Low Voltage Synchronous Buck Controller

The NCP81046 is a low cost PWM controller designed to operate from a 5 V or 12 V supply. This device is capable of producing an output voltage as low as 0.8 V. This device is capable of converting voltage from as low as 2.5 V. This 10-pin device provides an optimal level of integration to reduce size and cost of the power supply. Features include a 1.5 A gate driver design and an internally set 300 kHz oscillator. In addition to the 1.5 A gate drive capability, other efficiency enhancing features of the gate driver include adaptive non-overlap circuitry. The NCP81046 also incorporates an externally compensated error amplifier. Protection features include programmable short circuit protection and undervoltage lockout (UVLO).

Features

- V_{CC} Range from 4.5 V to 13.2 V
- 300 kHz Internal Oscillator
- Boost Pin Operates to 30 V
- Voltage Mode PWM Control
- Precision 0.8 V Internal Reference
- Adjustable Output Voltage
- Internal 1.5 A Gate Drivers
- 80% Max Duty Cycle
- Input Under Voltage Lockout
- Programmable Current Limit
- This is a Pb–Free Device

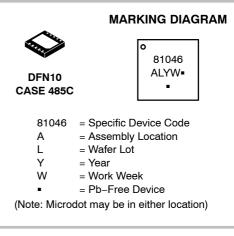
Applications

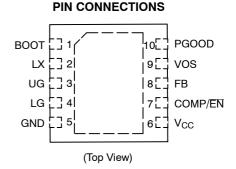
- Graphics Cards
- Desktop Computers
- Servers / Networking
- DSP & FPGA Power Supply
- DC–DC Regulator Modules



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ORDERING INFORMATION

Device	Package	Shipping [†]
NCP81046MNTWG	DFN10 (Pb-Free)	3000 / Tape & Reel
NCP81046MNTXG	DFN10 (Pb-Free)	3000 / Tape & Reel

