

# MJE13003

## SWITCHMODE™ Series NPN Silicon Power Transistor

These devices are designed for high-voltage, high-speed power switching inductive circuits where fall time is critical. They are particularly suited for 115 and 220 V SWITCHMODE applications such as Switching Regulators, Inverters, Motor Controls, Solenoid/Relay drivers and Deflection circuits.

### Features

- Reverse Biased SOA with Inductive Loads @  $T_C = 100^\circ\text{C}$
- Inductive Switching Matrix 0.5 to 1.5 A, 25 and  $100^\circ\text{C}$   
 $t_c$  @ 1 A,  $100^\circ\text{C}$  is 290 ns (Typ)
- 700 V Blocking Capability
- SOA and Switching Applications Information
- Pb-Free Package is Available\*

### MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Collector-Emitter Voltage	$V_{CEO(sus)}$	400	Vdc
Collector-Emitter Voltage	$V_{CEV}$	700	Vdc
Emitter Base Voltage	$V_{EBO}$	9	Vdc
Collector Current – Continuous – Peak (Note 1)	$I_C$ $I_{CM}$	1.5 3	Adc
Base Current – Continuous – Peak (Note 1)	$I_B$ $I_{BM}$	0.75 1.5	Adc
Emitter Current – Continuous – Peak (Note 1)	$I_E$ $I_{EM}$	2.25 4.5	Adc
Total Power Dissipation @ $T_A = 25^\circ\text{C}$ Derate above $25^\circ\text{C}$	$P_D$	1.4 11.2	W mW/ $^\circ\text{C}$
Total Power Dissipation @ $T_C = 25^\circ\text{C}$ Derate above $25^\circ\text{C}$	$P_D$	40 320	W mW/ $^\circ\text{C}$
Operating and Storage Junction Temperature Range	$T_J, T_{stg}$	-65 to +150	$^\circ\text{C}$

### THERMAL CHARACTERISTICS

Characteristic	Symbol	Max	Unit
Thermal Resistance, Junction-to-Case	$R_{\theta JC}$	3.12	$^\circ\text{C}/\text{W}$
Thermal Resistance, Junction-to-Ambient	$R_{\theta JA}$	89	$^\circ\text{C}/\text{W}$
Maximum Load Temperature for Soldering Purposes: 1/8" from Case for 5 Seconds	$T_L$	275	$^\circ\text{C}$

Maximum ratings are those values beyond which device damage can occur. Maximum ratings applied to the device are individual stress limit values (not normal operating conditions) and are not valid simultaneously. If these limits are exceeded, device functional operation is not implied, damage may occur and reliability may be affected.

1. Pulse Test: Pulse Width = 5 ms, Duty Cycle  $\leq 10\%$ .

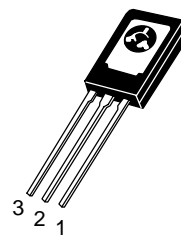
\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.



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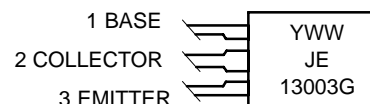
<http://onsemi.com>

1.5 AMPERES  
NPN SILICON POWER  
TRANSISTORS  
300 AND 400 VOLTS  
40 WATTS



TO-225  
CASE 77  
STYLE 3

### MARKING DIAGRAM



Y = Year  
WW = Work Week  
JE13003 = Device Code  
G = Pb-Free Package

### ORDERING INFORMATION

Device	Package	Shipping
MJE13003	TO-225	500 Units/Box
MJE13003G	TO-225 (Pb-Free)	500 Units/Box

# MJE13003

## ELECTRICAL CHARACTERISTICS (T<sub>C</sub> = 25°C unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
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### OFF CHARACTERISTICS (Note 2)

