SPI interface		
		Open	SDO_B disconnected		
J89 Chanr	Channel B SDO pin connection	Closed 1-2	SDO_B connected to common hardware SPI interface	Closed 1-2	
		Closed 2-3	SDO_B connected to separated software SPI interface		
J75	Bus Driver Dig. Pull-ups (Ch A)	Driver Dig, Bull upg (Ch.A) Open TxEN, SCN and SCK pull-ups disconnected from VIO		Closed	
		Closed	TxEN, SCN and SCK pull-ups connected to VIO	Ciosea	
		Open	TxEN, SCN and SCK pull-ups disconnected from VIO	Closed	
J85	Bus Driver Dig. Pull-ups (Ch B)	Closed	TxEN, SCN and SCK pull-ups connected to VIO		
		Closed	TxEN, SCN and SCK pull-ups connected to VIO	]	

# Table 4. NCV7383 EVB Jumpers Configuration

# **Bus Termination Configuration**

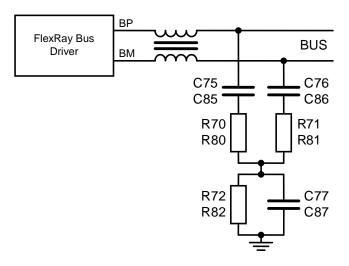


Figure 6. FlexRay bus termination connection (Channel A: R7x, C7x; Channel B: R8x, C8x)

# Table 5. FlexRay Bus Termination configuration

Component	End node (Low-Ohmic termination)	Middle node – Variant 1 (High-Ohmic termination)	Middle node – Variant 2 (Custom termination)
Ch. A: C75, C76 Ch. B: C85, C86	Short	Short	100 pF
Ch. A: R70, R71 Ch. B: R80, R81	47 Ω	1300 Ω	24 Ω
Ch. A: R72 Ch. B: R82	Not Assembled	Not Assembled	47 Ω
Ch. A: C77 Ch. B: C87	4.7 nF	4.7 nF	4.7 pF