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

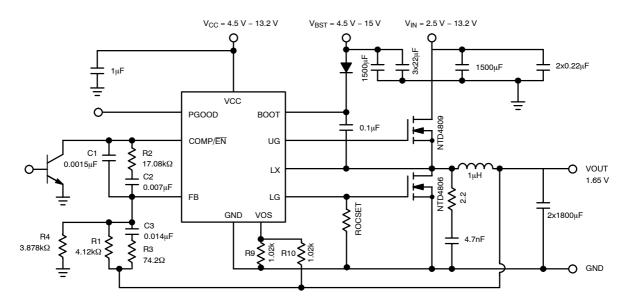


Figure 1. Typical Application Diagram

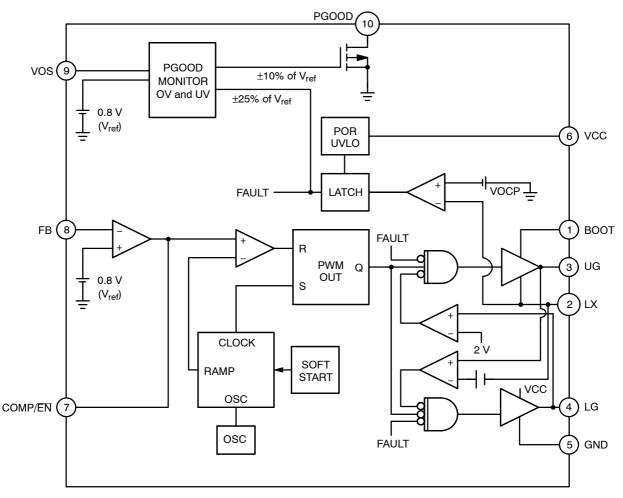


Figure 2. Detailed Block Diagram

PIN FUNCTION DESCRIPTION

Pin No.	Symbol	Description
1	BOOT	Supply rail for the floating top gate driver. To form a boost circuit, use an external diode to bring the desired input voltage to this pin (cathode connected to BOOT pin). Connect a capacitor (C_{BOOT}) between this pin and the LX pin. Typical values for C_{BOOT} range from 0.1 μ F to 1 μ F. Ensure that C_{BOOT} is placed near the IC.
2	LX	Switch node pin. This is the reference for the floating top gate driver. Connect this pin to the source of the top MOSFET.
3	UG	Top gate MOSFET driver pin. Connect this pin to the gate of the top N-channel MOSFET.
4	LG	Bottom gate MOSFET driver pin. Connect this pin to the gate of the bottom N-channel MOSFET.
5	GND	IC ground reference. All control circuits are referenced to this pin.
6	VCC	Supply rail for the internal circuitry. Operating supply range is 4.5 V to 13.2 V. Decouple with a 1 μ F capacitor to GND. Ensure that this decoupling capacitor is placed near the IC.
7	COMP/EN	Compensation Pin. This is the output of the error amplifier (EA) and the non-inverting input of the PWM com- parator. Use this pin in conjunction with the FB pin to compensate the voltage-control feedback loop. Pull this pin low for disable.
8	FB	This pin is the inverting input to the error amplifier. Use this pin in conjunction with the COMP pin to com- pensate the voltage-control feedback loop. Connect this pin to the output resistor divider (if used) or directly to V _{out} .
9	VOS	Voltage Offset Sense
10	PGOOD	Power Good output. Pulled Low if VOS is $\pm 10\%$ of 0.8 V V _{ref} .

ABSOLUTE MAXIMUM RATINGS

Pin Name	Symbol	V _{MAX}	V _{MIN}
Main Supply Voltage Input	VCC	15 V	–0.3 V
Bootstrap Supply Voltage Input	BOOT	35 V wrt/GND 40 V < 100 ns 15 V wrt/LX	-0.3 V -0.3 V -0.3 V
Switching Node (Bootstrap Supply Return)	LX	35 V 40 V for < 100 ns	_5 V _10 V for < 200 ns
High-Side Driver Output (Top Gate)	UG	30 V wrt/GND 15 V wrt/LX 40 V for < 100 ns	-0.3 V wrt/LX -2 V for < 200 ns
Low-Side Driver Output (Bottom Gate)	LG	V _{CC} + 0.3 V	−0.3 V −5 V for < 200 ns
Feedback, VOS	FB, VOS	5.0 V	–0.3 V
COMP/EN	COMP/EN	3.6 V	–0.3 V
PGOOD	PGOOD	7 V	–0.3 V

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Thermal Resistance, Junction-to-Ambient	R _{0JA}	165	°C/W
Thermal Resistance, Junction-to-Case	R _{0JC}	45	°C/W
Operating Junction Temperature Range	Т _Ј	0 to 150	°C
Operating Ambient Temperature Range	T _A	0 to 70	°C
Storage Temperature Range	T _{stg}	-55 to +150	°C
Moisture Sensitivity Level	MSL	1	-

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

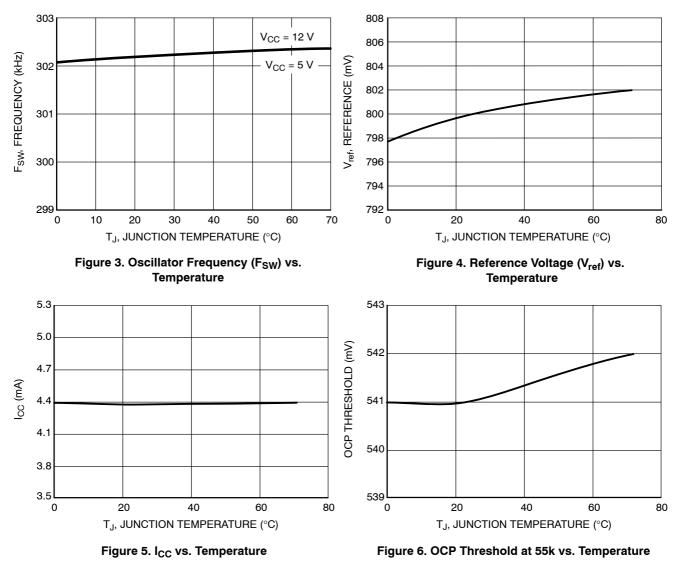
This device is ÉSD sensitive. Use standard ESD precautions when handling.

ELECTRICAL CHARACTERISTICS (0°C < T_A < 70°C; 4.5 V < [BST-PHASE] < 13.2 V, 4.5 V < BST < 30 V, 0 V < PHASE < 21 V, $C_{TG} = C_{BG} = 1.0$ nF, for min/max values unless otherwise noted.)