Collector–Emitter Sustaining Voltage (I <sub>C</sub> = 10 mA, I <sub>B</sub> = 0)	V <sub>CEO(sus)</sub>	400	–	–	Vdc
Collector Cutoff Current (V <sub>CEV</sub> = Rated Value, V <sub>BE(off)</sub> = 1.5 Vdc) (V <sub>CEV</sub> = Rated Value, V <sub>BE(off)</sub> = 1.5 Vdc, T <sub>C</sub> = 100°C)	I <sub>CEV</sub>	–	–	1 5	mAdc
Emitter Cutoff Current (V <sub>EB</sub> = 9 Vdc, I <sub>C</sub> = 0)	I <sub>EBO</sub>	–	–	1	mAdc

### SECOND BREAKDOWN

Second Breakdown Collector Current with bass forward biased	I <sub>S/b</sub>	See Figure 11			–
Clamped Inductive SOA with base reverse biased	RBSOA	See Figure 12			–

### ON CHARACTERISTICS (Note 2)

DC Current Gain (I <sub>C</sub> = 0.5 Adc, V <sub>CE</sub> = 2 Vdc) (I <sub>C</sub> = 1 Adc, V <sub>CE</sub> = 2 Vdc)	h <sub>FE</sub>	8 5	– –	40 25	–
Collector–Emitter Saturation Voltage (I <sub>C</sub> = 0.5 Adc, I <sub>B</sub> = 0.1 Adc) (I <sub>C</sub> = 1 Adc, I <sub>B</sub> = 0.25 Adc) (I <sub>C</sub> = 1.5 Adc, I <sub>B</sub> = 0.5 Adc) (I <sub>C</sub> = 1 Adc, I <sub>B</sub> = 0.25 Adc, T <sub>C</sub> = 100°C)	V <sub>CE(sat)</sub>	– – – –	– – – –	0.5 1 3 1	Vdc
Base–Emitter Saturation Voltage (I <sub>C</sub> = 0.5 Adc, I <sub>B</sub> = 0.1 Adc) (I <sub>C</sub> = 1 Adc, I <sub>B</sub> = 0.25 Adc) (I <sub>C</sub> = 1 Adc, I <sub>B</sub> = 0.25 Adc, T <sub>C</sub> = 100°C)	V <sub>BE(sat)</sub>	– – –	– – –	1 1.2 1.1	Vdc

### DYNAMIC CHARACTERISTICS

Current–Gain – Bandwidth Product (I <sub>C</sub> = 100 mAdc, V <sub>CE</sub> = 10 Vdc, f = 1 MHz)	f <sub>T</sub>	4	10	–	MHz
Output Capacitance (V <sub>CB</sub> = 10 Vdc, I <sub>E</sub> = 0, f = 0.1 MHz)	C <sub>ob</sub>	–	21	–	pF

### SWITCHING CHARACTERISTICS

Resistive Load (Table 1)						
Delay Time	(V <sub>CC</sub> = 125 Vdc, I <sub>C</sub> = 1 A, I <sub>B1</sub> = I <sub>B2</sub> = 0.2 A, t <sub>p</sub> = 25 μs, Duty Cycle ≤ 1%)	t <sub>d</sub>	–	0.05	0.1	μs
Rise Time		t <sub>r</sub>	–	0.5	1	μs
Storage Time		t <sub>s</sub>	–	2	4	μs
Fall Time		t <sub>f</sub>	–	0.4	0.7	μs
Inductive Load, Clamped (Table 1, Figure 13)						
Storage Time	(I <sub>C</sub> = 1 A, V <sub>clamp</sub> = 300 Vdc, I <sub>B1</sub> = 0.2 A, V <sub>BE(off)</sub> = 5 Vdc, T <sub>C</sub> = 100°C)	t <sub>sv</sub>	–	1.7	4	μs
Crossover Time		t <sub>c</sub>	–	0.29	0.75	μs
Fall Time		t <sub>fi</sub>	–	0.15	–	μs

2. Pulse Test: PW = 300 μs, Duty Cycle ≤ 2%.

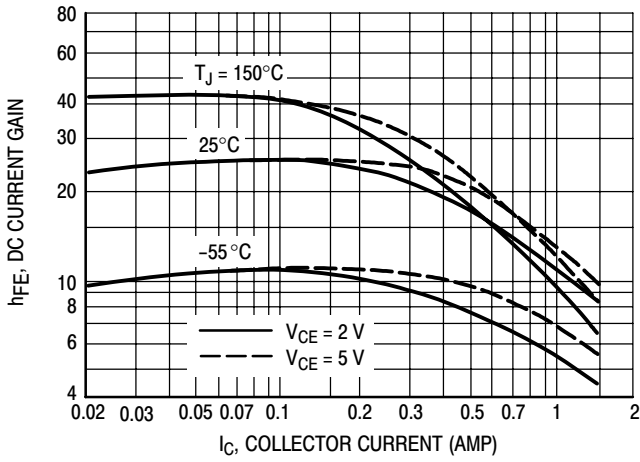


Figure 1. DC Current Gain

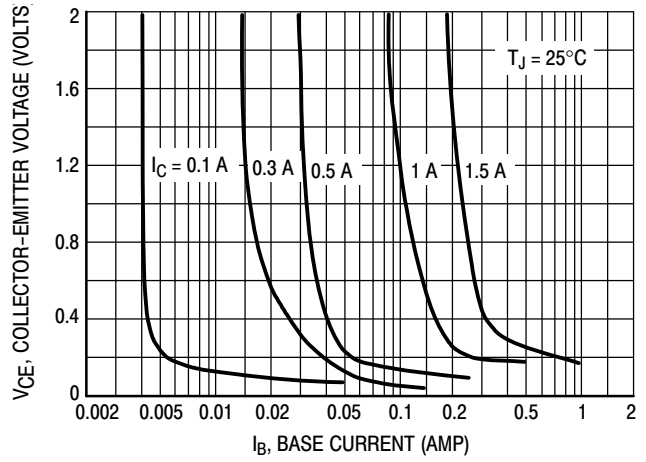


Figure 2. Collector Saturation Region

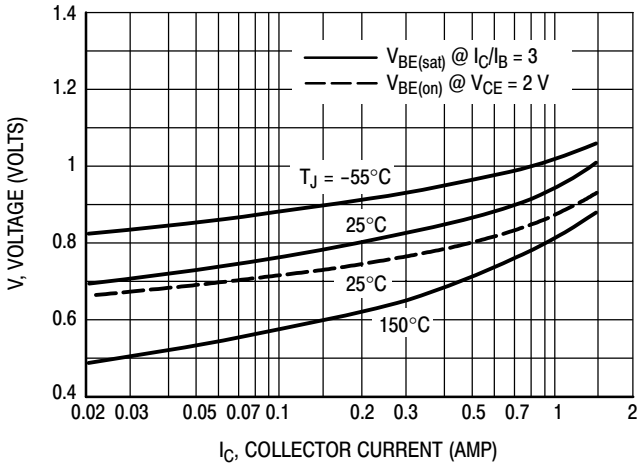


Figure 3. Base-Emitter Voltage

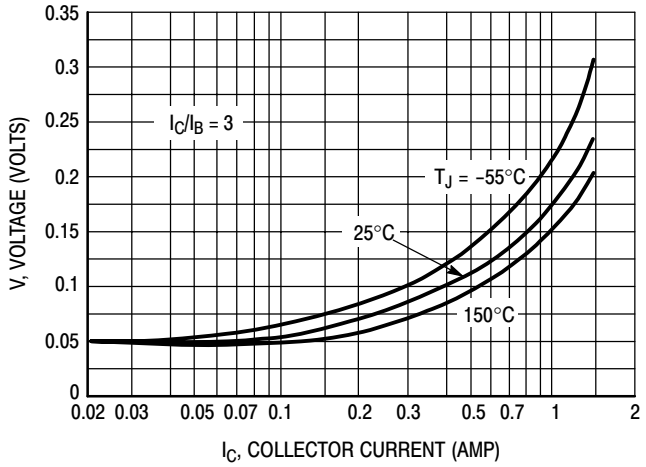


Figure 4. Collector-Emitter Saturation Region

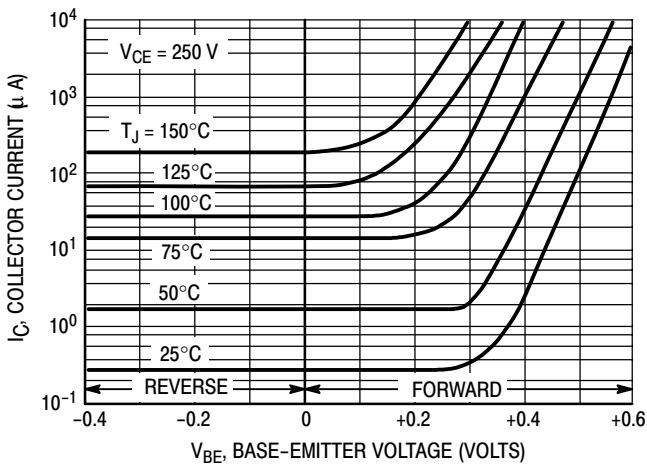


Figure 5. Collector Cutoff Region

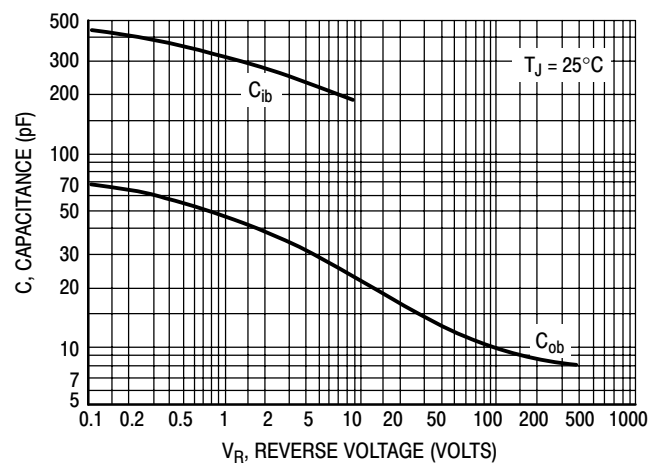


Figure 6. Capacitance

# MJE13003

Table 1. Test Conditions for Dynamic Performance

REVERSE BIAS SAFE OPERATING AREA AND INDUCTIVE SWITCHING		RESISTIVE SWITCHING
TEST CIRCUITS	<p>DUTY CYCLE <math>\leq 10\%</math>  <math>t_r, t_f \leq 10 \text{ ns}</math></p> <p>NOTE          PW and <math>V_{CC}</math> Adjusted for Desired <math>I_C</math>  <math>R_B</math> Adjusted for Desired <math>I_{B1}</math></p>	