Typ Max Unit	Тур	Min	Conditions	Characteristic	
13.2 V		4.5		Input Voltage Range	
30 V		4.5	13.2 V wrt LX	Boost Voltage Range	
				Supply Current	
8.0 mA		1.0	V_{FB} = 1.0 V, No Switching, V_{CC} = 13.2 V	Quiescent Supply Current	
μΑ		0.1	V _{FB} = 1.0 V, No Switching	Boost Quiescent Current	
				Undervoltage Lockout	
4.0 4.2 V	4.0	3.8	V _{CC} Rising	UVLO Threshold	
3.6 3.8 V	3.6	3.4	V _{CC} Falling	UVLO Threshold	
0.4 V	0.4		V_{CC} Rising or V_{CC} Falling	UVLO Hysteresis	
				Switching Regulator	
0.8 0.8064 V	0.8	0.7936	Feedback Voltage (FB Tied to Comp. Measure FB Pin.)		
300 330 kHz	300	270		Oscillator Frequency	
1.1 V	1.1			Ramp-Amplitude Voltage	
0 %	0			Minimum Duty Cycle	
75 80 %	75	70		Maximum Duty Cycle	
500 ns	500			LG Minimum on Time	
				Error Amplifier	
80 dB	80	70		Open Loop DC Gain (Note 1)	
mA		2.0 2.0	V _{fb} < 0.8 V V _{fb} > 0.8 V	Output Source Current Output Sink Current	
0 2.0 mV	0	-2.0		Input Offset Voltage (Note 1)	
0.1 1.0 μΑ	0.1			Input Bias Current	
Mhz		15		Unity Gain Bandwidth (Note 1)	
0.8 V	0.8	0.6		Disable Threshold	
10 40 μA	10			Output Source Current During Disable	
				Gate Drivers	
A		1.5	V_{CC} = 5 V, VUG – VLX = 2.5 V	Upper Gate Source	
1.4 Ω	1.4			Upper Gate Sink	
A		1.5		Lower Gate Source	
1.0 Ω	1.0		V _{CC} = 12 V	Lower Gate Sink	
18 ns	18	12.4	V _{CC} = 12 V, UG–LX < 2.0 V, LG > 2.0 V	UG Falling to LG Rising Delay	
18 ns	18	12.4	V_{CC} = 12 V, LG < 2.0 V, UG > 2.0 V	LG Falling to UG Rising Delay	
				Soft-Start	
7.0 ms		3.0		Soft-Start time	
				Power Good	
0.4 V			Logic Low, Sinking 4 mA	Output Voltage	
0.88 1.0 V	0.88		Ramp VOS from 0.7 to 1.2. Monitor when PGOOD goes Low	OVP Threshold to PGOOD Output Low	
1.0 1.2 V	1.0		Ramp VOS from 0.8 to 1.2. Monitor when outputs disable	OVP Threshold to Part Disable	
).72 V	0.72	0.65	Ramp VOS from 800 mV to 500 mV. Monitor when PGOOD goes Low	UVP Threshold to PGOOD Output Low	
0.6 V	0.6	0.5	Ramp VOS from 800 mV to 500 mV. Monitor when utputs stop switching	UVP Threshold to Part Disable	
I		<u>.</u>	•	Overcurrent Protection	
0.6			Ramp VOS from 800 mV to 500 mV. Monitor when PGOOD goes Low Ramp VOS from 800 mV to 500 mV.	UVP Threshold to Part Disable	

1. Guaranteed by design but not tested in production.

TYPICAL CHARACTERISTICS



APPLICATIONS INFORMATION

Over Current Protection (OCP)

The NCP81046 monitors the voltage drop across the low side mosfet and uses this information to determine if there is excessive output current. The voltage across the low side mosfet is measured from the LX pin, and is referenced to ground. The over current measurement is timed to occur at the end of the low side mosfet conduction period, just before the bottom mosfet is turned off.

If the voltage drop across the bottom mosfet exceeds the over current protection threshold, then an internal counter is incremented. If the voltage drop does not exceed the over current protection threshold, then the internal counter is reset. The NCP81046 will latch the over current protection fault condition only if the over current protection threshold is exceeded for four consecutive cycles.