CIRCUIT VALUES	<p>Coil Data:          Ferroxcube Core #6656          Full Bobbin (~200 Turns) #20</p> <p>GAP for 30 mH/2 A  <math>L_{\text{coil}} = 50 \text{ mH}</math></p> <p><math>V_{CC} = 20 \text{ V}</math>  <math>V_{\text{clamp}} = 300 \text{ Vdc}</math></p>	<p><math>V_{CC} = 125 \text{ V}</math>  <math>R_C = 125 \Omega</math>  <math>D1 = 1N5820 \text{ or Equiv.}</math>  <math>R_B = 47 \Omega</math></p>
TEST WAVEFORMS	<p>OUTPUT WAVEFORMS</p> <p><math>t_1</math> Adjusted to Obtain <math>I_C</math></p> $t_1 \approx \frac{L_{\text{coil}} (I_{Cpk})}{V_{CC}}$ <p>Test Equipment          Scope—Tektronics          475 or Equivalent</p> $t_2 \approx \frac{L_{\text{coil}} (I_{Cpk})}{V_{\text{clamp}}}$	<p><math>t_r, t_f &lt; 10 \text{ ns}</math>          Duty Cycle = 1.0%  <math>R_B</math> and <math>R_C</math> adjusted for desired <math>I_B</math> and <math>I_C</math></p>