When the NCP81046 latches an over current protection fault, both the high side and low side mosfets are turned off. To reset the over current protection fault, the power to the VCC pin must be cycled.

The over current threshold voltage can be externally, by varying the value of the ROCSET resistor. The ROCSET resistor is a resistor connected between the LG pin (low side mosfet gate) and ground.

During startup, after the VCC and BOOT pins reach the under voltage lock out threshold, the NCP81046 will source 10 μ A of current out of the LG pin. This current will flow through the ROCSET resistor and produce a voltage that is sampled and then used as the over current protection threshold voltage. For example, if ROCSET is set to 10 kΩ, the 10 μ A of current will yield a 100 mV threshold, and if the voltage drop across the low side mosfet exceeds 100 mV at the end of its conduction period, then an over current event will be detected.

If the ROCSET resistor is not present, then the over current protection threshold will max out at 640 mV. The valid range for ROCSET is 5 k Ω to 55 k Ω which yields a threshold voltage range of 50 mV to 550 mV.

Internal Soft-Start

To prevent excess inrush current during startup, the NCP81046 uses a calibrated current source with an internal soft start capacitor to ramp the reference voltage from 0 to 800 mV over a period of 4 ms. The softstart ramp generator will reset if the input power supply voltages reach the under

voltage lockout threshold, or if the NCP81046 is disabled by having the COMP pin pulled low.

Startup into a Precharged Load

During a startup and soft start sequence the NCP81046 will detect a residual charge on the output capacitors and not forcefully discharge the capacitors before beginning the softstart sequence, instead, the softstart ramping of the output will begin at the voltage level of the residual charge. For example, if the NCP81046 is configured to provide a regulated output voltage of 2.5 V, the normal softstart sequence will ramp the output voltage from 0 to 2.5 V in 4.2 ms; however if the output capcitors already have a 1.2 V charge on them, the NCP81046 will not discharge the capacitors, instead the softstart sequence will begin at 1.2 V and then ramp the output to 2.5 V.

Power Good

The PGOOD pin is an open drain active high output pin that signals the condition of the VOS (Voltage Output Sense) pin. PGOOD is pulled low during soft start cycle, and if there is a latched over current, over voltage, or under voltage fault. If the voltage on the VOS pin is within $\pm 10\%$ of Vref (800 mV) then the PGOOD pin will not be pulled low. The PGOOD pin does not have an internal pull-up resistor.

Overvoltage Protection

If the voltage on the VOS pin exceeds the over voltage threshold the NCP81046 will latch an over voltage fault. During an over voltage fault the UG pin will be pulled low, and the LG pin will be high while the until the voltage on the VOS pin goes below $V_{ref}/2$ (400 mV). The NCP81046 will continue drive the LG pin, LG will go high if VOS exceeds 1 V and then go low when VOS goes below 400 mV. The power to the NCP81046 must be cycled to reset the over voltage protection fault.

Under Voltage Protection

If the voltage on the VOS pin falls below the under voltage threshold after the soft start cycle completes, then the NCP81046 will latch an under voltage fault. During an under voltage fault, both the UG and LG pins will be pulled low. The power to the NCP81046 must be cycled to reset the under voltage protection fault.