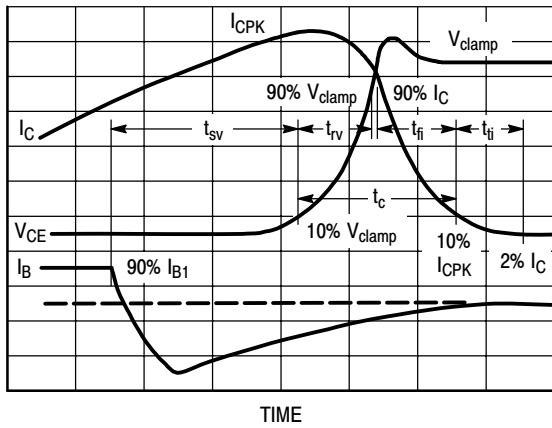


Figure 7. Inductive Switching Measurements

NOTE: All Data Recorded in the Inductive Switching Circuit in Table 1

Table 2. Typical Inductive Switching Performance

$I_C$ AMP	$T_C$ °C	$t_{sv}$ μS	$t_{rv}$ μS	$t_{fi}$ μS	$t_{ti}$ μS	$t_c$ μS
0.5	25	1.3	0.23	0.30	0.35	0.30
	100	1.6	0.26	0.30	0.40	0.36
1	25	1.5	0.10	0.14	0.05	0.16
	100	1.7	0.13	0.26	0.06	0.29
1.5	25	1.8	0.07	0.10	0.05	0.16
	100	3	0.08	0.22	0.08	0.28

SWITCHING TIMES NOTE

In resistive switching circuits, rise, fall, and storage times have been defined and apply to both current and voltage waveforms since they are in phase. However, for inductive loads which are common to SWITCHMODE power supplies and hammer drivers, current and voltage waveforms are not in phase. Therefore, separate measurements must be made on each waveform to determine the total switching time. For this reason, the following new terms have been defined.

- $t_{sv}$  = Voltage Storage Time,  $90\% I_{B1}$  to  $10\% V_{clamp}$
- $t_{rv}$  = Voltage Rise Time,  $10-90\% V_{clamp}$
- $t_{fi}$  = Current Fall Time,  $90-10\% I_C$
- $t_{ti}$  = Current Tail,  $10-2\% I_C$
- $t_c$  = Crossover Time,  $10\% V_{clamp}$  to  $10\% I_C$

An enlarged portion of the inductive switching waveforms is shown in Figure 7 to aid in the visual identity of these terms.

For the designer, there is minimal switching loss during storage time and the predominant switching power losses occur during the crossover interval and can be obtained using the standard equation from AN-222:

$$P_{SWT} = 1/2 V_{CC} I_C (t_c) f$$

In general,  $t_{rv} + t_{fi} \approx t_c$ . However, at lower test currents this relationship may not be valid.

As is common with most switching transistors, resistive switching is specified at  $25^\circ C$  and has become a benchmark for designers. However, for designers of high frequency converter circuits, the user oriented specifications which make this a "SWITCHMODE" transistor are the inductive switching speeds ( $t_c$  and  $t_{sv}$ ) which are guaranteed at  $100^\circ C$ .