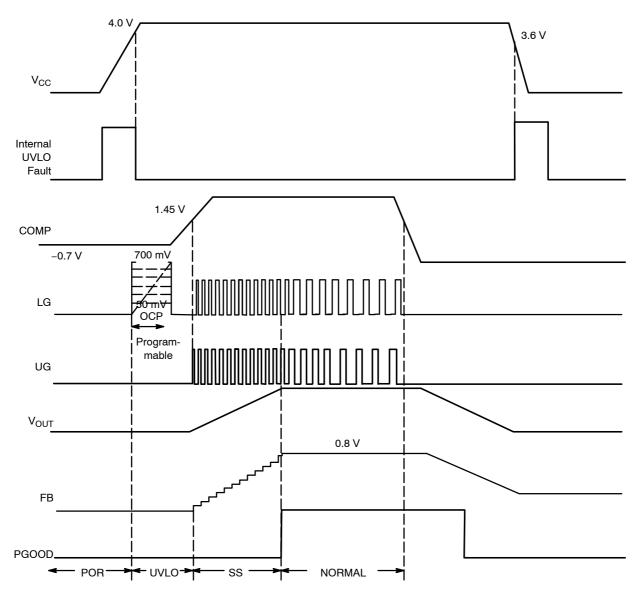


Figure 7. Typical Startup Sequence

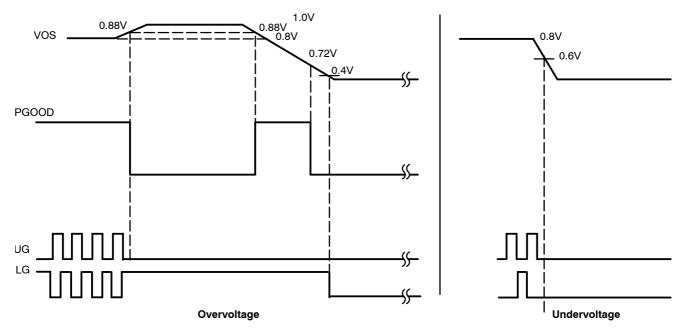
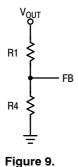


Figure 8. Typical Power Good Function

Feedback and Compensation

The NCP81046 allows the output voltage to be adjusted from 0.8 V to 5.0 V via an external resistor divider network. The controller will try to maintain 0.8 V at feedback pin. Thus, if a resistor divider circuit was placed across the feedback pin to V_{OUT} , the controller will regulate the output voltage proportional to the resistor divider network in order to maintain 0.8 V at the FB pin. The same formula applies to the VOS pin and the controller will maintain 0.8 V at the VOS pin.



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The relationship between the resistor divider network above and the output voltage is shown in the following equation:

$$\mathsf{R}_4 = \mathsf{R}_1 \times \left(\frac{\mathsf{V}_{\mathsf{REF}}}{\mathsf{V}_{\mathsf{OUT}} - \mathsf{V}_{\mathsf{REF}}}\right)$$

The same formula can be applied to the feedback resistors at VOS.

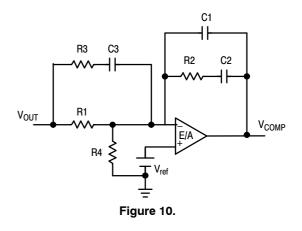
$$R_9 = R_{10} \times \left(\frac{V_{REF}}{V_{OUT} - V_{REF}}\right)$$

Design Example

Voltage Mode Control Loop with TYPE III Compensation

Converter Parameters:

Input Voltage: $V_{IN} = 5 V$ Output Voltage: $V_{OUT} = 1.65 V$ Switching Frequency: 300 kHz Total Output Capacitance: $C_{OUT} = 3600 \mu F$ Total ESR: ESR = $6 m\Omega$ Output Inductance: L_{OUT} : 1 μ H Ramp Amplitude: $V_{RAMP} = 1.1 V$



a.. Set a target for the close loop bandwidth at 1/6th of the switching frequency.

F_{cross over} := 50 kHz

b.. Output Filter Double Pole Frequency

$$\mathsf{F}_{\mathsf{lc}} := \frac{1}{2 \cdot \pi \cdot \sqrt{\mathsf{L}_{\mathsf{OUT}} \cdot \mathsf{C}_{\mathsf{OUT}}}}$$

 $F_{lc} = 2.653 \text{ kHz}$

c.. ESR Zero Frequency:

$$\mathsf{F}_{\mathsf{ESR}} := \frac{1}{2 \cdot \pi \cdot \mathsf{C}_{\mathsf{OUT}} \cdot \mathsf{C}_{\mathsf{ESR}}}$$

 $F_{ESR} = 7.368 \text{ kHz}$

Step 1: Set a value for R1 between 2 $k\Omega$ and 5 $k\Omega$

$$R1 := 4.12 \text{ k}\Omega$$

Step 2: Pick compensation DC gain (R2/R1) for desired close loop bandwidth.

$$\begin{split} & \mathsf{V}_{\mathsf{RAMP}} := \ 1.1 \ \mathsf{V} \\ & \mathsf{R2} := \ \mathsf{R1} \ \cdot \left(\frac{\mathsf{V}_{\mathsf{RAMP}}}{\mathsf{V}_{\mathsf{IN}}}\right) \cdot \left(\frac{\mathsf{F}_{\mathsf{cross_over}}}{\mathsf{F}_{\mathsf{Ic}}}\right) \end{split}$$

 $\text{R2}\,=\,\text{17.085}\,\text{k}\Omega$

Step 3: Place 1st zero at half the output filter double pole frequency.

$$C2 := \frac{2 \cdot \sqrt{L_{OUT} \cdot C_{OUT}}}{R2}$$

$$C2 = 7.024 \times 10^{-3} \,\mu\text{F}$$

Step 4: Place 1st pole at ESR zero frequency.

$$C1 := \frac{C2}{C2 \cdot R2 \cdot 2 \cdot \pi \cdot F_{ESR} - 1}$$
$$C1 = 1.542 \times 10^{-3} \,\mu\text{F}$$

Step 5: Place 2^{nd} zero at the output filter double pole frequency.

$$R3 := \frac{R1}{\frac{F_{SW}}{2 \cdot F_{lc}} - 1}$$
$$R3 = 74.169 \ \Omega$$

Step 6: Place 2nd pole at half the switching frequency.

$$\begin{split} \text{C3} := \frac{1}{\left(\pi \cdot \text{R3} \cdot \text{F}_{\text{SW}}\right)} \\ \text{C3} &= 0.014 \ \mu\text{F} \end{split}$$

Step 7: R4 is sized to maintain the feedback voltage to $V_{ref} = 0.8 \text{ V}.$

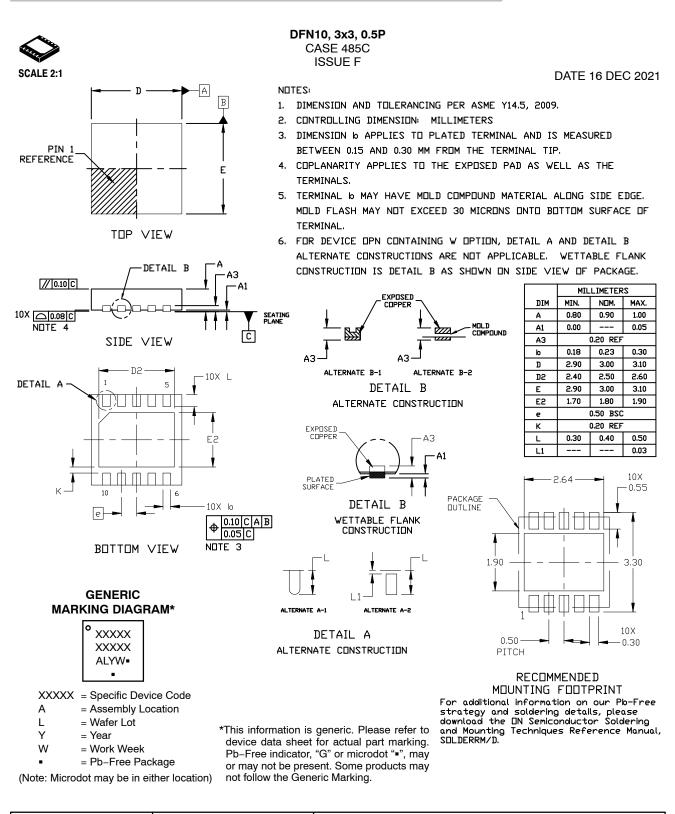
$$R4 := \frac{V_{REF} \cdot R1}{V_{OUT} - V_{REF}}$$

$$R4 = 3.878 \text{ k}\Omega$$

The Component values for Type III Compensation are:

 $\begin{array}{l} R1 = 4.12 \ \text{k}\Omega \\ R2 = 17.085 \ \text{k}\Omega \\ R3 = 74.169 \ \Omega \\ R4 = 3.878 \ \text{k}\Omega \\ C1 = 0.0015 \ \mu\text{F} \\ C2 = 0.007 \ \mu\text{F} \\ C3 = 0.014 \ \mu\text{F} \end{array}$

NOTE: Recommend to change values to industry standard component values.



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