RESISTIVE SWITCHING PERFORMANCE

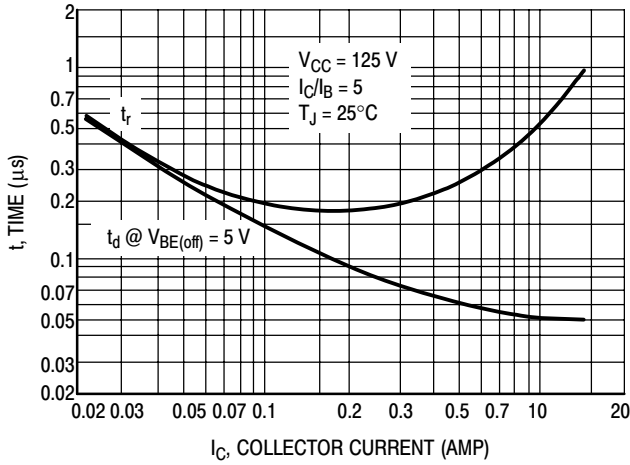


Figure 8. Turn-On Time

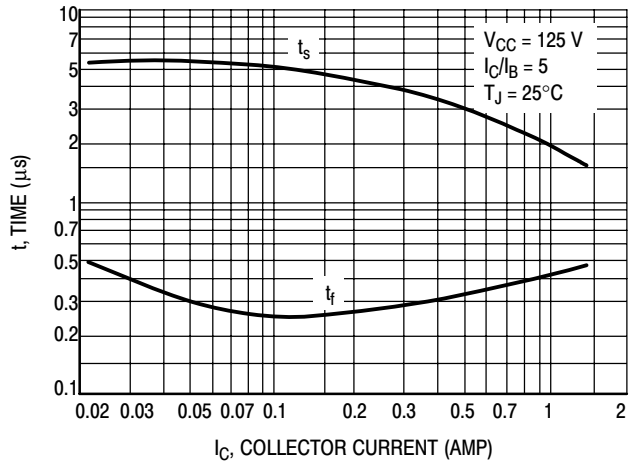


Figure 9. Turn-Off Time

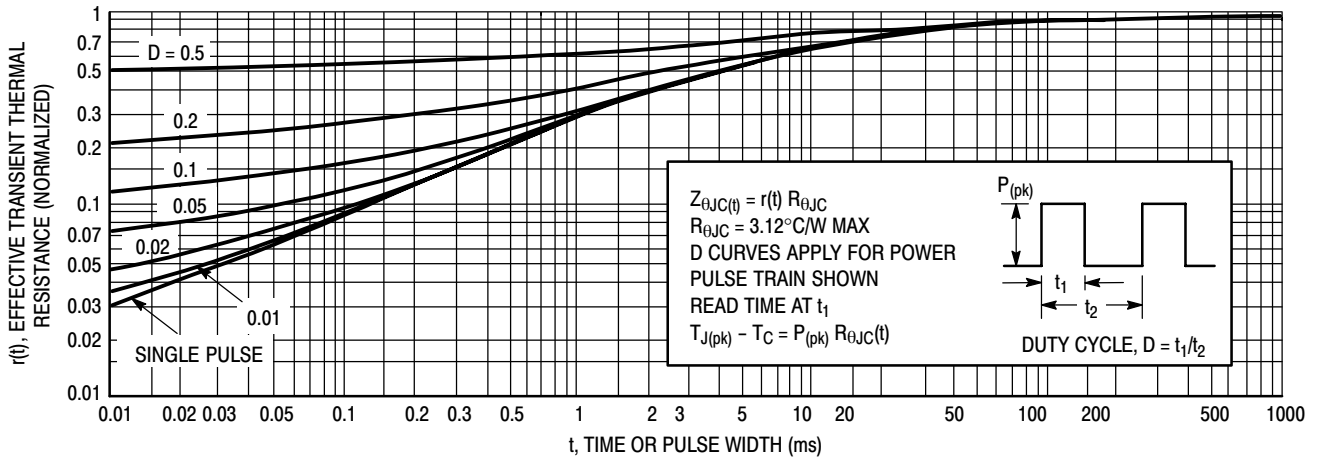


Figure 10. Thermal Response

The Safe Operating Area figures shown in Figures 11 and 12 are specified ratings for these devices under the test conditions shown.

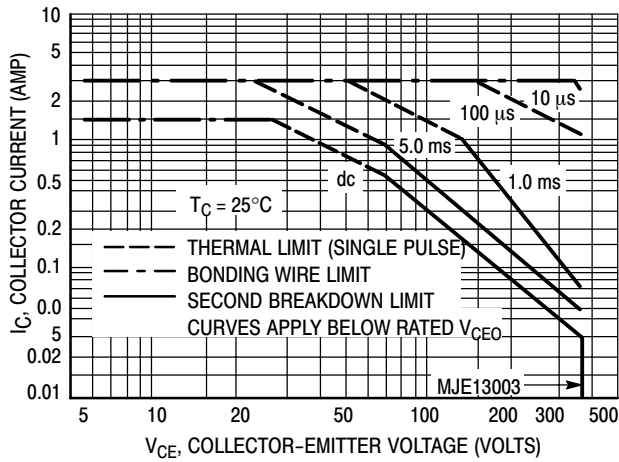


Figure 11. Active Region Safe Operating Area

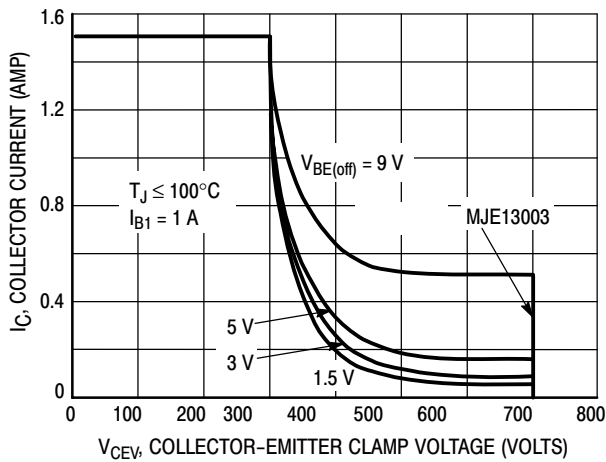


Figure 12. Reverse Bias Safe Operating Area

SAFE OPERATING AREA INFORMATION

FORWARD BIAS

There are two limitations on the power handling ability of a transistor: average junction temperature and second breakdown. Safe operating area curves indicate  $I_C - V_{CE}$  limits of the transistor that must be observed for reliable operation; i.e., the transistor must not be subjected to greater dissipation than the curves indicate.

The data of Figure 11 is based on  $T_C = 25^\circ\text{C}$ ;  $T_{J(pk)}$  is variable depending on power level. Second breakdown pulse limits are valid for duty cycles to 10% but must be derated when  $T_C \geq 25^\circ\text{C}$ . Second breakdown limitations do not derate the same as thermal limitations. Allowable current at the voltages shown on Figure 11 may be found at any case temperature by using the appropriate curve on Figure 13.

$T_{J(pk)}$  may be calculated from the data in Figure 10. At high case temperatures, thermal limitations will reduce the power that can be handled to values less than the limitations imposed by second breakdown.

REVERSE BIAS

For inductive loads, high voltage and high current must be sustained simultaneously during turn-off, in most cases, with the base to emitter junction reverse biased. Under these conditions the collector voltage must be held to a safe level at or below a specific value of collector current. This can be accomplished by several means such as active clamping, RC snubbing, load line shaping, etc. The safe level for these devices is specified as Reverse Bias Safe Operating Area and represents the voltage-current conditions during reverse biased turn-off. This rating is verified under clamped conditions so that the device is never subjected to an avalanche mode. Figure 12 gives RBSOA characteristics.

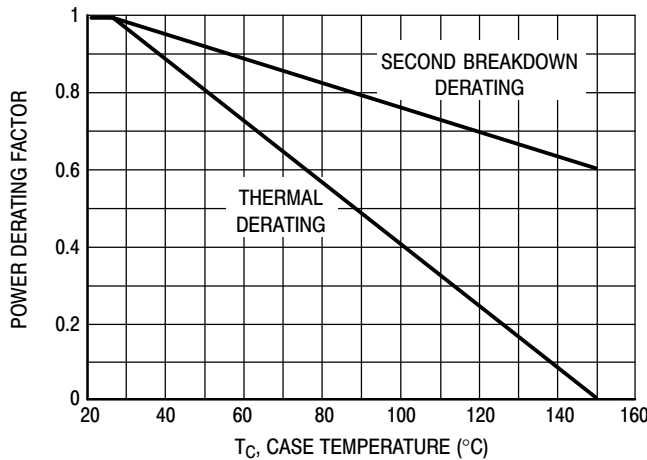
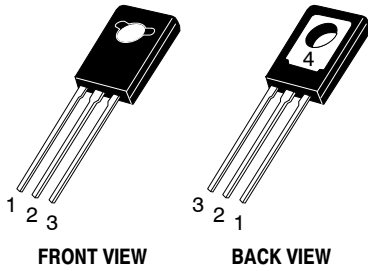


Figure 13. Forward Bias Power Derating

# MECHANICAL CASE OUTLINE

## PACKAGE DIMENSIONS

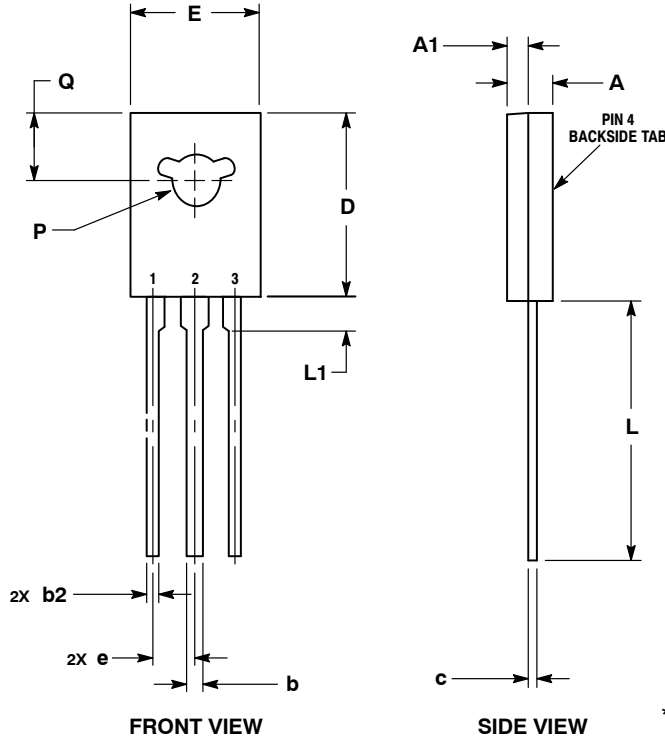
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**TO-225**  
CASE 77-09  
ISSUE AD

DATE 25 MAR 2015

SCALE 1:1

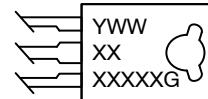


**NOTES:**

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. NUMBER AND SHAPE OF LUGS OPTIONAL.

DIM	MILLIMETERS	
	MIN	MAX
A	2.40	3.00
A1	1.00	1.50
b	0.60	0.90
b2	0.51	0.88
c	0.39	0.63
D	10.60	11.10
E	7.40	7.80
e	2.04	2.54
L	14.50	16.63
L1	1.27	2.54
P	2.90	3.30
Q	3.80	4.20

**GENERIC MARKING DIAGRAM\***



- Y = Year
- WW = Work Week
- XXXXX = Device Code
- G = Pb-Free Package

\*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot "•", may or may not be present.

- |   |   |   |   |   |
|---|---|---|---|---|
| <p>STYLE 1:<br/>PIN 1. EMITTER<br/>2., 4. COLLECTOR<br/>3. BASE</p> | <p>STYLE 2:<br/>PIN 1. CATHODE<br/>2., 4. ANODE<br/>3. GATE</p> | <p>STYLE 3:<br/>PIN 1. BASE<br/>2., 4. COLLECTOR<br/>3. EMITTER</p> | <p>STYLE 4:<br/>PIN 1. ANODE 1<br/>2., 4. ANODE 2<br/>3. GATE</p> | <p>STYLE 5:<br/>PIN 1. MT 1<br/>2., 4. MT 2<br/>3. GATE</p>     |
| <p>STYLE 6:<br/>PIN 1. CATHODE<br/>2., 4. GATE<br/>3. ANODE</p>     | <p>STYLE 7:<br/>PIN 1. MT 1<br/>2., 4. GATE<br/>3. MT 2</p>     | <p>STYLE 8:<br/>PIN 1. SOURCE<br/>2., 4. GATE<br/>3. DRAIN</p>      | <p>STYLE 9:<br/>PIN 1. GATE<br/>2., 4. DRAIN<br/>3. SOURCE</p>    | <p>STYLE 10:<br/>PIN 1. SOURCE<br/>2., 4. DRAIN<br/>3. GATE</p> |

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